

LF series remote IO

User manual

WUXI XINJE ELECTRIC CO., LTD.

Data No. : PR 02 20231208 1.0

Basic notes

- Thank you for purchasing the Xinje LF series remote IO and XF series expansion modules.
- This manual mainly introduces the hardware characteristics of LF series couplers and XF series expansion modules.
- Before using the product, please read this manual carefully and operate on the premise of fully understanding the contents of the manual.
- For the introduction of software and programming, please refer to the relevant manzuals.
- Please deliver this manual to the end user.

User instructions

- Only operators with certain electrical knowledge can carry out wiring and other operations on the product. If there are any unknown cases, please consult our technicians.
- The examples listed in the manual and other technical materials are only for users' understanding and reference, and don't guarantee certain actions.
- When using this product in combination with other products, please confirm whether it complies with relevant specifications and principles.
- When using this product, please confirm whether it meets the requirements and is safe.
- Please set up backup and safety functions by yourself to avoid possible machine failure or loss caused by the failure of this product.

Statement of responsibility

- Although the contents of the manual have been carefully checked, errors are inevitable, and we can't guarantee complete consistency.
- We will often check the contents of the manual and correct them in subsequent versions. We welcome your valuable comments.
- Please understand that the contents described in the manual are subject to change without notice.

Contact method

If you have any questions about the use of this product, please contact the agent and office who purchased the product, or directly contact Xinje company.

• Telephone: 400-885-0136

• Fax: 0510-85111290

Address: 4th floor, building 7, creative industry park, No. 100, Dicui Road, Wuxi, China

• Post code: 214072

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November, 2023

Safety precautions

(Please make sure to read before use)

The potential problems that may arise during the use of the product are basically listed in safety precautions, and are all indicated in two levels: attention and danger. For other unfinished matters, please follow the basic electrical operating procedures.



Note

When used incorrectly, it may pose a danger and may result in moderate or minor injuries, as well as potential property damage.



Danger

When used incorrectly, it may pose a danger, causing personal injury or serious injury, as well as potentially causing serious property damage.

• Confirmation upon receiving the product



Note

1. Damaged controllers, controllers with missing components, or controllers with models that don't meet the requirements, please don't install them.

There is a risk of injury.

System design of the product



Danger

1. Please design a safety circuit outside the controller to ensure that the entire system can operate safely in case of abnormal controller operation.

There is a risk of causing misoperation and malfunction.



Note

 Please don't tie the control wiring and power wiring together. In principle, they should be separated by 10cm.

May cause misoperation and product damage.

Product installation



Danger

1. Before installing the controller, be sure to disconnect all external power sources.

There is a risk of electric shock.



Note

1. Please install and use this product under the environmental conditions specified in the general specifications of the manual.

Don't use in damp, high temperature, dusty, smoke, conductive dust, corrosive gases, flammable gases, as well as places with vibration and impact.

It may cause electric shock, fire, misoperation, product damage, etc.

2. Don't directly touch the conductive parts of the product.

May cause misoperation or malfunction.

3. Please use DIN46277 guide rail to fix this product and install it on a flat surface.

Incorrect installation may cause misoperation and product damage.

4. When processing screw holes, please don't allow cutting powder or wire debris to fall into the product casing.

May cause misoperation or malfunction.

5. When connecting the expansion module with an expansion cable, please confirm that the connection is tight and the contact is good.

May lead to poor communication and misoperation.

6. When connecting peripheral devices, expansion devices, batteries, etc., please make sure to power off the operation.

May cause misoperation or malfunction.

Product wiring



Danger

1. Before wiring the controller, be sure to disconnect all external power sources.

There is a risk of electric shock.

- 2. Please correctly connect the AC or DC power supply to the dedicated power terminal of the controller. Connecting the wrong power supply may burn out the controller.
- 3. Before powering on and running the controller, please cover the cover plate on the terminal block. There is a risk of electric shock.



Note

- 1. Please use a power supply within the voltage range to power the coupler or module, otherwise it may cause damage to the product.
- 2. Please use a 2mm² wire to perform the third type of grounding on the grounding terminals of the controller and expansion equipment, and don't connect them to the common grounding of the strong current system. May cause malfunctions, product damage, etc.
- 3. Don't perform external wiring on empty terminals.

May cause misoperation and product damage.

- 4. When processing screw holes, please don't allow cutting powder or wire debris to fall into the product casing. May cause misoperation, malfunction, etc.
- 5. When using wires to connect terminals, please be sure to tighten them tightly and don't let the conductive parts come into contact with other wires or terminals.

May cause misoperation and product damage.

Operation and maintenance of products



Danger

1. After powering on the controller, don't touch the terminals.

There is a risk of electric shock.

2. Don't wire or disassemble terminals with electricity.

There is a risk of electric shock.

3. Before making changes to the program in the controller, please make sure to stop it first.

May cause misoperation.



Note

1. Don't disassemble or assemble this product without authorization.

May cause damage to the product.

2. Please plug and unplug the connecting cable in case of power outage.

May cause damage to cables and cause misoperation.

3. Don't perform external wiring on empty terminals.

May cause misoperation and product damage.

4. When disassembling expansion devices, peripheral devices, and batteries, please power off first.

May cause misoperation, malfunction, etc.

- 5. When the product is discarded, please dispose of it as industrial waste.
- 6. Before installing the device, please make sure to turn off the power. If the power is not turned off, the device may malfunction or be damaged. When disassembling the XF-I/O unit, be sure to turn off the CPU unit or intermediate power supply.

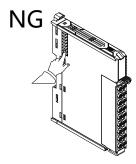
May cause malfunctions, product damage, etc.

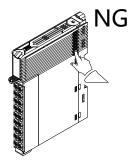
7. Don't stick adhesive tape or labels on both sides of the device or at the golden finger. Adhesive tape or labels may affect the normal vertical sliding installation of the module unit. The residue of the adhesive tape or debris may adhere to the pins of the XF- I/O bus connector.

May cause misoperation, malfunction, etc.

8. Don't touch the XF- I/O bus connector on the device as sweat and dust may adhere to the connector or golden fingers.

This may cause malfunctions.





9. Don't use ink to write on the device in the area shown in the picture.

This may cause malfunctions.

Preface

Sincerely thank you for purchasing the XF-IO series of Xinje programmable controllers.

This manual is convenient for users to understand and use the necessary precautions, specifications, functions, and other content when using XF-IO units.

Before use, it is important to thoroughly read this manual and related manuals, and correctly use this product based on a thorough understanding of the functionality/performance of the XF-IO series expansion modules.

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1. Document Guide

1.1 Related manual

1) CPU unit

Manual name	Main content	
User Manual for XSF Series Programmable Controllers	Mainly records the hardware specifications and	
[Hardware section]	maintenance information of XSF series CPU units	
XS series PLCopen standard controller user manual	Mainly accorded in the VS social instruction section	
[Instruction section] (XS studio)	Mainly recorded in the XS series instruction section	
XS series PLCopen standard controller user manual	Mainly records the operation and corresponding	
[Software section] (XS studio)	functions of XS Studio programming software	

2) I/O unit

Manual name	Main content	
XF Series Expansion Module User Manual	Mainly records the product specifications and	
AF Series Expansion Module Oser Manual	maintenance information of the XF series IO unit	

2. Terminology

In this manual, unless otherwise specified, the following terms will be used for explanation.

Terminology	Explanation		
Coupler	XF series expansion module adapter, supporting EtherCAT and PROFINET bus protocols.		
Power module unit	General term for XF series power modules.		
IP20	Protection level according to DIN 40050: protection against finger contact and intrusion of particles with a diameter greater than 12mm.		
Backplane bus	The backplane bus is a serial data bus used by various modules to communicate with each other. The backplane bus is also used to provide some necessary power for each module. Each module is connected through a bus connector.		

3. Coupler unit

In this chapter, the specifications, appearance dimensions, and usage methods of each bus coupler unit are introduced.

3.1 Naming rules

$$\underline{L}_{1} \underline{F}_{2} \underline{C}_{3} \underline{A} - \underline{AP}_{5}$$

1	Series name	L:	Remote I/O series
2	Refers to the extension module	F:	Indicating compatibility with XF series right
			expansion module
3	Bus type	C:	EtherCAT bus
		P:	Profinet bus
		E:	EtherNet/IP bus (In development, please stay tuned)
4	Ethernet bandwidth	3:	100M
5	Unit type	AP:	Coupler unit

3.2 EtherCAT coupler LFC3-AP

3.2.1 Overview

LFC3-AP coupler unit supports EtherCAT bus communication protocol, a single adapter module can connect up to 32 XF series I/O modules, it can achieve seamless connection with mainstream PLCs such as XINJE, Beckhoff, Omron, and Keyence.

- Compact structure, saving installation space.
- Minimum support for 250us DC synchronization.
- Support firmware upgrade for network ports.
- Support hardware static station number setting.
- High speed bus microsecond response.
- Maximum support for 32 expansion modules.

■ Module version

Hardware version	Firmware version	Function
H2.0.0	V2.0.0	Basic functions for the first official production

3.2.2 Module view

1) Description of each section



No.	Name	No.	Name
1	DC24V power supply terminal	2	Status indicator
3	EtherCAT IN port	4	EtherCAT OUT port
(5)	Guide rail buckle	6	Used to set ECAT static station numbers, ranging from 1 to 255. When the station number is 0, the main station automatically assigns a station number

2) System indicator

Abbreviation	Explanation	
PWR	Power indicator light, lit when the power system is normal	
RUN	Running indicator light, lit up when the system is running normally	
ERR	System malfunction indicator light, lit up when system malfunction occurs	
SF	Module error indicator light	

• RUN indicator

RUN indicator	State	Explanation
Extinguish	INT	Initialize
Flash (2Hz)*2	PRE-OP	Trial running
Flash (1Hz)*1	SAFE-OP	Safe run
Light	OP	Running state
Flash (10Hz)*3	BOOTSTRAP or loading the EEPROM	Download EEPROM

• ERR indicator

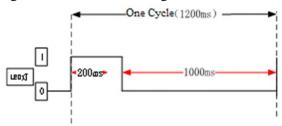
ERR indicator	Explanation	Processing method		
Extinguish	No Error			
Flash (10Hz)*1	EEPROM load error	1. Power on again.		
riasii (IUHZ)	EEFROW load effor	2. Reflash EEPROM.		
		1. Check the configuration of the		
Single flash*4	AL status register error	main station and upper computer.		
		2. Reactivate configuration.		
		1. Check if the connection between		
	Process data watchdog timeout	the slave station and the master		
Double flashing*5		station is intact.		
		2. Check if the main station reports		
		any errors.		
		1. Check if the connection between		
		the slave station and the master		
		station is intact.		
Light	DDI weetah da a tima asut	2. Check if the main station reports		
	PDI watchdog timeout	any errors.		
		3. Check if there is excessive		
	interference on site.			
		4. Power on again.		

SF indicator

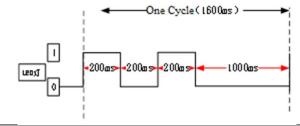
SF indicator	Explanation	Processing method
Extinguish	Expansion module is normal	
		1. Check the module power supply.
Single flash*4		2. Check if the module is faulty.
	Expansion module failure	Replace the module.
		3. Check the external channel wiring
		status.

SF indicator	Explanation	Processing method
Light	Detect configuration topology mismatch with reality	 Check the communication interface contact of the expansion module or restart the entire system. Check if the module in the corresponding slot is powered off or unplugged. Check the communication interface contact of the expansion module or restart the entire system.

- *1: A square wave with a duty cycle of 50% and a frequency of 1Hz.
- *2: A square wave with a duty cycle of 50% and a frequency of 2Hz.
- *3: A square wave with a duty cycle of 50% and a frequency of 10Hz.
- *4: Single flash as shown in the figure below:



• *5: Double flashing as shown in the figure below:



3.2.3 General specification

General specification		
Project		Specifications
	Maximum	55°C
On anoting town another	temperature	33 €
Operating temperature	Minimum	-20°C
	temperature	-20 C
	Maximum	70°C
Transportation/Storage	temperature	70 C
temperature	Minimum	-40°C
	temperature	-
Environmental humidity	Upper limit	95%
(including operation/storage)	Lower limit	10%

General specification		
Project	Specifications	
IP code	IP20	
	Compliant with IEC61131-2	
	Under intermittent vibration (frequency 5-9Hz, constant	
	amplitude 3.5mm peak displacement) and (frequency	
	9-150Hz, constant acceleration 1.0g peak acceleration)	
Anti vibration	Under continuous intermittent vibration (frequency 5-9Hz	
	half amplitude 1.75mm displacement) and (frequency	
	9-150Hz constant acceleration 0.5g constant frame	
	amplitude)	
	Scan 10 times in X, Y, and Z directions	
	Complies with IEC61131-2 standard	
Impact resistance	The impact strength is 15G (peak) and the duration is 11ms.	
impact resistance	It is applied to three mutually perpendicular axes, and each	
	axis is impacted 3 times (a total of 18 impacts)	
Using environment	Non corrosive gas	
Using altitude	0-2000 m	
Overvoltage level	II: Complies with IEC61131-2	
Pollution level	2: Complies with IEC61131-2	
Anti interference EMC	Complies with IEC 61131-2 IEC61000-6-4 Type B	
Related certifications	CE	

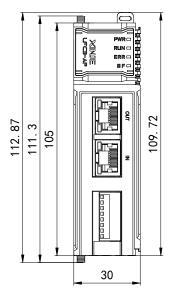
3.2.4 Technical specifications

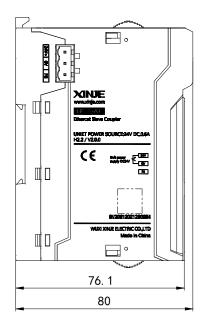
Project	Specifications
Bus type	EtherCAT
Rated input voltage	DC24V
Voltage allowable range	DC21.6-26.4V
Input current	120mA DC2V
Allow instant power outage time	10ms DC24V
Impulse current	10A DC26.4V
Down protection	Anti reverse connection protection, overcurrent protection, surge
Power protection	absorption
Single AP process data	Input maximum 1024 bytes, output maximum 1024 bytes
Network interface	2 RJ45 ports
Physical layer	100BASE-TX
Synchronization cycle	Support 250us, 500us, 1000us, 2000us, 4000us
Transmission distance	Less than or equal to 100m between two nodes
Transmission medium	Over five categories and above
Topological structure	Linear or star shaped (external branching device)
Number of expansion modules	Supports 32 modules
Firmware upgrade	Support
Station number setting	Configuration by dial switch (1-255) or allocation by main station

3.2.5 Installation&Wiring

3.2.5.1 Appearance dimension diagram

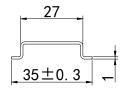
(Unit: mm)





3.1.5.2 Installation method

The module is installed using DIN rails, which must comply with the IEC 60715 standard (35mm wide, 1mm thick). The dimension information is shown in the following figure, and the unit is (mm).



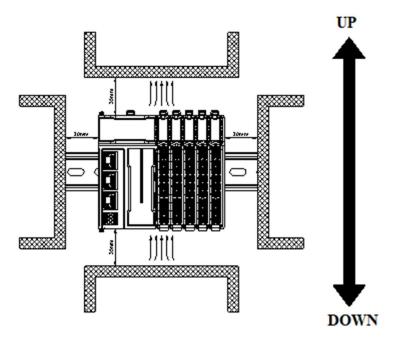


Note

When the module is installed on a non recommended DIN rail, the DIN rail latch may not lock properly.

3.1.5.3 Installation environment

This product can be installed in four positions (i.e. installation direction): horizontal, vertical, top of cabinet, and bottom of cabinet, it is recommended to install in a horizontal direction, and the heat dissipation design should be through natural convection, to ensure normal ventilation and heat dissipation, and to reserve sufficient wiring space, the minimum gap must be left around this product, as shown in the following figure:

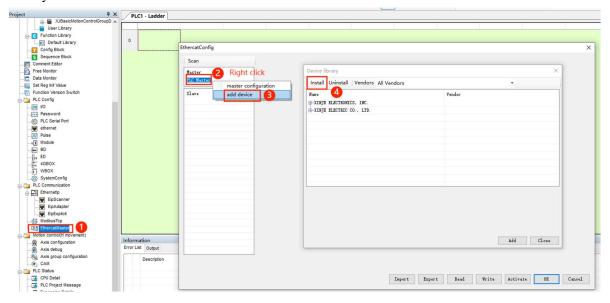


If there is a high-temperature heat source equipment (heater, transformer, high resistance, etc.) around this product, at least 100mm gap should be left between it and the high-temperature heat source equipment.

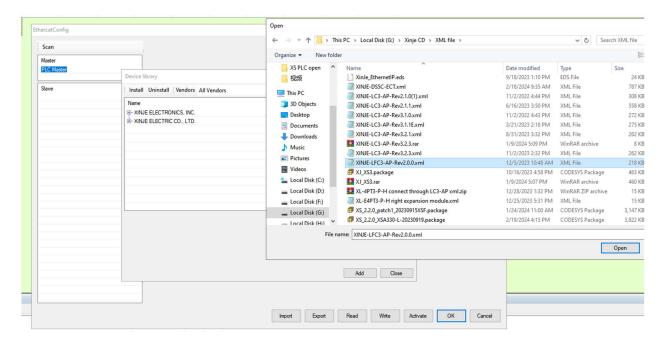
3.2.6 Use cases

3.2.6.1 LFC3-AP connected to XINJE XDH/XLH/XG2

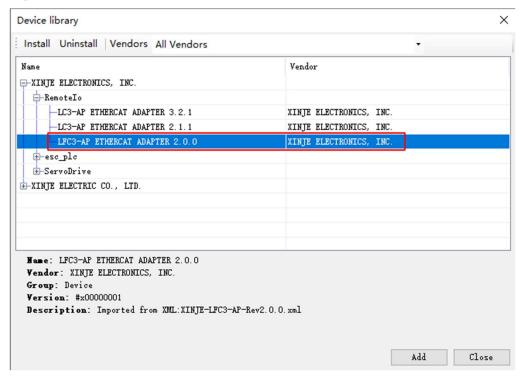
1. Add the ".xml" file corresponding to LFC3-AP. Open the XINJE XDPPro programming software and right-click on "PLC Master" in EthercatMaster, click "Add Device" and click "Import Device" in the device library.



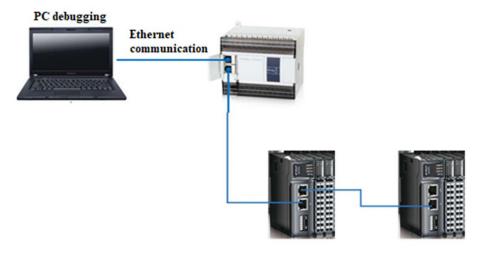
2. Find the directory where the LFC3-AP xml file is located, select it, and click "Open" to complete the addition.



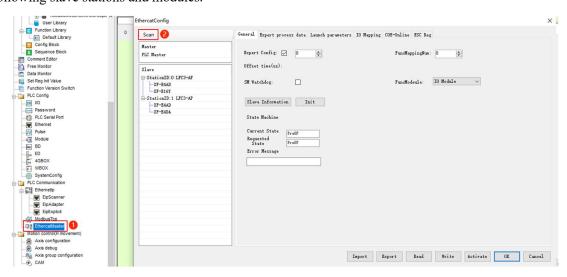
3. You can query the added xml files in the device library.



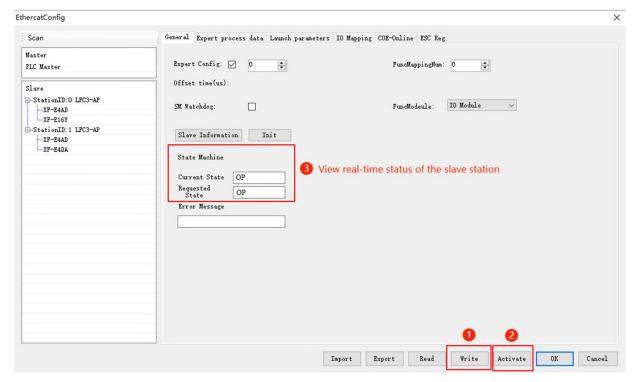
4. Check the connection between PLC and LFC3-AP, which follows the principle of "bottom in and top out".



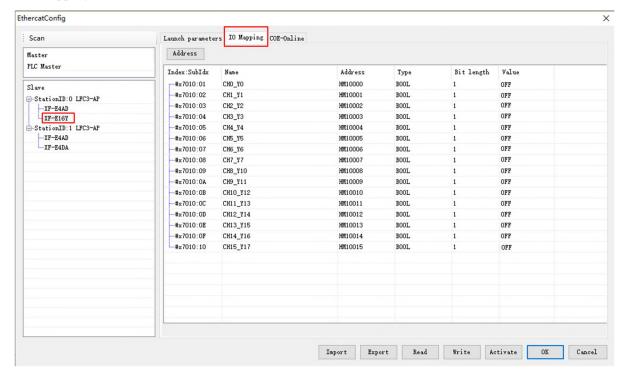
5. Connect the PLC using XDPPro, click "Scan" in "EthercatMaster", and the PLC will automatically add the following slave stations and modules.



6. Click "Configuration Write", after successful writing, click "Activate" to activate the slave station. You can check whether the slave station is in "OP" status in the "Status Machine".

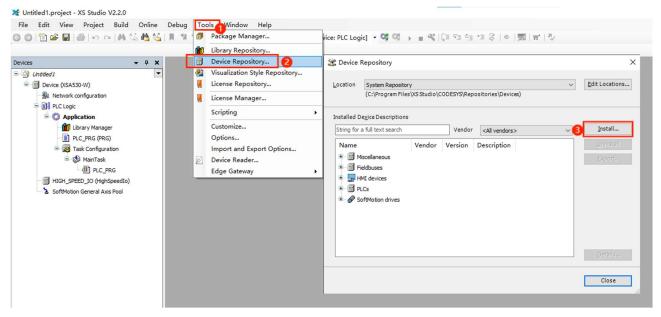


7. In the IO mapping of the module, the mapping address can be viewed, and the corresponding output points can be controlled in the IO mapping to check whether the actual output of the module is consistent with the IO mapping control.

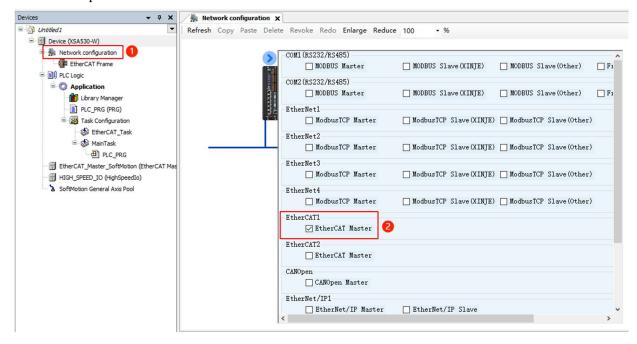


3.2.6.2 LFC3-AP and Codesys connection

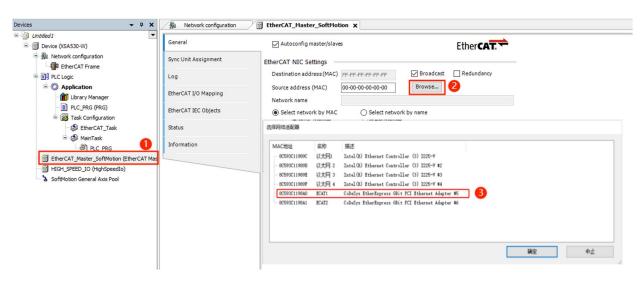
1. Add the ".xml" file corresponding to LFC3-AP. Open the XS Studio programming software, click on "Device repository..." in the "Tools" dropdown menu, and add the corresponding ". xml" file.



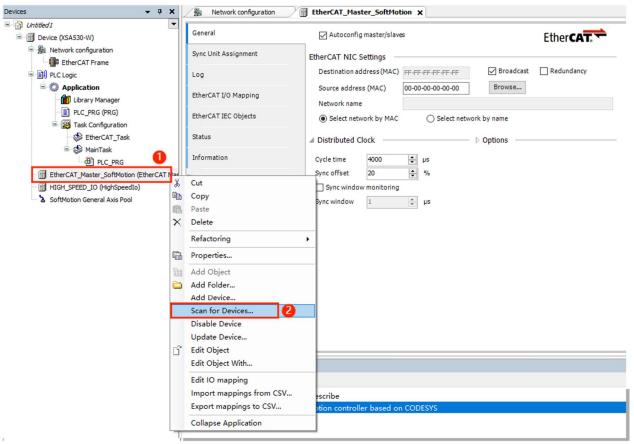
2. Click on "Network Configuration" to select "EtherCAT Master Station" and complete the configuration of the EtherCAT protocol.



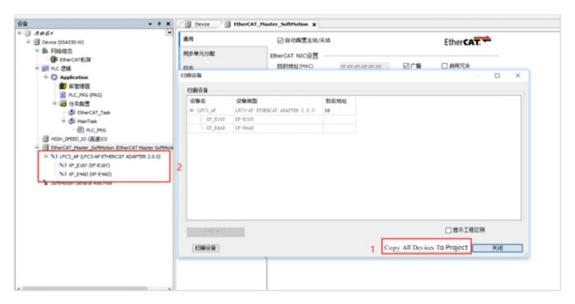
3. Double click on "EtherCAT Master SoftMotion" to select and configure the Ethercat source address (MAC).



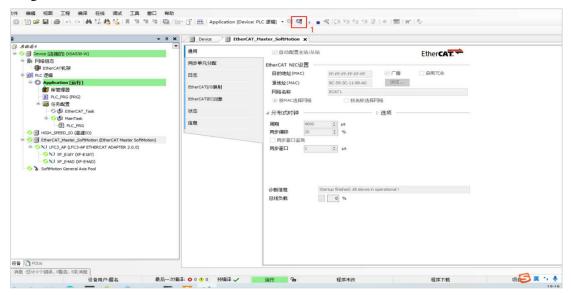
4. Right click on "EtherCAT_Master_SoftMotion" and click on the scanning device to scan and configure the information of the LFC3-AP+XF-E16YT+XF-E4AD module.



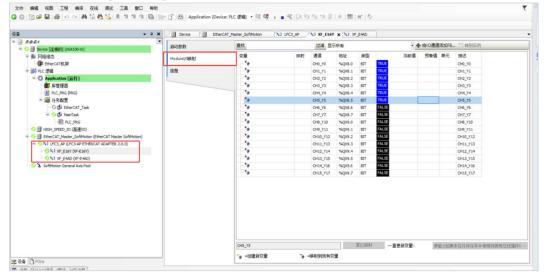
5. After completing the scan, click "Copy all devices to the project" and view the remote IO configuration status scanned under the left tree.



6. Click to log in and download the corresponding configuration information to the PLC, and view the current running results.

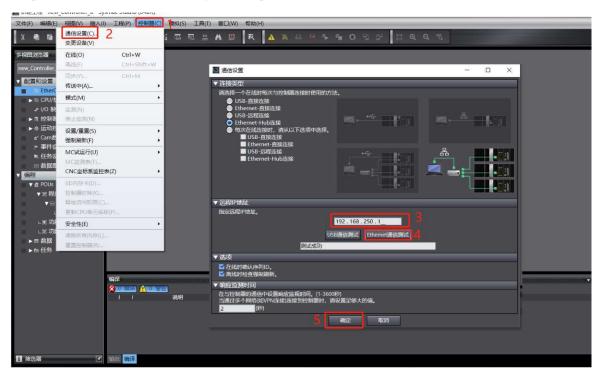


7. Click on the corresponding module in the left tree, and under the corresponding module, click on "Module I/O Mapping" to monitor or control the corresponding points, and check that the corresponding monitoring or control matches the required output.

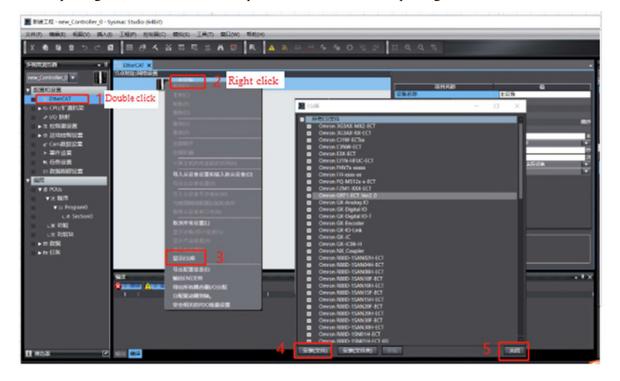


3.2.6.3 LFC3-AP connected to Omron

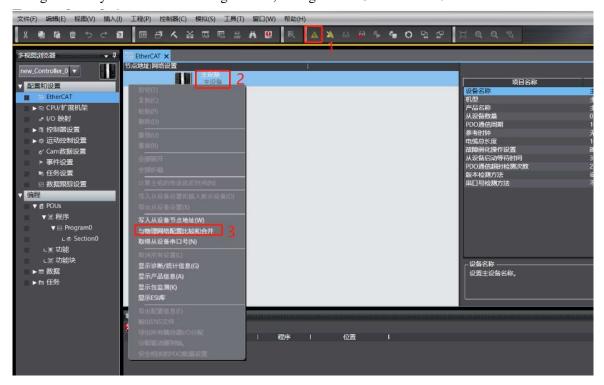
1. Click on "Controller", select "Communication Settings", and fill in the IP address of the PLC to be communicated in the specified remote IP address, click on "Ethernet Communication Test" and the display "Test Successful" indicates that the communication between the PC and PLC is successful, click "OK" to complete the communication configuration operation.



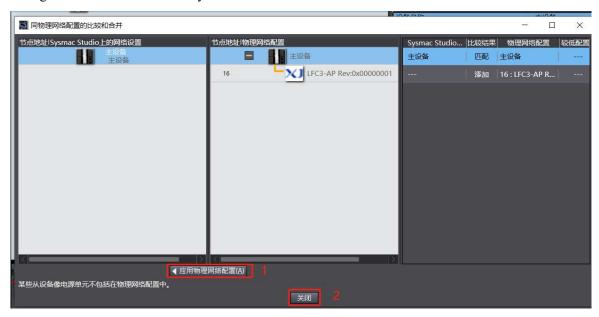
2. Add the ".xml" file corresponding to LFC3-AP. Open the Omron "Sysmac Studio" programming software, double-click "EtherCAT", right-click "Main Device", click "Display ESI Library" to install the corresponding ".xml" parsing file, click "Close" to complete the installation of the parsing file.



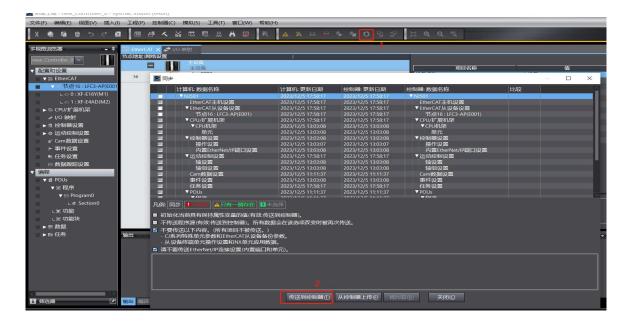
3. Click "Online" to put the PLC in an online state, right-click on "Main Device" and select "Compare and Merge with Physical Network Configuration", configure LFC3-AP+XF-E16YT+XF-E4AD.



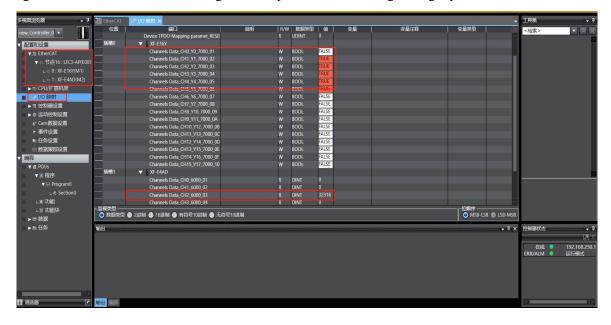
4. On the comparison and merging page of the same physical network configuration, click "Apply Physical Network Configuration (A)" to synchronize the scanned node information of LFC3-AP to "Network Configuration on Node Address Sysmac Studio".



5. Click "Sync" on the corresponding synchronization interface and click "Transfer to Controller".



6. View the corresponding node and module information under the left tree of Ethercat, and verify that the scanned module matches the actual configured module, click on "IO Mapping" to view or control the corresponding variables, the output viewing module corresponding to the setting has a corresponding output signal, and the external excitation signal corresponds to the viewing analog input value.



3.3 PROFINET coupler LFP3-AP

3.3.1 Overview

The LFP3-AP coupler unit supports the PROFINET bus communication protocol, and a single adapter module can connect up to 32 XF series I/O modules at most. Capable of connecting with Siemens 200smart, 1200, 1500 series PLCs, and seamlessly connecting with Botu software.

- Compact structure, saving installation space.
- Supports RT and IRT transmission modes.
- Support MRP and MRPD redundancy.
- Compatible with Siemens and TIA portal.
- Support firmware upgrade for network ports.
- Maximum support for 32 expansion modules.

■ Module version

Hardware version	Firmware version	Function
H2.0.0	V2.0.0	Basic functions for the first official production

3.3.2 Module view

1) Description of each section



No.	Name	No.	Name
1	DC24V power supply terminal	2	Status indicator
3	EtherNet	4	MAC address
(5)	Guide rail buckle		

2) System indicator

Abbreviation	Explanation
PWR	Power indicator light, lit when the power system is normal
RUN	Running indicator light, lit up when the system is running normally
ERR	System malfunction indicator light, lit up when system malfunction occurs
SF	Module error indicator light

RUN indicator

RUN indicator	State	Explanation
Light	Operating mode	Establish communication with the main station
Extinguish	Not running	Not connected
Single flicker*1	Find	TIA Portal clicks on the "flashing LED" function
Flash*2	Firmware update	Firmware update in progress
Light	Operating mode	Establish communication with the main station

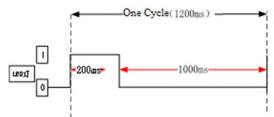
ERR indicator

ERR indicator	Explanation	Processing method
Extinguish	No Error	Normal operation
		Unplugged network cable
		2. Diagnostic message sent
		3. The number of configured modules is consistent with the
		number of physical connections, but the modules
Light	PDI watchdog timeout	physically connected to a certain slot are not consistent
		with the actual configuration (at this time, the SF light
		will also remain on)
		4. The number of configured modules exceeds the actual
		number of physical connections

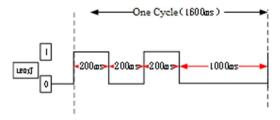
• SF indicator

SF indicator	Explanation	Processing method
Extinguish	Expansion module is	
Extiliguisii	normal	
	Expansion module failure	Check the module power supply.
Single flicker*4		2. Check if the module is faulty. Replace the module.
		3. Check the external channel wiring status.
		1. Check the communication interface contact of the
	Detect configuration topology mismatch with reality	expansion module or restart the entire system.
Light		2. Check if the module in the corresponding slot is powered
		off or unplugged.
		3. Check the communication interface contact of the
		expansion module or restart the entire system.

• *1: Single flash as shown in the figure below:



• *2: Double flashing as shown in the figure below:



3.3.3 General specification

	neral specification	
Project		Specifications
	Maximum temperature	55°C
Operating temperature	Minimum temperature	-20°C
Transportation/Storage	Maximum temperature	70°C
Temperature	Minimum temperature	-40°C
Environmental humidity	Upper limit	95%
(including operation/storage)	Lower limit	10%
IP code		IP20
Anti vibration		Compliant with IEC61131-2 Under intermittent vibration (frequency 5-9Hz, constant amplitude 3.5mm peak displacement) and (frequency 9-150Hz, constant acceleration 1.0g peak acceleration) Under continuous intermittent vibration (frequency 5-9Hz half amplitude 1.75mm displacement) and (frequency 9-150Hz constant acceleration 0.5g constant frame amplitude) Scan 10 times in X, Y, and Z directions
Impact resistance		Complies with IEC61131-2 standard The impact strength is 15G (peak) and the duration is 11ms. It is applied to three mutually perpendicular axes, and each axis is impacted 3 times (a total of 18 impacts)
Using environment		Non corrosive gas
Using altitude		0-2000 m
Overvoltage level		II: Compliant with IEC61131-2

General specification		
Project Specifications		
Pollution level	2: Compliant with IEC61131-2	
Anti interference EMC	Compliant with IEC 61131-2 IEC61000-6-4 Type B	
Related certifications	CE	

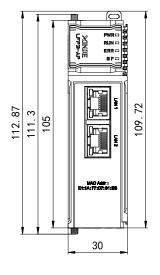
3.3.4 Technical specifications

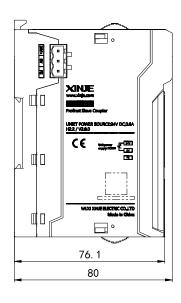
Project	Specifications
Bus type	PROFINET
Rated input voltage	DC24V
Voltage allowable range	DC21.6-26.4V
Input current	120mA DC2V
Allow instant power outage time	10ms DC24V
Impulse current	10A DC26.4V
Power protection	Anti reverse connection protection, overcurrent protection, surge
	absorption
Single AP process data	Input maximum 1440 bytes, output maximum 1440 bytes
Communication mode	RT mode, IRT mode
Media redundancy (MRP)	Support
Media Path Planning Redundancy	Support
(MRPD)	
Network interface	2 RJ45 ports
Connection rate	10/100Mbps adaptive, full duplex
Transmission distance	Less than or equal to 100m between two nodes
Transmission medium	Over five categories and above
Topological structure	Supports line type, star type, tree type, etc
Number of expansion modules	Supports 32 modules
Firmware upgrade	Support

3.3.5 Installation&Wiring

3.3.5.1 Appearance dimension diagram

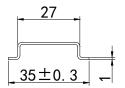
(Unit: mm)





3.3.5.2 Installation method

The module is installed using DIN rails, which must comply with the IEC 60715 standard (35mm wide, 1mm thick). The size information is shown in the following figure, in millimeters.



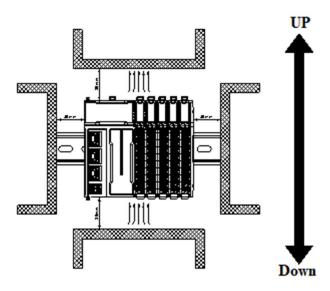


Note

When the module is installed on a non recommended DIN rail, the DIN rail latch may not lock properly.

3.3.5.3 Installation environment

This product can be installed in four positions (i.e. installation direction): horizontal, vertical, top of cabinet, and bottom of cabinet, it is recommended to install in a horizontal direction, and the heat dissipation design should be through natural convection, to ensure normal ventilation and heat dissipation, and to reserve sufficient wiring space, the minimum gap must be left around this product, as shown in the following figure:

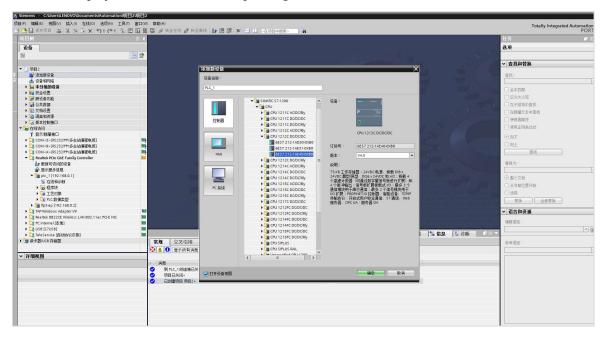


If there is a high-temperature heat source equipment (heater, transformer, high resistance, etc.) around this product, at least 100mm gap should be left between it and the high-temperature heat source equipment.

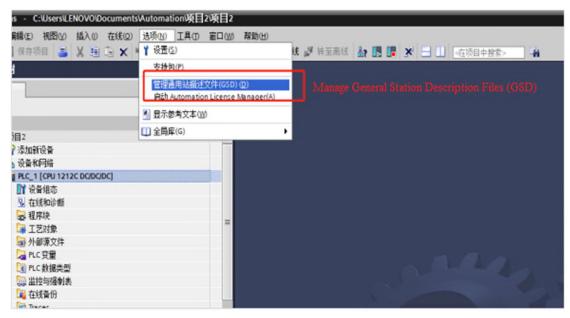
3.3.6 Use Cases

3.3.6.1 LFP3-AP connected to Siemens S7-1200/1500

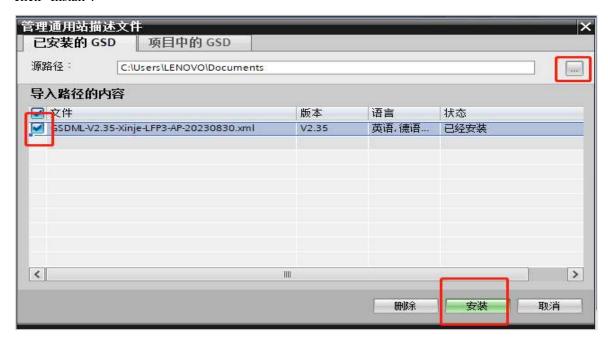
1. Create a new project and select the corresponding PLC hardware.



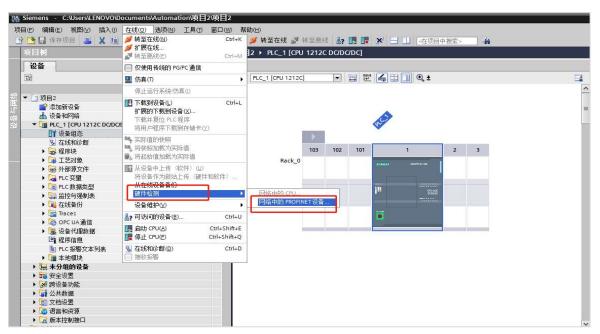
2. In the menu bar "Selection", click "Manage General Station Description Files (GSD)" to add the GSD file for LFP3-AP.



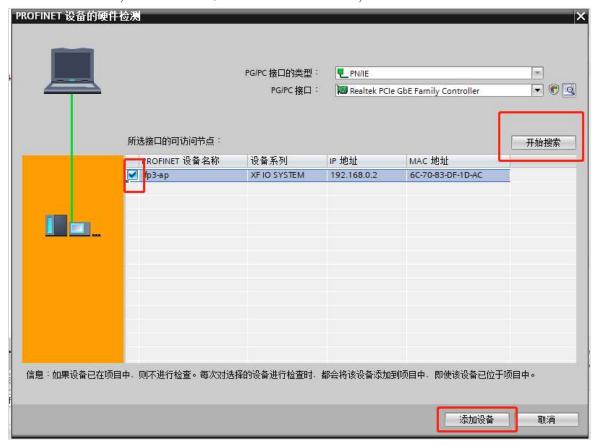
3. Select the folder where the GSD file is located in the source path, select the corresponding GSD file, and click "Install".



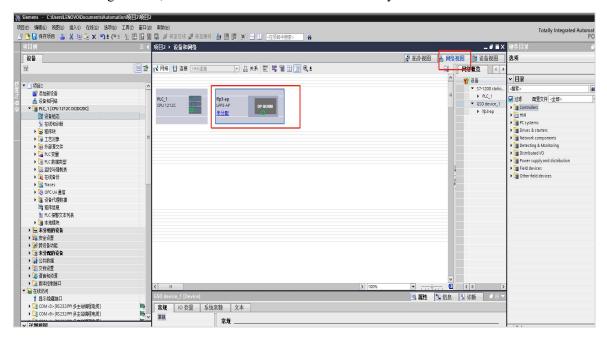
4. In the menu bar "Online", click "Hardware Detection" and then click "PROFINET Devices in the Network".



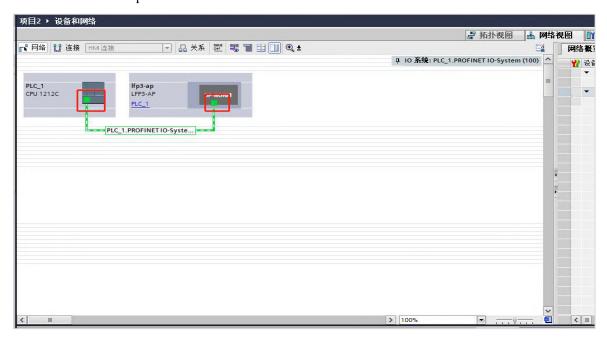
5. Click "Start Search", select the "LFP3-AP" found in the search, and click "Add Device".



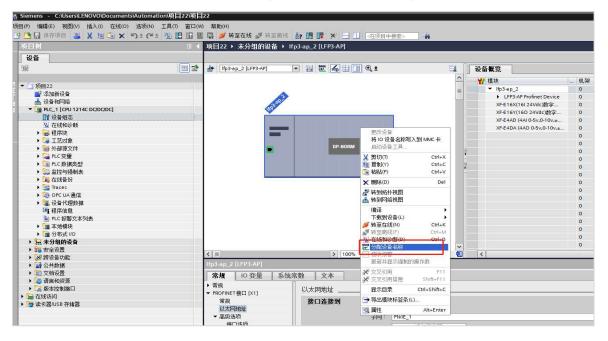
6. In "Device Configuration", click "Network View" to view the newly added slave devices.



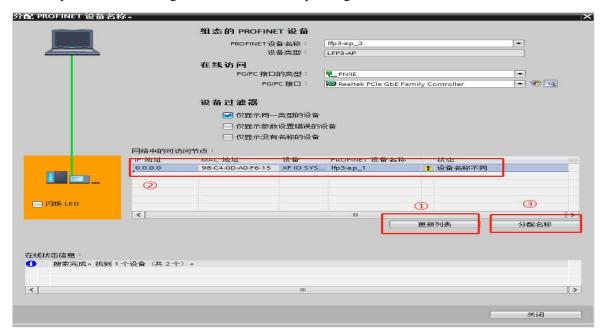
7. In the Network View, drag the mouse from the PLC network port to the LFP3-AP network port to establish a connection relationship.



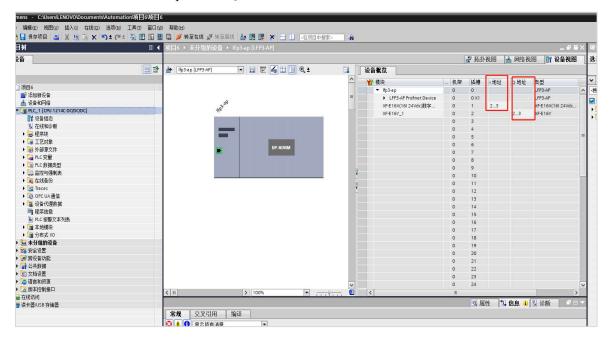
8. Click on LFP3-AP to enter the device view, right-click and select "Assign Device Name".



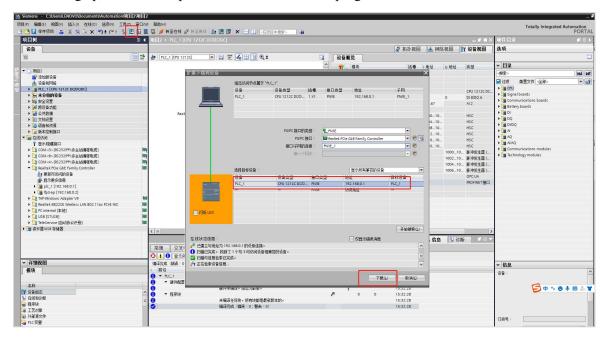
9. Click "Update List" to "Assign Names" to the corresponding slave stations.



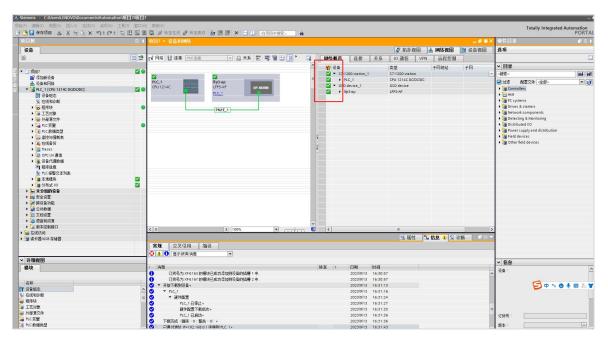
10. Click on LFP3-AP to enter the device view, where you can view the mapping addresses corresponding to the expansion module. For example, the input address of XF-E16X corresponds to I2.0-3.7, and the output address of XF-E16YT corresponds to Q2.0-3.7.



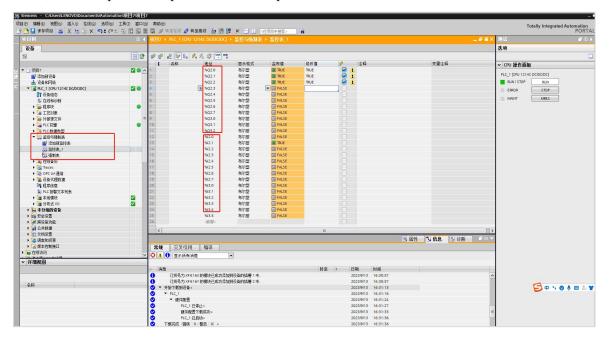
11. After setting up, click on compile and download the PLC program.



12. Click "Go Online" to check if the connection status of the module is normal.

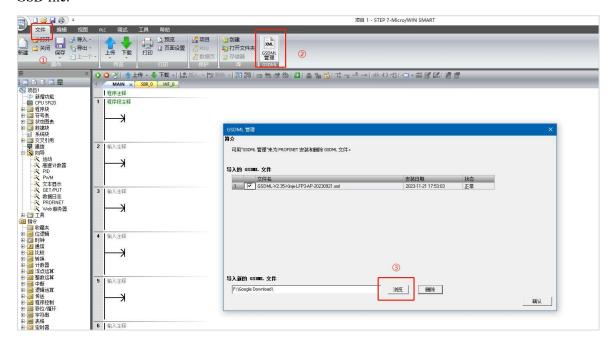


13. In the "Monitoring and Enforcement Table", a monitoring table can be added, mapped IO addresses can be added, and the input and output status of the expansion module can be monitored in real time.

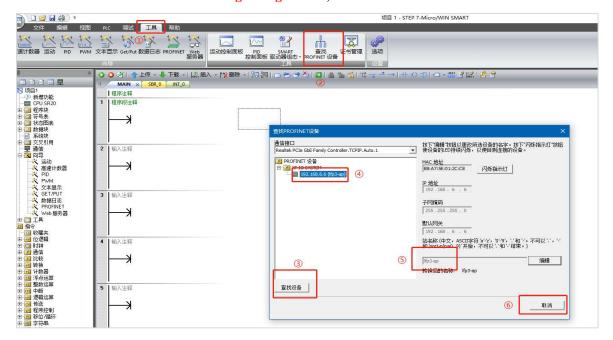


3.3.6.2 LFP3-AP connected to Siemens S7-200SMART

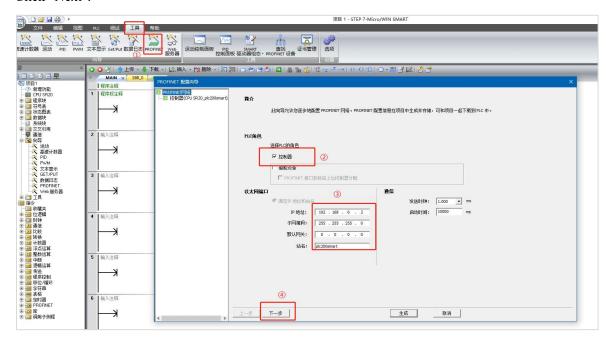
- 1. Require 200SMART firmware version V2.05 and above.
- 2. Power on the module and S7-200SMART, and connect the network port to the PC. Open the Siemens STEP 7-MicroWIN SMART software. Under the "File" menu, click on "GSDML Management". In the pop-up window, click browse to find the GSD file for LFP3-AP and click open to complete the installation of the GSD file.



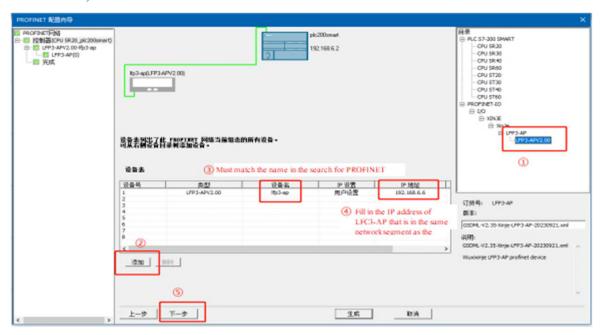
3. Click on the tool, click find PROFINET device, click find device, find LFC3-AP module, the module device name is lfp3-ap, you can click "EDIT" to customize the name. (Discovered device name, it needs to be consistent with this name during configuration)



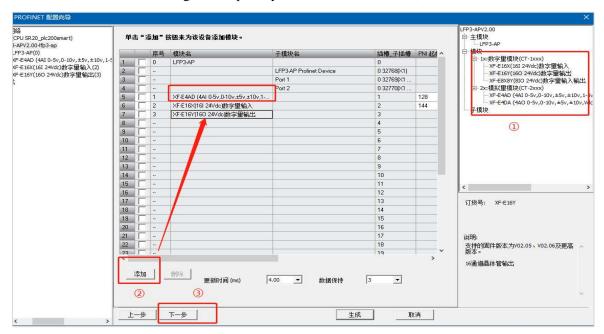
4. Click on the tool and then click on PROFINET. Select the controller and modify the IP address of the PLC. Click "Next".



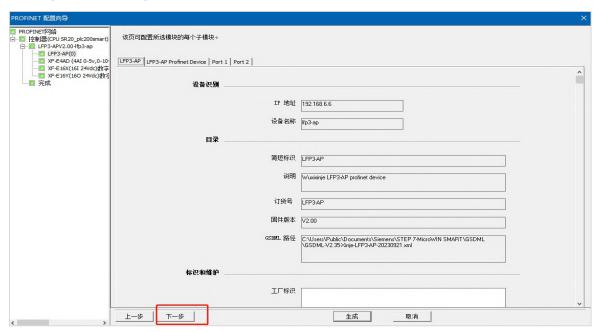
5. Find LFP3-AP in the hardware directory, add it to the device list, and modify the device name to LFP3-AP (Must match the name in the search for PROFINET devices), the IP address assigned to LFC3-AP simultaneously is 192.168.6.6 (located in the same network segment as the PLC's IP). After completing the modifications, click "Next".



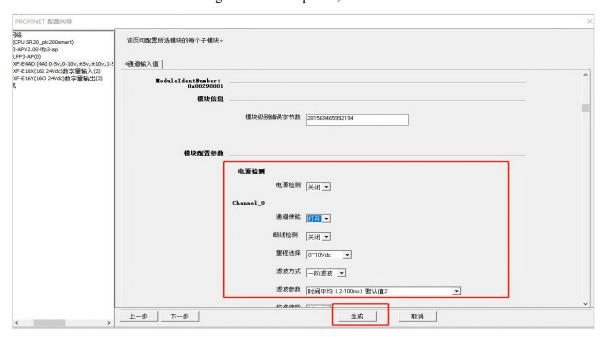
6. According to the IO module model attached after LFP3-AP, manually add the corresponding module. You can view the addresses and lengths occupied by each module in the PLC, and click "Next".



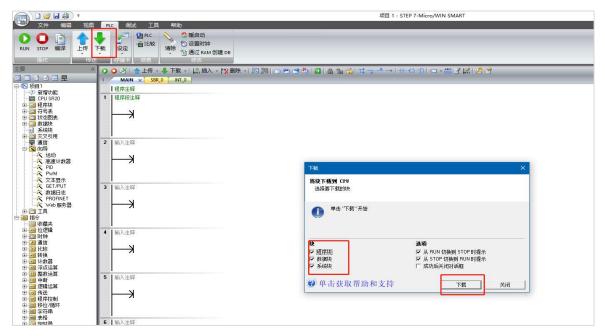
7. For the parameter description of LFP3-AP, click "Next directly".



8. Parameters can be configured for each module, and detailed configuration instructions can be found in the manuals of each module. After configuration is completed, click "Production".

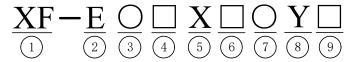


9. Click download in the "PLC" menu, select all block downloads, and click "Download". After downloading, check if the RUN indicator light of LFP3-AP is always on, which indicates a successful connection and normal operation.



4. Digital quantity module unit

4.1 Naming rules



1	Series name	XF:	XF series expansion module
2	Refers to the extension module	E:	Represents the right expansion module
3	Input channel	4:	4 channels
		8:	8 channels
		16:	16 channels
		32:	32 channels
		64:	64 channels
4	Input point type	Empty:	Digital input PNP&NPN compatible
		N:	Digital input NPN type
		P:	Digital input PNP type
(5)	Type	X:	Digital input
6	Output channel	4:	4 channels
		8:	8 channels
		16:	16 channels
		32:	32 channels
		64:	64 channels
7	Type of output	Empty:	Digital output NPN type
		P:	Digital output PNP type
8	Type	Υ:	Digital output
9	Output point type	T:	Digital output transistor type
		R:	Digital output relay type

4.2 Digital input unit XF-E16X

4.2.1 Overview

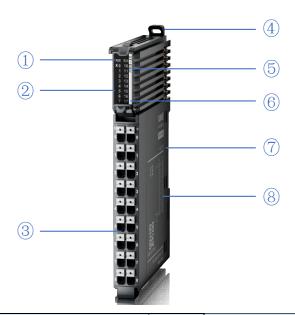
The XF-E16X series digital input expansion module has 16 channels of digital input, supports NPN and PNP inputs, and is compatible with XF, XSF series CPU units and XF series communication coupler units.

- 16 channel digital input.
- Complies with IEC-61131 input standard type 3.
- NPN&PNP bipolar input.
- 12mm width design.
- Module version

Hardware version Firmware version		Function
H2.0 V2.0		Basic functions for the first official production

4.2.2 Module view

1) Description of each section

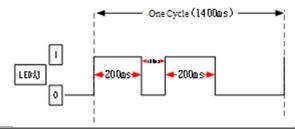


No.	Name	No.	Name
1	System LED indicator lights	2	Channel LED indicator light
3	Detachable terminal block	4	Snap
(5)	Model indication	6	Color identification indicating module type
7	Module hardware and firmware versions	8	Wiring diagram

2) System indicator

System indicator	Explanation		
	Extinguish	Module not powered on	
PWR(Green)	Light	All external power supplies of the module are normal	
		(Backplane bus power supply&external input 24V)	
	Light	The module is running normally	
	Flash 1Hz*1	General errors in module logs	
RUN(Green)	Extinguish	Important errors in module logs	
	Flash 10Hz*2	Module establishing communication	
	Double flashing*3	Module firmware update	

- *1: A square wave with a duty cycle of 50% and a frequency of 1Hz.
- *2: A square wave with a duty cycle of 50% and a frequency of 10Hz.
- *3: As shown in the following figure:



3) Channel indicator light

Model	Channel indicator light		
VE E1CV	V0 V17	Light (Green)	Corresponding input channel has input ON signal
XF-E16X	X0-X17	Extinguish	Corresponding input channel has no input ON signal

4) Color identification

No.	Colour		Module type
1	White		Digital input
2		Grey	Digital output & Digital mixing module
3		Light blue	Analog input
4		Deep blue	Analog output

4.2.3 General specification

General specification				
Project		Specifications		
	Maximum	55°C		
Operating temperature	temperature			
operating temperature	Minimum	-20°C		
	temperature			
	Maximum	70°C		
Transportation/Storage	temperature	70 0		
temperature	Minimum	-40°C		
	temperature	- 1 0 C		

		General specification		
Project		Specifications		
Environmental humidity Upper limit		95%		
(including	Lower limit	10%		
operation/storage)	Lower IIIIII	10%		
IP code		IP20		
		Compliant with IEC61131-2		
		Under intermittent vibration (frequency 5-9Hz, constant amplitude		
		3.5mm peak displacement) and (frequency 9-150Hz, constant		
Anti vibration		acceleration 1.0g peak acceleration)		
And violation		Under continuous intermittent vibration (frequency 5-9Hz half		
		amplitude 1.75mm displacement) and (frequency 9-150Hz constant		
		acceleration 0.5g constant frame amplitude)		
		Scan 10 times in X, Y, and Z directions		
		Complies with IEC61131-2 standard		
Impact registance		The impact strength is 15G (peak) and the duration is 11ms. It is		
Impact resistance		applied to three mutually perpendicular axes, and each axis is		
		impacted 3 times (a total of 18 impacts)		
Using environment		Non corrosive gas		
Using altitude		0-2000 m		
Overvoltage level		II: Compliant with IEC61131-2		
Pollution level		2: Compliant with IEC61131-2		
Anti interference EMC		Compliant with IEC 61131-2 IEC61000-6-4 Type B		
Related certifications		CE		

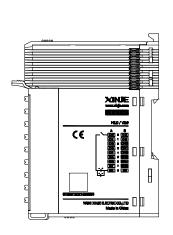
4.2.4 Technical specifications

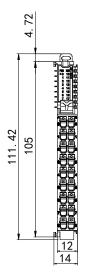
Project	Specifications		
Input	16		
Rated input voltage	DC24V		
Rated input current	6mA		
Input ON voltage	11v		
Input ON current	2.5mA		
Input OFF voltage	5v		
Input OFF current	1mA		
Input resistor ON → OFF response time	20		
(hardware)	20us		
Input resistor OFF \rightarrow ON response time	100us		
(hardware)			
Input derating	Derate by 75% when operating at 60 °C (with no more than 12 ON		
input derating	input points), or by 10 °C when all input points are ON		
Public end method	8 ports 1 public terminal		
Wiring method	See external terminal connection diagram		
Module power consumption	1.3W		
Module weight	80g		

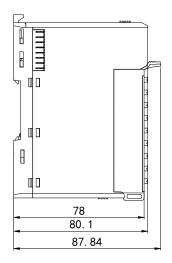
4.2.5 Installation&Wiring

4.2.5.1 Appearance dimension diagram

(Unit: mm)







4.2.5.2 Terminal definition&Wiring

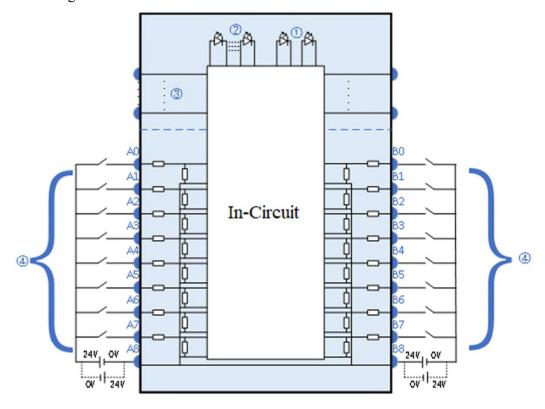
■ Terminal definition

XF-E16X					
Meaning	A-column terminal	Terminal layout	B-column terminal	Meaning	
CH0	0		0	СН8	
CH1	1		1	СН9	
CH2	2		2	CH10	
СНЗ	3	3	3	CH11	
CH4	4	4004	4	CH12	
CH5	5	5 3	5	CH13	
СН6	6		6	CH14	
CH7	7	7 7	7	CH15	
SS	8	• 🗔 🗖 •	8	SS	



Two SS have internal short circuits, so all input points of a single module can only choose between NPN or PNP.

■ External wiring

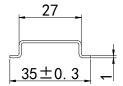


- 1 System indicator
- (2) Channel indicator light
- 3 Backplane bus
- 4 Input channels&wiring

4.2.5.3 Installation method

1) Installation requirements

The module is installed using DIN rails, which must comply with the IEC 60715 standard (35mm wide, 1mm thick), the size information is shown in the following figure, the unit is (mm).

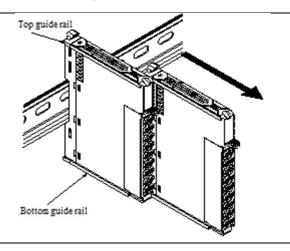




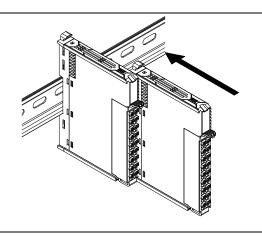
Note

When the module is installed on a non recommended DIN rail, the DIN rail latch may not lock properly.

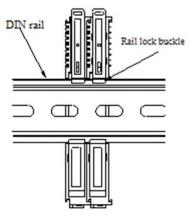
2) Installation steps



1. The assembly between IO modules is installed by sliding through the top and bottom guide rails of the modules, as shown in the left figure:

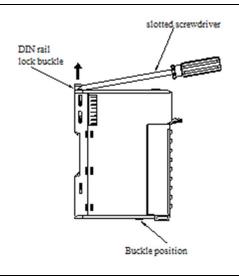


2. The module is installed on the rail, and during installation, align the module with the DIN rail, press the module in the direction indicated by the arrow, after installation, there is a noticeable snap sound, As shown in the left figure:

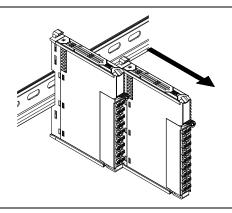


Explanation: After the module installation is completed, the locking buckle will automatically move downwards for locking, if the latch does not move downwards, press down on the top of the latch, ensure proper installation.

3) Disassembly steps



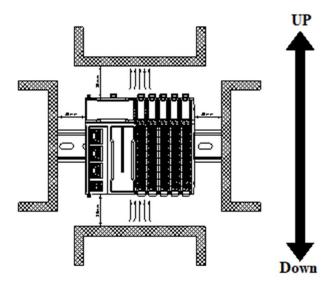
1. Use a flat screwdriver or similar tool to pry the rail lock upwards, as shown in the left figure:



2. Pull the module straight forward at the buckle position (raised part), after completion, press down on the top of the latch, as shown in the left image:

4.2.5.4 Installation environment

This product can be installed in four positions (i.e. installation direction): horizontal, vertical, top of cabinet, and bottom of cabinet, it is recommended to install in a horizontal direction, and the heat dissipation design should be through natural convection, to ensure normal ventilation and heat dissipation, and to reserve sufficient wiring space, the minimum gap must be maintained around this product, as shown in the following figure:



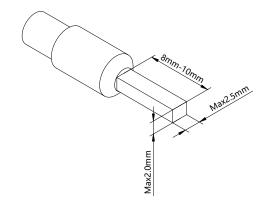
If there are high-temperature heat source equipment (heaters, transformers, large resistors, etc.) around this product, leave at least 100mm gap between the equipment and the high-temperature heat source.

4.2.5.5 Equipment wiring

When wiring the module, its terminal must meet the following requirements:

Adaptor diameter			
National standard/mm ²	American standard/AWG		
0.3	22		
0.5	20		
0.75	18		
1.0	18		
1.5	16		

If using other tube type wire ears, please crimp them to the twisted wire. The shape and size requirements are shown in the following figure:



4.2.6 Usage of XF-E16X and LFC3-AP

4.2.6.1 Process data mapping (PDO)

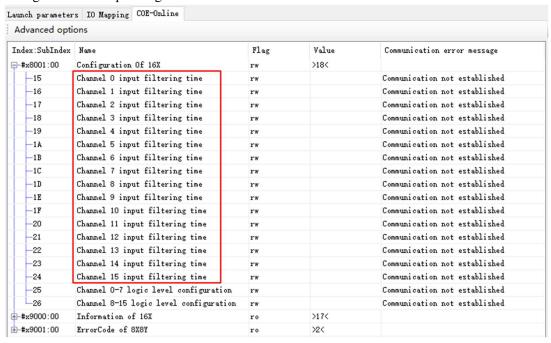
Name	Туре	Explanation
XF_E16X	Stuct	16 channel input module
CH0_X0	BOOL	Channel 0 input value
———— CH1_X1	BOOL	Channel 1 input value
——————————————————————————————————————	BOOL	Channel 2 input value
СН3_Х3	BOOL	Channel 3 input value
CH4_X4	BOOL	Channel 4 input value
CH5_X5	BOOL	Channel 5 input value
СН6_Х6	BOOL	Channel 6 input value
CH7_X7	BOOL	Channel 7 input value
CH8_X10	BOOL	Channel 8 input value
СН9_Х11	BOOL	Channel 9 input value
CH10_X12	BOOL	Channel 10 input value
CH11_X13	BOOL	Channel 11 input value
CH12_X14	BOOL	Channel 12 input value
CH13_X15	BOOL	Channel 13 input value
CH14_X16	BOOL	Channel 14 input value
CH15_X17	BOOL	Channel 15 input value

4.2.6.2 Module configuration parameters (SDO)

Variable name	Type	Notes
Channel 0 input filtering time	BYTE	
Channel 1 input filtering time	BYTE	
Channel 2 input filtering time	BYTE	
Channel 3 input filtering time	BYTE	0: No filtering 11: 9ms
Channel 4 input filtering time	BYTE	1: 0.25ms 12: 10ms
Channel 5 input filtering time	BYTE	2: 0.5ms 13: 11ms
Channel 6 input filtering time	BYTE	3: 1ms (Default) 14: 12ms
Channel 7 input filtering time	BYTE	4: 2ms 15: 13ms 5: 3ms 16: 14ms
Channel 8 input filtering time	BYTE	5: 3ms 16: 14ms 6: 4ms 17: 15ms
Channel 9 input filtering time	BYTE	7: 5ms 18: 20ms
Channel 10 input filtering time	BYTE	8: 6ms 19: 30ms
Channel 11 input filtering time	BYTE	9: 7ms 20: 64ms
Channel 12 input filtering time	BYTE	10: 8ms 21: 128ms
Channel 13 input filtering time	BYTE	
Channel 14 input filtering time	BYTE	
Channel 15 input filtering time	BYTE	
Channel 0-7 logic level configuration	BYTE	0: Positive logic (default). 1: Negative logic
Channel 8-15 logic level configuration	ВҮТЕ	bit0~bit7corresponds to channels 0~7 (bit8~bit15corresponds to channels 8~15)

Channel input filtering time

"Filtering time" corresponds to a separate filtering parameter for each channel, and double-click the parameter name to configure the corresponding value.



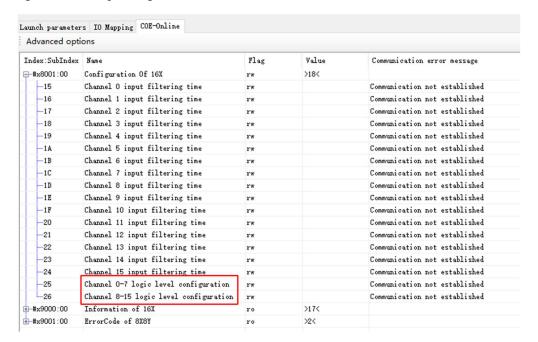
Parameter definition

When there is a signal at the input terminal and the signal duration exceeds the filtering time, it is considered as a valid signal

Settable parameters	Configure the corresponding index objects in COE-Online, startup parameters, or
	SDO read and write instructions: unfiltered, 0.25ms, 0.5ms, 1ms, 2ms, 3ms, 4ms,
	5ms, 6ms, 7ms, 8ms, 9ms, 10ms, 11ms, 12ms, 13ms, 14ms, 15ms, 20ms, 30ms,
	64ms, 128ms
Default parameters	1ms

■ Channel logic level

"Logic level configuration" each channel corresponds to a separate logic level, and double-click on the parameter name to configure the corresponding value.

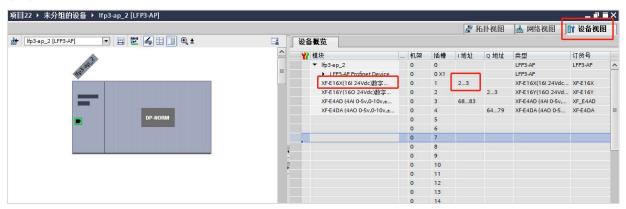


	Program execution logic after external signal input				
	External input	Logic level	Running	Operation	
	signal	configuration	programs	result	
Parameter definition	X0=1	Positive logic	LD X0.	Y0=1	
	X0=1	Negative logic	OUT Y0.	Y0=0	
	X0=0	Positive logic		Y0=0	
	X0=0	Negative logic		Y0=1	
Configure the corresponding index objects in COE-Online or startup			r startup parameters:		
Settable parameters	positive logic (default), negative logic.				

4.2.7 Usage of XF-E16X and LFP3-AP

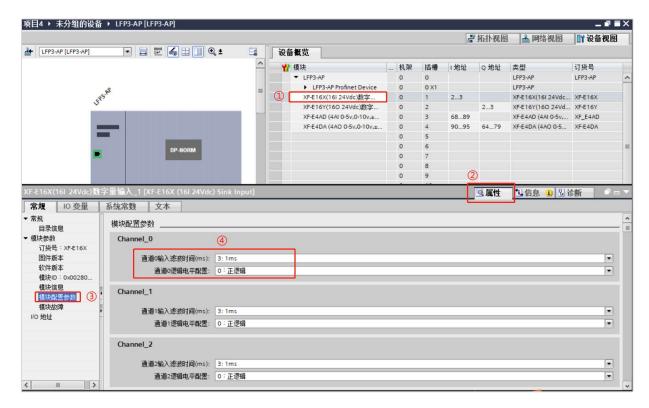
4.2.7.1 Process data mapping

In the device view, the mapping address of module process data can be viewed, with case mapping addresses ranging from I2.0-I3.7.



Name	Туре	Explanation
XF_E16X	Stuct	16 channel input module
I2.0	BOOL	Channel 0 input value
I2.1	BOOL	Channel 1 input value
I2.2	BOOL	Channel 2 input value
I2.3	BOOL	Channel 3 input value
I2.4	BOOL	Channel 4 input value
I2.5	BOOL	Channel 5 input value
I2.6	BOOL	Channel 6 input value
I2.7	BOOL	Channel 7 input value
I3.0	BOOL	Channel 8 input value
I3.1	BOOL	Channel 9 input value
I3.2	BOOL	Channel 10 input value
I3.3	BOOL	Channel 11 input value
I3.4	BOOL	Channel 12 input value
I3.5	BOOL	Channel 13 input value
I3.6	BOOL	Channel 14 input value
I3.7	BOOL	Channel 15 input value

4.2.7.2 Module configuration parameters



■ Channel input filtering time

"Filtering time" corresponds to a separate filtering parameter for each channel, and the setting method is to select the parameter from the drop-down menu.

D	When there is a signal at the input terminal and the signal duration exceeds the
Parameter definition	filtering time, it is considered as an effective signal
Settable parameters	0ms, 0.25ms, 0.5ms, 1ms, 2ms, 3ms, 4ms, 5ms, 6ms, 7ms, 8ms, 9ms, 10ms, 11ms,
	12ms, 13ms, 14ms, 15ms, 20ms, 30ms, 64ms, 128ms
Default parameters	1ms

■ Channel logic level

"Logic level configuration" Each channel corresponds to a separate logic level configuration. The setting method is to select parameters from the drop-down menu.

	Program execution logic after external signal input				
	External input	Logic level	Running	Operation	
	signal	configuration	programs	result	
Parameter definition	X0=1	X0=1 Positive logic		Y0=1	
	X0=1	Negative logic	OUT Y0.	Y0=0	
	X0=0	Positive logic		Y0=0	
	X0=0 Negative logic			Y0=1	
C + 11	The following table pulling method reflects the adjustable parameters: positive logic,				
Settable parameters	negative logic				

4.3 Digital output unit XF-E16YT

4.3.1 Overview

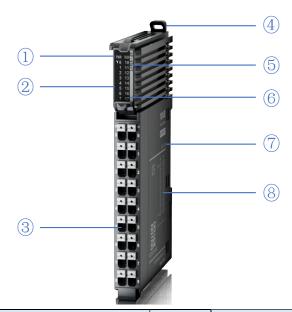
XF-E16YT series digital output expansion module, which has 16 channels of digital output, support NPN output, compatible with XF, XSF series CPU unit products and XF series communication coupler units.

- 16 channel digital output.
- NPN output .
- Designed with a width of 12mm.
- Module version

Hardware version	Firmware version	Function
H2.0	V2.0	Basic functions for the first official production

4.3.2 Module view

1) Description of each section

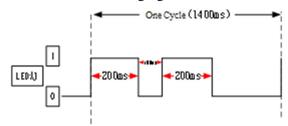


No.	Name	No.	Name
1	System LED indicator lights	2	Channel LED indicator light
3	Detachable terminal block	4	Snap
(5)	Model indication	6	Color identification indicating module type
7	Module hardware and firmware versions	8	Wiring diagram

2) System indicator

System indicator	Explanation			
	Extinguish	Module not powered on		
	Light	All external power supplies of the module are normal (backplane		
PWR(Green)		bus power supply&external input 24V)		
	Flash1Hz*1	Abnormal power supply in the module and inability to operate		
		normally		
	Light	The module is running normally		
	Flash1Hz*1	General errors in module logs		
RUN(Green)	Extinguish	Important errors in module logs		
	Flash10Hz*2	Module establishing communication		
	Double flashing*3	Module firmware update		

- *1: A square wave with a duty cycle of 50% and a frequency of 1Hz.
- *2: A square wave with a duty cycle of 50% and a frequency of 10Hz.
- *3: As shown in the following figure:



3) Channel indicator light

Model	Channel indicator light		
VE E16VT	XF-E16YT Y0-Y17	Light(Green)	Corresponding input channel has input ON signal
ΑΓ-Ε1011		Extinguish	Corresponding input channel has no input ON signal

4) Color identification

No.	Colou	ır	Module type
1		White	Digital input
2		Grey	Digital output&digital mixing module
3		Light blue	Analog input
4		Deep blue	Analog output

4.3.3 General specification

General specification			
Project		Specifications	
	Maximum	55°C	
On anating tampanatura	temperature	33 C	
Operating temperature	Minimum	-20°C	
	temperature	-20°C	
	Maximum	70°C	
Transportation/Storage	temperature	70 C	
Temperature	Minimum	-40°C	
	temperature	-4 0 C	

General specification			
Project		Specifications	
Environmental humidity (including operation/storage) Upper limit Lower limit		95%	
		10%	
IP code		IP20	
Anti vibration		Compliant with IEC61131-2 Under intermittent vibration (frequency 5-9Hz, constant amplitude 3.5mm peak displacement) and (frequency 9-150Hz, constant acceleration 1.0g peak acceleration) Under continuous intermittent vibration (frequency 5-9Hz half amplitude 1.75mm displacement) and (frequency 9-150Hz constant acceleration 0.5g constant frame amplitude) Scan 10 times in X, Y, and Z directions	
Impact resistance		Complies with IEC61131-2 standard The impact strength is 15G (peak) and the duration is 11ms. It is applied to three mutually perpendicular axes, and each axis is impacted 3 times (a total of 18 impacts)	
Using environment		Non corrosive gas	
Using altitude		0-2000 m	
Overvoltage level		II: Compliant with IEC61131-2	
Pollution level		2: Compliant with IEC61131-2	
Anti interference EMC		Compliant with IEC 61131-2 IEC61000-6-4 Type B	
Related certifications		CE	

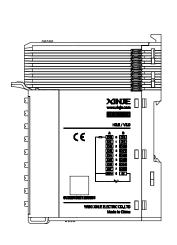
4.3.4 Technical specifications

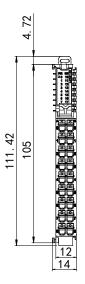
Project	Specifications	
Output	16	
Rated load voltage	DC24V(DC10.2V~28.8V)	
Maximum load current	0.5A/1 point, 4A/module	
Surge current protection	Support	
Leakage current when OFF	Below 0.1mA	
Maximum voltage drop during ON	0.5V~1V	
Output ON \rightarrow OFF response time	0.1ms	
(hardware)	0.1ms	
Output OFF \rightarrow ON response time	0.1ms	
(hardware)	0.11118	
Output derating	Reduce the rating by 50% when operating at 55 °C (while the output	
	current of ON does not exceed 2A), or reduce the rating by 10 °C	
	when the output point is fully ON	
Public end method	16 ports 1 public terminal	
Output protection	Supports short circuit and overload protection functions	
Module power consumption	1.3W (backplane bus)+0.4W (external input)	
Module weight	80g	

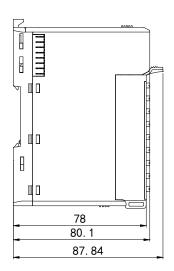
4.3.5 Installation&Wiring

4.3.5.1 Appearance dimension diagram

(Unit: mm)





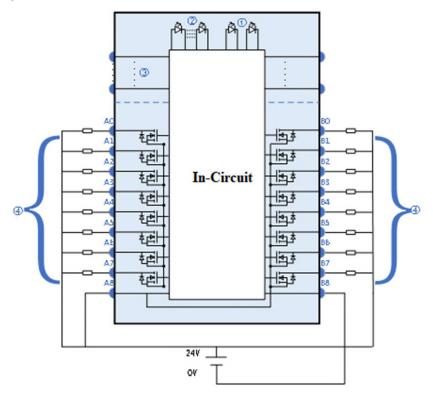


4.3.5.2 Terminal definition&Wiring

■ Terminal definition

XF-E16YT				
Meaning	A-column terminal	Terminal layout	B-column terminal	Meaning
СН0	0		0	CH8
CH1	1		1	СН9
CH2	2	2 2	2	CH10
СНЗ	3		3	CH11
CH4	4	4 4	4	CH12
CH5	5	5 5	5	CH13
СН6	6		6	CH14
CH7	7	7 7	7	CH15
24V+	8	•	8	0V

External wiring

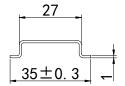


- 1 System indicator
- (2) Channel indicator light (3) Backplane bus
- 4 Output Channel&Wiring

4.3.5.3 Installation method

1) Installation requirements

The module is installed using DIN rails, which must comply with the IEC 60715 standard (35mm wide, 1mm thick), the size information is shown in the following figure, the unit is (mm).

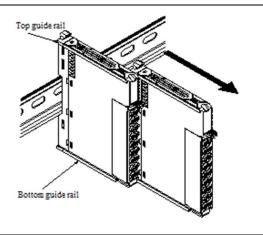




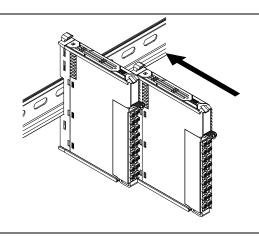
Note

When the module is installed on a non recommended DIN rail as mentioned above, the DIN rail latch may not lock properly.

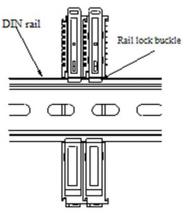
2) Installation steps



The assembly between IO modules is installed by 1. sliding through the top and bottom guide rails of the modules, as shown in the left figure:

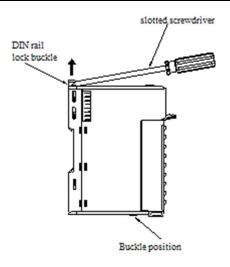


2. The module is installed on the guide rail, and during installation, align the module with the DIN rail and press the module in the direction indicated by the arrow, after installation, there is a noticeable snap sound, as shown in the left image:

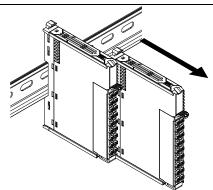


Explanation: After the module installation is completed, the locking buckle will automatically move downwards for locking, if the latch does not move downwards, press down on the top of the latch, ensure proper installation.

3) Disassembly steps



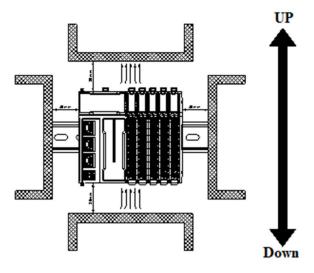
1. Use a flat screwdriver or similar tool to pry the rail lock upwards, as shown in the left figure:



2. Pull the module straight forward at the buckle position (raised part), after completion, press down on the top of the latch, as shown in the left image:

4.3.5.4 Installation environment

This product can be installed in four positions (i.e. installation direction): horizontal, vertical, top of cabinet, and bottom of cabinet, it is recommended to install in a horizontal direction, and the heat dissipation design should be through natural convection, to ensure normal ventilation and heat dissipation, and to reserve sufficient wiring space, the minimum gap must be left around this product, as shown in the following figure:



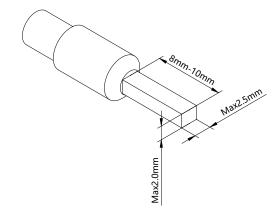
If there are high-temperature heat source equipment (heaters, transformers, large resistors, etc.) around this product, leave at least 100mm gap between the equipment and the high-temperature heat source.

4.3.5.5 Equipment wiring

When wiring the module, its terminal must meet the following requirements:

Adaptor diameter			
National standard/mm ²	American standard/AWG		
0.3	22		
0.5	20		
0.75	18		
1.0	18		
1.5	16		

If using other tube type wire ears, please crimp them to the twisted wire. The shape and size requirements are shown in the following figure:



4.3.6 Usage of XF-E16Y and LFC3-AP

4.3.6.1 Process data mapping (PDO)

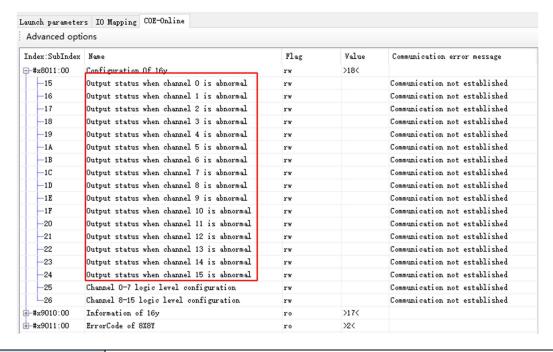
Name	Туре	Explanation
XF_E16YT	Stuct	16 channel output module
СН0_Ү0	BOOL	Channel 0 output value
CH1_Y1	BOOL	Channel 1 output value
CH2_Y2	BOOL	Channel 2 output value
СН3_Ү3	BOOL	Channel 3 output value
СН4_Ү4	BOOL	Channel 4 output value
CH5_Y5	BOOL	Channel 5 output value
СН6_Ү6	BOOL	Channel 6 output value
СН7_Ү7	BOOL	Channel 7 output value
CH8_Y10	BOOL	Channel 8 output value
СН9_Ү11	BOOL	Channel 9 output value
CH10_Y12	BOOL	Channel 10 output value
CH11_Y13	BOOL	Channel 11 output value
CH12_Y14	BOOL	Channel 12 output value
CH13_Y15	BOOL	Channel 13 output value
CH14_Y16	BOOL	Channel 14 output value
CH15_Y17	BOOL	Channel 15 output value

4.3.6.2 Module configuration parameters (SDO)

Byte sequence number	Туре	Note
Channel 0 output status in case of abnormality	ВҮТЕ	
Channel 1 output status in case of abnormality	ВҮТЕ	
Channel 2 output status in case of abnormality	BYTE	
Channel 3 output status in case of abnormality	BYTE	
Channel 4 output status in case of abnormality	BYTE	
Channel 5 output status in case of abnormality	BYTE	
Channel 6 output status in case of abnormality	BYTE	
Channel 7 output status in case of abnormality	BYTE	0: Output replacement value OFF (default)
Channel 8 output status in case of abnormality	BYTE	1: Keep previous value 2: Output replacement value ON
Channel 9 output status in case of abnormality	BYTE	
Channel 10 output status in case of abnormality	ВҮТЕ	
Channel 11 output status in case of abnormality	ВҮТЕ	
Channel 12 output status in case of abnormality	ВҮТЕ	
Channel 13 output status in case of abnormality	ВҮТЕ	
Channel 14 output status in case of abnormality	BYTE	
Channel 15 output status in case of abnormality	BYTE	
Channel 0-7 logic level configuration	BYTE	0: Positive logic (default). 1: Negative logic
Channel 8-15 logic level configuration	ВҮТЕ	Bit0~bit7 corresponds to channels 0~7 (bit8~bit15corresponds to channels 8~15)

■ Abnormal/STOP output status

"Abnormal/STOP output status" Each channel corresponds to a separate parameter, and double-click on the parameter name to configure the corresponding value.



	Configure the corresponding index objects in COE-Online, startup parameters, or			
Parameter definition	SDO read and write instructions: "Output replacement value OFF", "Keep previous			
	value", "Output replacement value ON"			
	Output	When the PLC is in STOP mode, the output terminal is in a		
	replacement	reset state (physical terminal, regardless of channel logic level)		
	value OFF			
	Keep previous value	When the PLC is in abnormal/STOP mode, the output terminal		
Settable parameters		outputs the last state of the PLC from RUN to STOP (physical		
		terminal, regardless of channel logic level).		
	Output	When the PLC is in abnormal/STOP mode, the output terminal		
	replacement	is in the set state (physical terminal, regardless of channel logic		
	value ON	level).		
Default parameters	Output replacement value OFF			

■ Channel logic level

"Logic level configuration" each channel corresponds to a separate logic level, and double-click on the parameter name to configure the corresponding value.

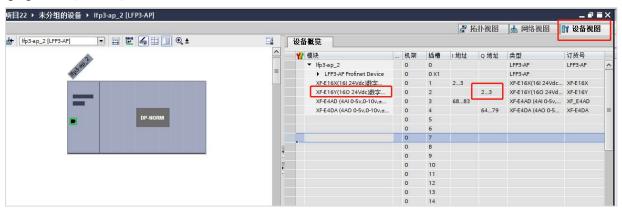
	ons			
Index:SubIndex	Name	Flag	Value	Communication error message
=#x8011:00	Configuration Of 16y	rw	>18<	
-15	Output status when channel O is abnormal	rw		Communication not established
-16	Output status when channel 1 is abnormal	rw		Communication not established
-17	Output status when channel 2 is abnormal	rw		Communication not established
-18	Output status when channel 3 is abnormal	rw		Communication not established
-19	Output status when channel 4 is abnormal	rw		Communication not established
-1A	Output status when channel 5 is abnormal	rw		Communication not established
-1B	Output status when channel 6 is abnormal	rw		Communication not established
-1C	Output status when channel 7 is abnormal	rw		Communication not established
—1D	Output status when channel 8 is abnormal	rw		Communication not established
-1E	Output status when channel 9 is abnormal	rw		Communication not established
-1F	Output status when channel 10 is abnormal	rw		Communication not established
-20	Output status when channel 11 is abnormal	rw		Communication not established
-21	Output status when channel 12 is abnormal	rw		Communication not established
-22	Output status when channel 13 is abnormal	rw		Communication not established
-23	Output status when channel 14 is abnormal	rw		Communication not established
-24	Output status when channel 15 is abnormal	rw		Communication not established
-25	Channel 0-7 logic level configuration	rw		Communication not established
<u></u> 26	Channel 8-15 logic level configuration	rw		Communication not established
#x9010:00	Information of 16y	ro	>17<	
#x9011:00	ErrorCode of 8X8Y	ro	>2<	

Parameter definition	Configure the corresponding index objects in COE-Online, startup parameters, or SDO read and write instructions: positive logic, negative logic			
	SDO lead alld wi	ne msu ucuons.	positive logic, negativ	e logic
	The program exe	cution logic after	r external signal input.	
	Logic level	Running	Operation result	
Settable parameters	configuration	programs		
	Positive logic	SET Y0.	Y0 set to ON	
	Negative logic		Y0 set to OFF	
	Positive logic	RST Y0.	Y0 set to OFF	
	Negative logic		Y0 set to ON	
Default parameters	Configure the corresponding index objects in COE-Online, startup parameters, or			
	SDO read and write instructions: positive logic (default), negative logic.			

4.3.7 Usage of XF-E16Y and LFP3-AP

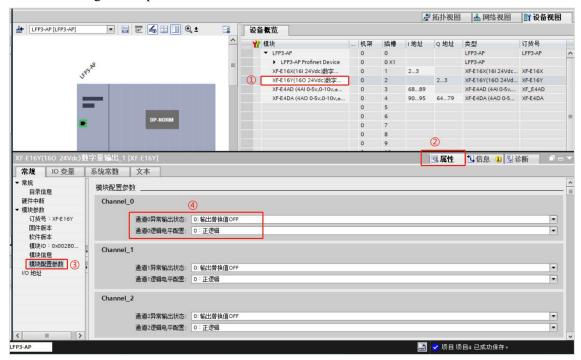
4.3.7.1 Process data mapping

In the device view, the mapping address of module process data can be viewed, with case mapping addresses ranging from Q2.0 to Q3.7.



Name	Туре	Explanation
XF_E16YT	Stuct	16 channel output module
Q2.0	BOOL	Channel 0 output value
Q2.1	BOOL	Channel 1 output value
Q2.2	BOOL	Channel 2 output value
Q2.3	BOOL	Channel 3 output value
Q2.4	BOOL	Channel 4 output value
Q2.5	BOOL	Channel 5 output value
Q2.6	BOOL	Channel 6 output value
Q2.7	BOOL	Channel 7 output value
Q3.0	BOOL	Channel 8 output value
Q3.1	BOOL	Channel 9 output value
Q3.2	BOOL	Channel 10 output value
Q3.3	BOOL	Channel 11 output value
Q3.4	BOOL	Channel 12 output value
Q3.5	BOOL	Channel 13 output value
Q3.6	BOOL	Channel 14 output value
Q3.7	BOOL	Channel 15 output value

4.3.7.2 Module configuration parameters



■ Abnormal/STOP output status

"Abnormal/STOP output status" each channel corresponds to a separate parameter, which can be set by selecting the parameter from the drop-down menu.

Parameter	The following table pulling method reflects the adjustable parameters: "Output				
definition	replacement value OFF", "Keep previous value", "Output replacement value ON"				
	Output replacement When the PLC is in STOP mode, the output terminal is i				
	value OFF	state (physical terminal, regardless of channel logic level).			
0 4 11	Keep previous	When the PLC is in abnormal/STOP mode, the output terminal			
	value	outputs the last state of the PLC from RUN to STOP (physical			
Settable parameters		terminal, regardless of channel logic level).			
	Output replacement	When the PLC is in abnormal/STOP mode, the output terminal is			
	value ON	in the set state (physical terminal, regardless of channel logic			
		level).			
Default parameters	Output replacement v	alue OFF			

■ Channel logic level

"Logic level configuration" Each channel corresponds to a separate logic level configuration. The setting method is to select parameters from the drop-down menu.

Parameter	The following table pulling method reflects the adjustable parameters: positive logic,			
definition	negative logic			
	The program execution logic after external signal input.			
	Logic level configuration	Running programs	Operation result	
Settable parameters	Positive logic	SET Y0.	Y0 set to ON	
	Negative logic		Y0 set to OFF	
	Positive logic	RST Y0.	Y0 set to OFF	
	Negative logic		Y0 set to ON	
D C 1	The following table pulling method reflects the adjustable parameters: positive logic,			
Default parameters	negative logic			

4.4 Digital input output hybrid unit XF-E8NX8YT

4.4.1 Overview

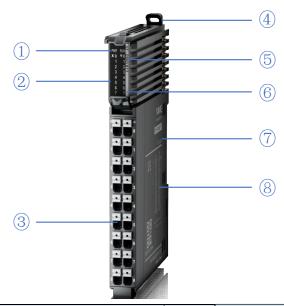
XF-E8NX8YT series digital input output hybrid expansion module, which has 8 channels of digital input and supports NPN input. 8-channel digital output, supporting NPN output, compatible with XF, XSF series CPU units and XF series communication coupler units.

- 8-channel digital input.
- NPN type input.
- 8-channel digital output.
- NPN type output.
- 12mm width design.
- Module version

Hardware version	Firmware version	Function	
H2.0	V2.0	Basic functions for the first official production	

4.4.2 Module view

1) Description of each section



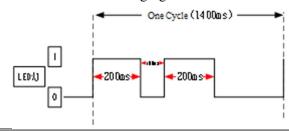
No.	Name	No.	Name
1	System LED indicator lights	2	Channel LED indicator light
3	Detachable terminal block	4	Snap
5	Model indication	6	Color identification indicating module type
7	Module hardware and firmware versions	8	Wiring diagram

2) System indicator

System indicator	Explanation			
	Extinguish	Module not powered on		
PWR(Green)	Light All external power supplies of the module are normal (backplane bus power supply&external input 24V)			

System indicator	Explanation		
	Flash1Hz*1	Abnormal power supply in the module and inability to operate	
	riasiii fiz	normally	
	Light	The module is running normally	
RUN(Green)	Flash1Hz*1	General errors in module logs	
	Extinguish	Important errors in module logs	
	Flash10Hz*2	Module establishing communication	
	Double flashing*3	Module firmware update	

- *1: A square wave with a duty cycle of 50% and a frequency of 1Hz.
- *2: A square wave with a duty cycle of 50% and a frequency of 10Hz.
- *3: As shown in the following figure:



3) Channel indicator light

Model	Channel indicator light		
VE E16V	X0-X7	Light (Green)	Corresponding input channel has input ON signal
XF-E16X	Y0-Y7	Extinguish	Corresponding input channel has no input ON signal

4) Color identification

No.	Colour		Module type
1	White		Digital input
2		Grey	Digital output&digital mixing module
3		Light blue	Analog input
4		Deep blue	Analog output

4.4.3 General specification

	General specification		
Project		Specifications	
	Maximum	55°C	
Operating temperature	temperature		
Operating temperature	Minimum	-20°C	
	temperature	-20 C	
	Maximum	70°C	
Transportation/Storage	temperature	70 C	
Temperature	Minimum	-40°C	
	temperature	-40 C	
Environmental humidity	Upper limit	95%	
(including	Lower limit	10%	
operation/storage)	Lower mint	10/0	
IP code		IP20	

General specification			
Project Specifications			
	Compliant with IEC61131-2		
	Under intermittent vibration (frequency 5-9Hz, constant		
	amplitude 3.5mm peak displacement) and (frequency 9-150Hz,		
Anti vibration	constant acceleration 1.0g peak acceleration)		
And violation	Under continuous intermittent vibration (frequency 5-9Hz half		
	amplitude 1.75mm displacement) and (frequency 9-150Hz		
	constant acceleration 0.5g constant frame amplitude)		
	Scan 10 times in X, Y, and Z directions		
	Complies with IEC61131-2 standard		
Impact resistance	The impact strength is 15G (peak) and the duration is 11ms. It is		
impact resistance	applied to three mutually perpendicular axes, and each axis is		
	impacted 3 times (a total of 18 impacts)		
Using environment	Non corrosive gas		
Using altitude	0-2000 m		
Overvoltage level	II: Compliant with IEC61131-2		
Pollution level	2: Compliant with IEC61131-2		
Anti interference EMC	Compliant with IEC 61131-2 IEC61000-6-4 Type B		
Related certifications	CE		

4.4.4 Technical specifications

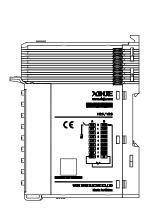
Project		Specifications	
	Input channel	8	
	Input type	NPN	
	Rated input voltage	DC24V	
	Rated input current	6mA	
	Input ON voltage	15v	
	Input ON current	3mA	
Input	Input OFF voltage	5V	
specifications	Input OFF current	1mA	
specifications		Reduce the rating by 50% when operating at 55 °C (with	
	Input derating	no more than 4 input points on simultaneously), or by	
		10 °C when all input points are on	
	Input resistor ON → OFF response	20us	
	time (hardware)	2008	
	Input resistor OFF → ON response	100us	
	time (hardware)	Toous	
	Output channel	8	
	Output type	Transistor (NPN)	
Output	Rated load voltage	DC24V(DC10.2V~28.8V)	
	Maximum load current	0.5A/1 point	
specifications	Surge current protection	Support	
	Leakage current when OFF	Below 0.1mA	
	Maximum voltage drop during ON	0.5A, 2A/module	

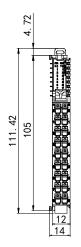
Project		Specifications	
		Reduce the rating by 50% when operating at 55 °C (while	
	Output derating	the output current of ON does not exceed 2A), or reduce	
		the rating by 10 °C when the output point is fully ON	
	Input resistor ON → OFF response	100us	
	time (hardware)		
	Input resistor OFF → ON response	100us	
	time (hardware)		
Module	Module power consumption	1.3W (backplane bus)+1.7W (external input)	
specifications	Module weight	80g	

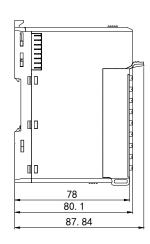
4.4.5 Terminal definition&Wiring

4.4.5.1 Appearance dimension diagram

(Unit: mm)





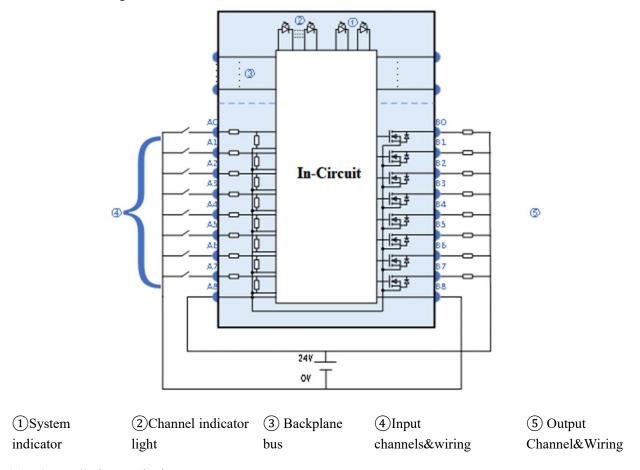


4.4.5.2 Terminal definition&Wiring

■ Terminal definition

XF-E8NX8YT					
Meaning	A-column terminal	Terminal layout	B-column terminal	Meaning	
CH0	0		0	СН8	
CH1	1	1 1	1	СН9	
CH2	2		2	CH10	
СН3	3		3	CH11	
CH4	4	4 4	4	CH12	
CH5	5		5	CH13	
СН6	6		6	CH14	
CH7	7		7	CH15	
24V+	8	•	8	0V	

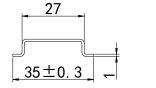
■ External wiring



4.4.5.3 Installation method

1) Installation requirements

The module is installed using DIN rails, which must comply with the IEC 60715 standard (35mm wide, 1mm thick), the size information is shown in the following figure, in millimeters.

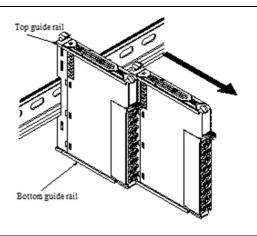




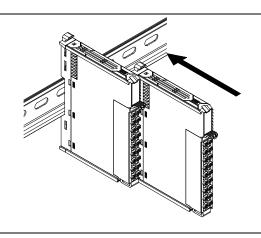
Note

When the module is installed on a non recommended DIN rail, the DIN rail latch may not lock properly.

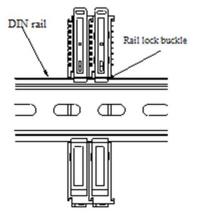
2) Installation steps



1. The assembly between IO modules is installed by sliding through the top and bottom guide rails of the modules, as shown in the left figure:

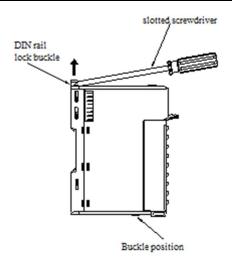


2. The module is installed on the guide rail. When installing, align the module with the DIN guide rail and press the module in the direction indicated by the arrow. After installation, there is a clear sound of engagement, as shown in the left figure:

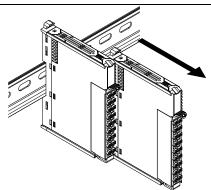


Explanation: After the module installation is completed, the latch will automatically move downwards to lock. If the latch does not move downwards, press down on the top of the latch to ensure proper installation.

3) Disassembly steps



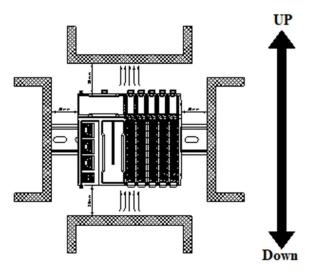
1. Use a flat screwdriver or similar tool to pry the rail lock upwards, as shown in the left figure:



2. Pull the module straight forward at the buckle position (raised part), and then press down on the top of the latch, as shown in the left figure:

4.4.5.4 Installation environment

This product can be installed in four positions (i.e. installation direction): horizontal, vertical, top of cabinet, and bottom of cabinet. It is recommended to install in the horizontal direction, and the heat dissipation design is through natural convection. To ensure normal ventilation and heat dissipation and reserve sufficient wiring space, the minimum gap must be left around this product, as shown in the following figure:



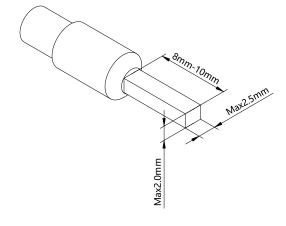
If there are high-temperature heat source equipment (heaters, transformers, large resistors, etc.) around this product, leave at least 100mm gap between the equipment and the high-temperature heat source.

4.4.5.5 Equipment wiring

When wiring the module, its terminal must meet the following requirements:

Adaptor diameter			
National standard/mm ²	American standard/AWG		
0.3	22		
0.5	20		
0.75	18		
1.0	18		
1.5	16		

If using other tube type wire ears, please crimp them to the twisted wire. The shape and size requirements are shown in the following figure:



$4.4.6\ Usage\ of\ XF\text{-}E8NX8YT\ and\ LFC3\text{-}AP$

4.4.6.1 Process data mapping (PDO)

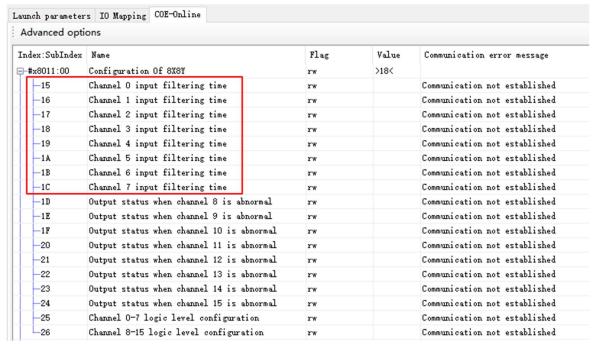
Name	Туре	Explanation
XF_E8X8Y	Stuct	8-channel input and 8-channel output module
CH8_Y0	BOOL	Channel 8 output value
СН9_Ү1	BOOL	Channel 9 output value
CH10_Y2	BOOL	Channel 10 output value
CH11_Y3	BOOL	Channel 11 output value
——————————————————————————————————————	BOOL	Channel 12 output value
——————————————————————————————————————	BOOL	Channel 13 output value
CH14_Y6	BOOL	Channel 14 output value
CH15_Y7	BOOL	Channel 15 output value
СН0_Х0	BOOL	Channel 0 input value
CH1_X1	BOOL	Channel 1 input value
CH2_X2	BOOL	Channel 2 input value
CH3_X3	BOOL	Channel 3 input value
CH4_X4	BOOL	Channel 4 input value
CH5_X5	BOOL	Channel 5 input value
СН6_Х6	BOOL	Channel 6 input value
CH7_X7	BOOL	Channel 7 input value

4.4.6.2 Module configuration parameters (SDO)

Byte sequence number	Туре	Note
Channel 0 input filtering time	BYTE	0: No filtering 11: 9ms
Channel 1 input filtering time	BYTE	1: 0.25ms
Channel 2 input filtering time	BYTE	2: 0.5ms 13: 11ms 3: 1ms (Default) 14: 12ms
Channel 3 input filtering time	BYTE	4: 2ms 15: 13ms
Channel 4 input filtering time	BYTE	5: 3ms 16: 14ms 6: 4ms 17: 15ms
Channel 5 input filtering time	BYTE	7: 5ms 18: 20ms
Channel 6 input filtering time	BYTE	8: 6ms 19: 30ms 9: 7ms 20: 64ms
Channel 7 input filtering time	BYTE	10: 8ms 21: 128ms
Channel 8 output status in case of abnormality	BYTE	
Channel 9 output status in case of abnormality	ВҮТЕ	
Channel 10 output status in case of abnormality	ВҮТЕ	
Channel 11 output status in case of abnormality	ВҮТЕ	0: Output replacement value OFF (default)
Channel 12 output status in case of abnormality	ВҮТЕ	1: Keep previous value 2: Output replacement value ON
Channel 13 output status in case of abnormality	ВҮТЕ	
Channel 14 output status in case of abnormality	ВҮТЕ	
Channel 15 output status in case of abnormality	BYTE	
Channel 0-7 logic level configuration	BYTE	0: Positive logic (default). 1: Negative logic
Channel 8-15 logic level configuration	ВҮТЕ	bit0~bit7corresponds to channels 0~7 (bit8~bit15corresponds to channels 8~15)

■ Channel input filtering time

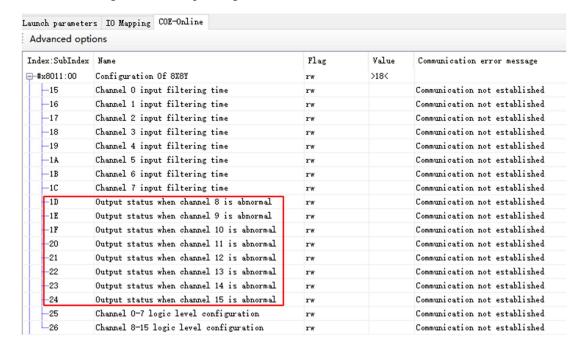
"Filtering time" corresponds to a separate filtering parameter for each channel, and double-click the parameter name to configure the corresponding value.



Donomatan definition	When there is a signal at the input terminal and the signal duration exceeds the
Parameter definition	filtering time, it is considered as an effective signal
	Configure the corresponding index objects in COE-Online, startup parameters, or
0 4 11	SDO read and write instructions: unfiltered, 0.25ms, 0.5ms, 1ms, 2ms, 3ms, 4ms,
Settable parameters	5ms, 6ms, 7ms, 8ms, 9ms, 10ms, 11ms, 12ms, 13ms, 14ms, 15ms, 20ms, 30ms,
	64ms, 128ms
Default parameters	1ms

■ Abnormal/STOP output status

"Abnormal/STOP output status" Each channel corresponds to a separate parameter, and double-click on the parameter name to configure the corresponding value.



	Configure the corresponding index objects in COE-Online, startup parameters, or SDO read and write instructions: "Output replacement value OFF", "Keep previous value",		
Parameter definition			
	"Output replacement value ON"		
	Output replacement	When the PLC is in STOP mode, the output terminal is in a reset	
	value OFF	state (physical terminal, regardless of channel logic level)	
	Settable parameters Keep previous value	When the PLC is in abnormal/STOP mode, the output terminal	
C-44-1.1		outputs the last state of the PLC from RUN to STOP (physical	
Settable parameters		terminal, regardless of channel logic level)	
	Output nonle coment	When the PLC is in abnormal/STOP mode, the output terminal	
value ON	Output replacement	is in the set state (physical terminal, regardless of channel logic	
	value ON	level)	
Default parameters	Output replacement value OFF		

■ Channel logic level

"Logic level configuration" Each channel corresponds to a separate logic level, and double-click on the parameter name to configure the corresponding value.

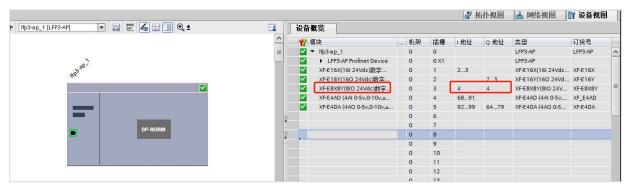
Advanced opti	ions			
Index:SubIndex	Name	Flag	Value	Communication error message
=-#x8011:00	Configuration Of 8X8Y	rw	>18<	
-15	Channel O input filtering time	rw		Communication not established
-16	Channel 1 input filtering time	rw		Communication not established
-17	Channel 2 input filtering time	rw		Communication not established
-18	Channel 3 input filtering time	rw		Communication not established
-19	Channel 4 input filtering time	rw		Communication not established
—1À	Channel 5 input filtering time	rw		Communication not established
—1B	Channel 6 input filtering time	rw		Communication not established
—1C	Channel 7 input filtering time	rw		Communication not established
—1D	Output status when channel 8 is abnormal	rw		Communication not established
—1E	Output status when channel 9 is abnormal	rw		Communication not established
—1F	Output status when channel 10 is abnormal	rw		Communication not established
-20	Output status when channel 11 is abnormal	rw		Communication not established
-21	Output status when channel 12 is abnormal	rw		Communication not established
-22	Output status when channel 13 is abnormal	rw		Communication not established
-23	Output status when channel 14 is abnormal	rw		Communication not established
-24	Output status when channel 15 is abnormal	rw		Communication not established
-25	Channel 0-7 logic level configuration	rw		Communication not established
L-26	Channel 8-15 logic level configuration	rw		Communication not established

Parameter definition	The following table pulling method reflects the adjustable parameters: positive logic,			
negative logic				
	Program execution logic after external signal input			
	Logic level configuration	Running programs	Operation result	
Settable parameters	Positive logic	SET Y0.	Y0 set to ON	
	Negative logic		Y0 set to OFF	
	Positive logic	RST Y0.	Y0 set to OFF	
	Negative logic		Y0 set to ON	
Default parameters	Configure the corresponding index objects in COE-Online or startup parameters: positive logic (default), negative logic			

4.4.7 Usage of XF-E8NX8YT and LFP3-AP

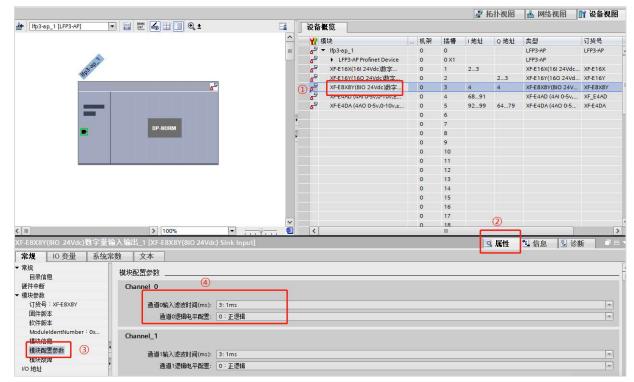
4.4.7.1 Process data mapping

In the device view, the mapping addresses of module process data can be viewed, with case mapping addresses being I4.0-I4.7 and Q4.0-Q4.7.



Name	Type	Explanation
XF_E8X8Y	Stuct	8-channel input and 8-channel output module
I4.0	BOOL	Channel 0 input value
I4.1	BOOL	Channel 1 input value
I4.2	BOOL	Channel 2 input value
I4.3	BOOL	Channel 3 input value
I4.4	BOOL	Channel 4 input value
I4.5	BOOL	Channel 5 input value
I4.6	BOOL	Channel 6 input value
I4.7	BOOL	Channel 7 input value
Q4.0	BOOL	Channel 8 input value
Q4.1	BOOL	Channel 9 input value
Q4.2	BOOL	Channel 10 input value
Q4.3	BOOL	Channel 11 input value
Q4.4	BOOL	Channel 12 input value
Q4.5	BOOL	Channel 13 input value
Q4.6	BOOL	Channel 14 input value
Q4.7	BOOL	Channel 15 input value

4.4.7.2 Module configuration parameters



■ Channel input filtering time

"Filtering time"Each channel corresponds to a separate filtering parameter, which can be set by selecting the parameter from the drop-down menu.

Donomoton definition	When there is a signal at the input terminal and the signal duration exceeds the filtering	
Parameter definition	time, it is considered as an effective signal	
	The following table pulling method reflects the adjustable parameters: No filtering,	
Settable parameters	0.25ms, 0.5ms, 1ms, 2ms, 3ms, 4ms, 5ms, 6ms, 7ms, 8ms, 9ms, 10ms, 11ms, 12ms,	
	13ms, 14ms, 15ms, 20ms, 30ms, 64ms, 128ms	
Default parameters	1ms	

■ Abnormal/STOP output status

"Abnormal/STOP output status" Each channel corresponds to a separate parameter, which can be set by selecting a parameter from the drop-down menu.

Parameter definition	The following table	pulling method reflects the adjustable parameters: "Output		
rarameter definition	replacement value OFF", "Keep previous value", "Output replacement value ON"			
	Output replacement	When the PLC is in STOP mode, the output terminal is in a reset		
	value OFF	state (physical terminal, regardless of channel logic level)		
		When the PLC is in abnormal/STOP mode, the output terminal		
Cattable managestans	Keep previous value	outputs the last state of the PLC from RUN to STOP (physical		
Settable parameters		terminal, regardless of channel logic level)		
	O	When the PLC is in abnormal/STOP mode, the output terminal		
	1 1	is in the set state (physical terminal, regardless of channel logic		
	value ON	level)		
Default parameters	Output replacement value OFF			
Default parameters	Output replacement value ON Output replacement va	is in the set state (physical terminal, regardless of channel logic level)		

■ Channel logic level

"Logic level configuration" Each channel corresponds to a separate logic level configuration. The setting method is to select parameters from the drop-down menu.

Parameter definition	The following table p	The following table pulling method reflects the adjustable		
r arameter definition	negative logic			
	The program execution	n logic after externa	al signal input.	
	Logic level	Running	Operation result	
Settable parameters	configuration	programs		
	Positive logic	SET Y0.	Y0 set to ON	
	Negative logic		Y0 set to OFF	
	Positive logic	RST Y0.	Y0 set to OFF	
	Negative logic		Y0 set to ON	
Default navamatara	The following table 1	oulling method refl	ects the adjustable pa	
Default parameters (default), negative logic				

5. Analog module unit

5.1 Naming rules



1	Series name	XF:	XF series expansion module
2	Refers to the extension module	Е:	Represents the right expansion module
3	Input channel	1:	1 channel
		2:	2 channel
		4:	4 channel
		6:	6 channel
		8:	8 channel
4	Type	AD:	Indicates analog voltage and current input
5	Output channel	1:	1 channel
		2:	2 channel
		4:	4 channel
		6:	6 channel
		8:	8 channel
6	Type	DA:	Indicates analog voltage and current input
7	Analog quantity type	Empty:	Indicating current&voltage type
		A:	Indicating current type
		V:	Indicating voltage type
8	Module type	Empty:	General
		Н:	Channel to channel isolation
		S:	High-precision
		U:	High speed

5.2 Analog input unit XF-E4AD

5.2.1 Overview

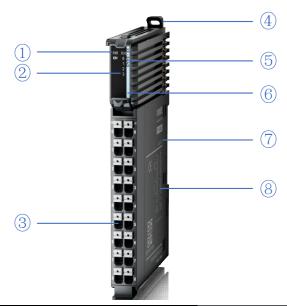
XF-E4AD series analog input expansion module, which has 4 channels of analog input, supports current and voltage inputs, adapt to XF, XSF series CPU unit products and XF series communication coupler units.

- 4-channel analog input.
- Channel conversion speed 60us/channel.
- Maximum 0.2% error.
- Voltage and current input.
- Designed with a width of 12mm.
- Module version

Hardware version	Firmware version	Function
H2.0	V2.0	Basic functions for the first official production

5.2.2 Module view

1) Description of each section

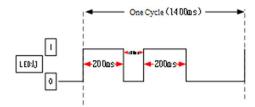


No.	Name	No.	Name
1	System LED indicator lights	2	Channel LED indicator light
3	Detachable terminal block	4	Snap
(5)	Model indication	6	Color identification indicating module type
7	Module hardware and firmware versions	8	Wiring diagram

2) System indicator

System indicator	Explanation			
Extinguish		Module not powered on		
DWD (Croon)	Light	All external power supplies of the module are normal (backplane bus		
PWR (Green)		power supply & external input 24V)		
Flash1Hz*1		Abnormal power supply in the module and inability to operate normally		
	Light	The module is running normally		
	Flash1Hz*1	General errors in module logs		
RUN (Green)	Extinguish	Important errors in module logs		
	Flash10Hz*2	Module establishing communication		
	Double	M 11 C		
	flashing*3	Module firmware update		

- *1: A square wave with a duty cycle of 50% and a frequency of 1Hz.
- *2: A square wave with a duty cycle of 50% and a frequency of 10Hz.
- *3: As shown in the following figure:



3) Channel indicator light

Model	Channel indicator light			
VE E4AD	VE E4AD CHO CH2		Channel enabled and configured correctly	
XF-E4AD	СН0~СН3	Extinguish	Mute channel	

4) Color identification

No.	Colour		Module type
1		White	Digital input
2		Grey	Digital output&digital mixing module
3		Light blue	Analog input
4		Deep blue	Analog output

5.2.3 General specification

General specification			
Project		Specifications	
	Maximum	55°C	
On anoting tammanatura	temperature	33 6	
Operating temperature	Minimum	-20°C	
	temperature	-20 C	
	Maximum	70°C	
Transportation/Storage	temperature	70 C	
Temperature	Minimum	-40°C	
	temperature	- 1 0 C	

Environmental	Upper limit	95%		
humidity (including operation/storage)	Lower limit	10%		
IP code		IP20		
		Compliant with IEC61131-2		
		Under intermittent vibration (frequency 5-9Hz, constant amplitude		
		3.5mm peak displacement) and (frequency 9-150Hz, constant		
Anti vibration		acceleration 1.0g peak acceleration)		
Allu vioration		Under continuous intermittent vibration (frequency 5-9Hz half		
		amplitude 1.75mm displacement) and (frequency 9-150Hz constant		
		acceleration 0.5g constant frame amplitude)		
		Scan 10 times in X, Y, and Z directions		
		Complies with IEC61131-2 standard		
Impact resistance		The impact strength is 15G (peak) and the duration is 11ms. It is		
Impact resistance		applied to three mutually perpendicular axes, and each axis is		
		impacted 3 times (a total of 18 impacts)		
Using environment		Non corrosive gas		
Using altitude		0-2000 m		
Overvoltage level		II: Compliant with IEC61131-2		
Pollution level		2: Compliant with IEC61131-2		
Anti interference EMC		Compliant with IEC 61131-2 IEC61000-6-4 Type B		
Related certifications CE		CE		

5.2.4 Technical specifications

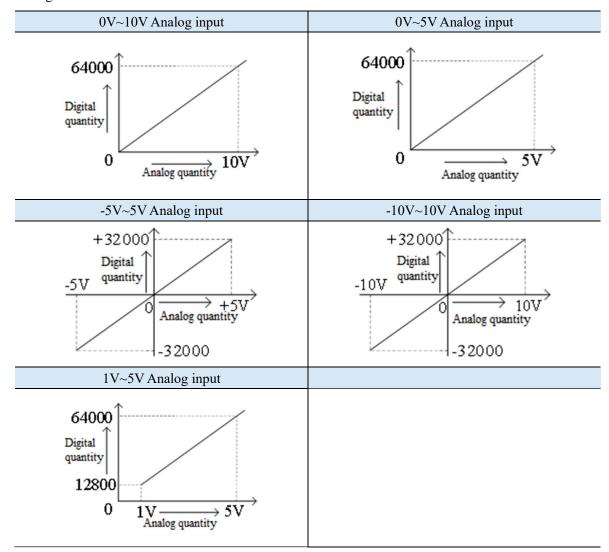
5.2.4.1 Module performance

Project		Specifications		
Input channel		4		
		0V~5V (0~64000)		
		0V~10V (0~64000)		
	Voltage input range	-5V~5V (-32000~32000)		
Analog input		-10V~10V (-32000~32000)		
range (rated)		1v~5v (12800~64000)		
		0mA~20mA (0~64000)		
	Current input range	4mA~20mA (12800~64000)		
		-20mA~20mA (-32000~32000)		
Maximum input	Voltage input	DC±15V		
range	Current input	-40~40mA		
Conversion speed		60us/CH		
Resolution ratio		1/64000 (16Bit)		
Module power	Rated input	DC24V±10%, 150mA		
supply	Protect	Reverse polarity protection		
Room temperature 25°C=		±0.1% (25±5 °C)		
EHOI	Full temperature end -20~55°C	±0.2%		
Isolated		Channel non isolated, power isolated		
Module power consumption		0.8W (backplane bus)+0.8W (external input)		

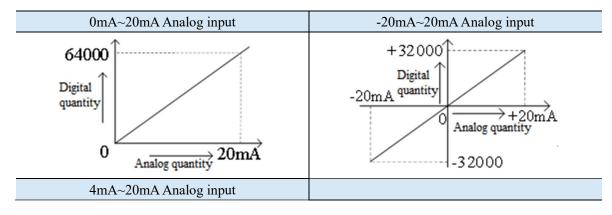
Module weight 80g

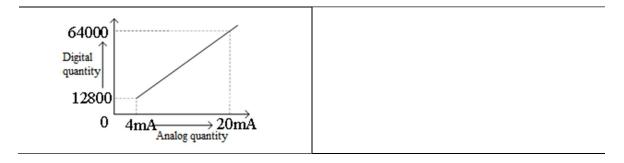
5.2.4.2 Analog-to-digital conversion diagram

■ Voltage



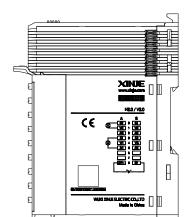
■ Current

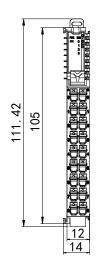


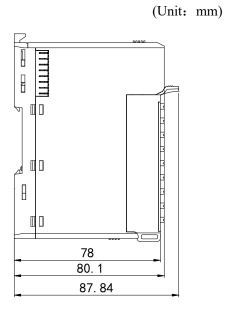


5.2.5 Terminal definition&Wiring

5.2.5.1 Appearance dimension diagram







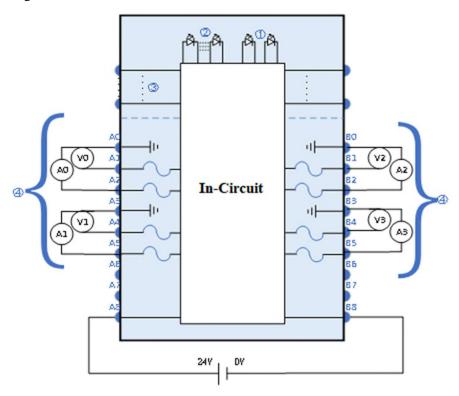
5.2.5.2 Terminal definition&Wiring

■ Terminal definition

XF-E4AD					
Meaning	A-column terminal	Terminal layout	B-column terminal	Meaning	
CH0- Input ground	0		0	CH2- Input ground	
CH0-AD analog voltage input terminal	1		1	CH2-AD analog voltage input terminal	
CH0-AD analog current input terminal	2	2 2	2	CH2-AD analog current input terminal	
CH1- Input ground	3	3 3	3	CH3- Input ground	
CH1-AD analog voltage input terminal	4	4	4	CH3-AD analog voltage input terminal	
CH1-AD analog current input terminal	5		5	CH3-AD analog current input terminal	
Empty	6		6	Empty	
Empty	7	•	7	Empty	

XF-E4AD				
Meaning	A-column terminal	Terminal layout	B-column terminal	Meaning
External 24V power supply for module positive	8		8	External power supply to the module 24V power supply negative

External wiring

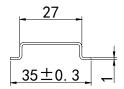


- 1)System indicator
- 2) Channel indicator light 3) Backplane bus
- 4 Input channels & wiring

5.2.5.3 Installation method

1) Installation requirements

The module is installed using DIN rails, which must comply with the IEC 60715 standard (35mm wide, 1mm thick). The dimension information is shown in the following figure, and the unit is (mm).

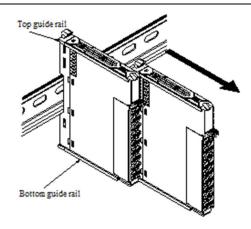




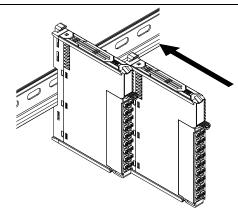
Note

When the module is installed on a non recommended DIN rail, the DIN rail latch may not lock properly.

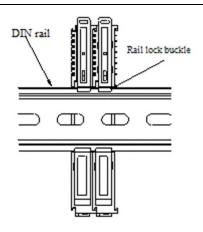
2) Installation steps



1. The assembly between IO modules is installed by sliding through the top and bottom guide rails of the modules, as shown in the left figure:

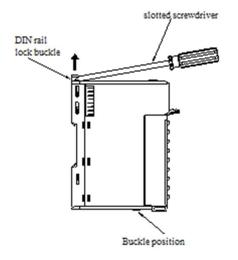


2. The module is installed on the guide rail. When installing, align the module with the DIN guide rail and press the module in the direction indicated by the arrow. After installation, there is a clear sound of engagement, as shown in the left figure:

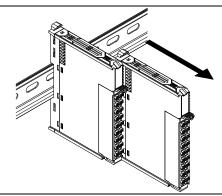


Explanation: After the module installation is completed, the locking buckle will automatically move downwards for locking, if the latch does not move downwards, press down on the top of the latch, ensure proper installation.

3) Disassembly steps



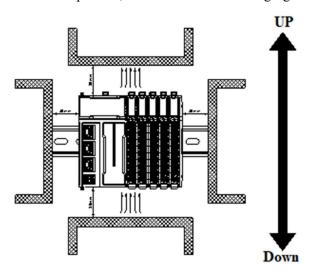
1. Use a flat screwdriver or similar tool to pry the rail lock upwards, as shown in the left figure:



2. Pull the module straight forward at the buckle position (raised part), and then press down on the top of the latch, as shown in the left figure:

5.2.5.4 Installation environment

This product can be installed in four positions (i.e. installation direction): horizontal, vertical, top of cabinet, and bottom of cabinet. It is recommended to install in the horizontal direction, and the heat dissipation design is through natural convection. To ensure normal ventilation and heat dissipation and reserve sufficient wiring space, the minimum gap must be left around this product, as shown in the following figure:



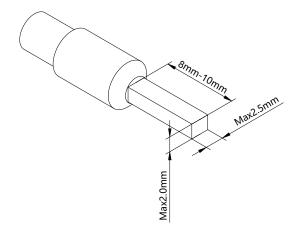
If there are high-temperature heat source equipment (heaters, transformers, large resistors, etc.) around this product, leave at least 100mm gap between the equipment and the high-temperature heat source.

5.2.5.5 Equipment wiring

When wiring the module, its terminal must meet the following requirements:

Adaptor diameter			
National standard/mm ²	American standard/AWG		
0.3	22		
0.5	20		
0.75	18		
1.0	18		
1.5	16		

If using other tube type wire ears, please crimp them to the twisted wire. The shape and size requirements are shown in the following figure:



5.2.6 Usage of XF-E4AD and LFC3-AP

5.2.6.1 Process data mapping (PDO)

Name	Type	Explanation
XF_E4AD	Stuct	4-channel input module
СН0	DINT	Channel 0 input value
——— CH1	DINT	Channel 1 input value
———— CH2	DINT	Channel 2 input value
CH3	DINT	Channel 3 input value
ErrCode_module	WORD	Module level error codes
ErrCode_CH	DWORD	Channel level error code

■ Error code parameters

	Module level error codes (ErrCode_module)	
Bit position	Meaning	Error level
0	The 24V input power supply of the module is abnormal	Important

Module level error codes (ErrCode_module)			
Bit position	Meaning	Error level	
2	Internal module error occurred and cannot be fixed by the user layer	Important	
3	Version mismatch	Important	
4	ADC/DAC read/write failure	Important	

Channel level error code (ErrCode_CH)			
Bit position	Meaning	Error level	
0	Channel 0 upper limit overflow	General	
1	Channel 0 lower limit overflow	General	
2	Channel 0 disconnected	Important	
3	Reserve	-	
4	Channel 1 upper limit overflow	General	
5	Channel 1 lower limit overflow	General	
6	Channel 1 disconnected	Important	
7	Reserve	-	
8	Channel 2 upper limit overflow	General	
9	Channel 2 lower limit overflow	General	
10	Channel 2 disconnected	Important	
11	Reserve	-	
12	Channel 3 upper limit overflow	General	
13	Channel 3 lower limit overflow	General	
14	Channel 3 disconnected	Important	

5.2.6.2 Module configuration parameters (SDO)

Parameter	Туре	Channel	No	ote
Power detection	E		0: Close	1: Open
Channel enable/disable	Enumeration of BYTE		0: Close	1: Open
Enable/disable wire breakage detection	Enumeration_of BYTE		0: Close	1: Open
Range selection	ВҮТЕ	Channel	0: 0~10V(Default) 1: 0~5V 2: -10~10V 3: -5~5V	4: 1~5V 5: 0~20mA 6: 4~20mA 7: -20~20mA
Filtering method	ВҮТЕ	0-4	0: First order filtering 1: Time average	2: Averagenumber of times3: Moving average
Filtering parameter	INT		Time average (2-100n Average frequency (4 Moving average (2-50 First order delay filte	-500) default value 4 00) default value 2

Parameter	Туре	Channel	Note
			to 0 (no filtering)
Calibration enable/disable	Enumeration of BYIE		0: Close 1: Open
Calibration 1 analog	INT		Voltage input
quantity			0~10V: Analog range: 0-10000mV
			Digital range: 0-64000
			0~5V:
			Analog range:0-5000mV Digital range: 0-64000
			-10~10V:
Calibration 1 digital quantity	DINT		Analog range: -10000-10000mV Digital range: -32000-32000
1 2			-5~5V:
			Analog range: -5000-5000mV Digital range: -32000-32000
			1~5V:
			Analog range: 1000mV-5000mV Digital range: 12800-64000
Calibration 2 analog	DIT		Current input
quantity	INT		0~20mA:
			Analog range: 0-20000uA Digital range: 0-64000
			4~20mA:
Calibration 2 digital	DINT		Analog range: 4000-20000uA Digital range: 12800-64000
quantity			-20~20mA:
			Analog range: -20000-20000uA
Enable/disable unit			Digital range: -32000-32000
display conversion	Enumeration of BYTE		0: Close 1: Open
Unit display conversion			
limit	DINT		Range: -100000000~100000000 and after
	DINT		conversion of enabled units (Upper limit-Lower limit) > 0
Unit Display Conversion Lower Limit			
Enable/disable upper and			
lower limit overflow	Enumeration of BYTE		0: Close 1: Open
settings Upper limit overflow			Analog range: in mV, uA units, for
analog quantity	INT		example: 0~10V: 0~10000mV
Upper limit overflow	DINT		Voltage input

Parameter	Туре	Channel	Note
output digital quantity			0~10V:
Lower limit overflow	INT		Analog range: 0-10000mV
analog quantity	INI		Digital range: 0-64000
Lower limit overflow	DINT		0~5V:
output digital quantity	DINT		Analog range: 0-5000mV
			Digital range: 0-64000
			-10~10V:
			Analog range: -10000-10000mV
			Digital range: -32000-32000
			-5~5V:
	DINT		Analog range: -5000-5000mV
			Digital range: -32000-32000
			1~5V:
Lower limit overflow			Analog range: 1000mV-5000mV
			Digital range: 12800-64000
output digital quantity			Current input
			0~20mA:
			Analog range: 0-20000uA
			Digital range: 0-64000
			4~20mA:
			Analog range: 4000-20000uA
			Digital range: 12800-64000
			-20~20mA:
			Analog range: -20000-20000uA
			Digital range: -32000-32000

- Module power supply detection
- Check if the external 24V power supply of the module is normal.
- Normal: The module is running normally.
- Exception: The module channel cannot be used but can be configured, configured, and scanned normally.
- Can set parameters: enable or disable (default is disabled).



■ Channel enable/disable

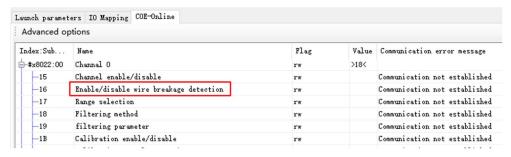
Enable or disable AD sampling channels to save module sampling time.

Advanced opti	ons			
Index:SubIndex	Name	Flag	Value	Communication error message
=-#x8021:00	Module	rw	>1<	
L-01	Power Detection	rw		Communication not established
#x8022:00	Channal O	rw	>18<	
-15	Channel enable/disable	rw		Communication not established
-16	Enable/disable wire breakage	rw		Communication not established
-17	Range selection	rw		Communication not established
-18	Filtering method	rw		Communication not established
-19	filtering parameter	rw		Communication not established
-1B	Calibration enable/disable	rw		Communication not established
-1C	Calibration 1 Analog Quantity	rw		Communication not established
—1E	Calibration 1 Digital Quantity	rw		Communication not established
-22	Calibration 2 Analog Quantity	rw		Communication not established
-24	Calibration 2 Digital Quantity	rw		Communication not established
-28	Enable/disable unit display	rw		Communication not established
-29	Unit display conversion limit	rw		Communication not established
-2D	Unit Display Conversion Lowe	rw		Communication not established
-31	Enable/disable upper and low	rw		Communication not established
-32	Upper limit overflow analog	rw		Communication not established
-34	Upper limit overflow output	rw		Communication not established
-38	Lower limit overflow analog	rw		Communication not established
—3A	Lower limit overflow output	rw		Communication not established

Cattable managestans	Enable/disable (in disable mode, subsequent software functions for the		
Settable parameters	corresponding channel cannot be set)		
Default parameters	Enable		
Note	The conversion time for each channel is 60us, and the total time is equal to the		
	on/off conversion speed multiplied by the number of enabled channels. If this		
	channel is not used, it can be set to "disable" to reduce the total conversion time of		
	the module		

- Wire breakage detection
- Detect abnormal disconnection of AD input channel and configure alarm logs. If there is no current flowing through the module or the current flowing is too low (the measurement range is 4-20 mA or 1-5V), the corresponding alarm log will be triggered, which can activate both circuit breaker detection and underflow simultaneously.
- Can set parameters: enable or disable (default is disabled).

This function is only supported when the "measurement range" is set to " $4mA\sim20mA$ " and " $1V\sim5V$ ".



■ Sampling type/range

You can choose different types and ranges of sampling analog signals.

Advanced or	otions			
Index:Sub	Name	Flag	Value	Communication error message
#x8022:00	Channal 0	rw	>18<	
-15	Channel enable/disable	rw		Communication not establishe
-16	Enable/disable wire breakage detection	rw		Communication not establishe
-17	Range selection	rw		Communication not establishe
-18	Filtering method	rw		Communication not establishe
-19	filtering parameter	rw		Communication not established
-1B	Calibration enable/disable	rw		Communication not established
-1C	Calibration 1 Analog Quantity	rw		Communication not established
-1E	Calibration 1 Digital Quantity	rw		Communication not established
-22	Calibration 2 Analog Quantity	rw		Communication not established
-24	Calibration 2 Digital Quantity	rw		Communication not established
-28	Enable/disable unit display conversion	rw		Communication not established
-29	Unit display conversion limit	rw		Communication not established
-2D	Unit Display Conversion Lower Limit	rw		Communication not established
-31	Enable/disable upper and lower limit overflow settings	rw		Communication not established
-32	Upper limit overflow analog quantity	rw		Communication not established
-34	Upper limit overflow output digital quantity	rw		Communication not established
-38	Lower limit overflow analog quantity	rw		Communication not establishe
∟з _А	Lower limit overflow output digital quantity	rw		Communication not establishe

Cattable nevernators	Configure the corresponding index objects in COE-Online, startup					
Settable parameters	parameters, or SDO read and write instructions: voltage, current					
Default parameters	0V~10V					
Valta as massimoment non as	0V~5V, 0V~10V, -5V~5V, -10V~10V, 1V~5V					
Voltage measurement range	Default: 0V~10V					
Current measuring range	0mA~20mA, 4mA~20mA, -20mA~20mA					

■ Channel filtering parameters

• First order filtering

The first-order low-pass filtering method uses the weighting of the current sampling value and the output value of the previous filtering to obtain the effective filtering value. The filtering coefficient is set by the user to $0\sim254$. The smaller the value, the more stable the data will be, but it may cause data lag; Therefore, when set to 1, the filtering effect is strongest and the data is most stable. When set to 254, the filtering effect is weakest. The default is 0 (not filtered).

• Average filtering

Time average	Functional actions	Perform A/D conversion according to the set time, and average the total value after removing the maximum and minimum values. The average processed value is stored in the corresponding output buffer memory. The number of processing times within the set time varies depending on the number of channels allowed for A/D conversion.
	Set range	$2\sim$ 100ms (Default value 2)
Frequency average	Functional actions	Perform A/D conversion according to the set number of times, and average the total value after removing the maximum and minimum values. The average processed value is stored in the corresponding channel variable. The time it takes for the average of the number of times to be stored in the corresponding channel variable varies depending on the number of channels allowed for A/D conversion.
	Set range	$4\sim$ 500 (Default value 4)

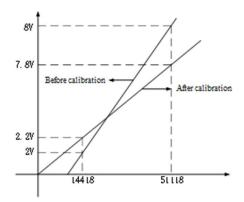
		After averaging the specified number of digital output values obtained in each
Move	Functional	sampling cycle, store them in the corresponding output register/variable. Due to
average	actions	moving average processing in each sampling process, the latest digital output
times		values can be obtained.
	Set range	2~500 (Default value 2)

Settable parameters

- Filtering mode (configuring corresponding index objects in COE-Online, startup parameters, or SDO read and write instructions): "first order filtering", "time average filtering", "frequency average filtering", and "moving average filtering" (default: first order filtering).
- ◆ Filter parameters (corresponding index objects configured in COE-Online, startup parameters, or SDO read and write instructions): in the "first-order filtering" mode, you can set: 0~254 (default value: 0), in the "time average filtering" mode, you can set: 2ms~100ms(default value: 2), in the "average filtering times" mode, it can be set to 4~500 (default value: 4), in the "moving average filtering" mode, it can be set to 2~500 (default value: 2).

Advanced opt	tions			
Index:SubI	Name	Flag	Value	Communication error message
#x8021:00	Module	rw	>1<	
#x8022:00	Channal 0	rw	>18<	
-15	Channel enable/disable	rw		Communication not established
-16	Enable/disable wire breakage detection	rw		Communication not established
-17	Range selection	rw		Communication not established
-18	Filtering method	rw		Communication not established
-19	filtering parameter	rw		Communication not established
—1B	Calibration enable/disable	rw		Communication not established
-1C	Calibration 1 Analog Quantity	rw		Communication not established
—1E	Calibration 1 Digital Quantity	rw		Communication not established
-22	Calibration 2 Analog Quantity	rw		Communication not established

■ Calibration function



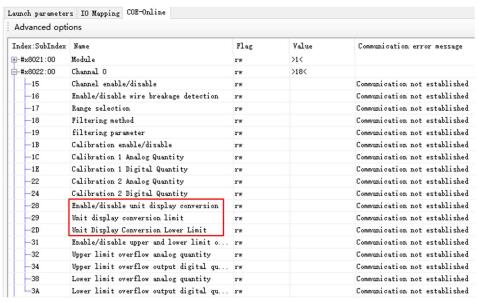
Due to the possibility of drift between the digital signals obtained from AD acquisition and conversion and the analog signals received after the product has been used for a period of time at the factory, customers can calibrate by setting the AD calibration function, immediately reflect to the scaling value (numerical operation value), you can easily complete the calibration during system startup on your own.

Index:SubIndex Name H		Flag	Value	Communication error messag	
#-#x8021:00 Module		rw	>1<		
-#x8022:00	Channal 0	rw	>18<		
-15	Channel enable/disable	rw		Communication not establish	
-16	Enable/disable wire breakage detection	rw		Communication not establis	
-17	Range selection	rw		Communication not establis	
-18	Filtering method	rw		Communication not establis	
-19	filtering parameter	rw		Communication not establis	
-1B	Calibration enable/disable	rw		Communication not establis	
-1C	Calibration 1 Analog Quantity	rw		Communication not establis	
-1E	Calibration 1 Digital Quantity	rw		Communication not establis	
-22	Calibration 2 Analog Quantity	rw		Communication not establis	
-24	Calibration 2 Digital Quantity	rw		Communication not establis	
-28	Enable/disable unit display conversion	rw		Communication not establis	
-29	Unit display conversion limit	rw		Communication not establis	
-2D	Unit Display Conversion Lower Limit	rw		Communication not establis	
-31	Enable/disable upper and lower limit o	rw		Communication not establis	
-32	Upper limit overflow analog quantity	rw		Communication not establis	
-34	Upper limit overflow output digital qu	rw		Communication not establis	
-38	Lower limit overflow analog quantity	rw		Communication not establis	
∟3A	Lower limit overflow output digital qu	rw		Communication not establis	

Unit display conversion

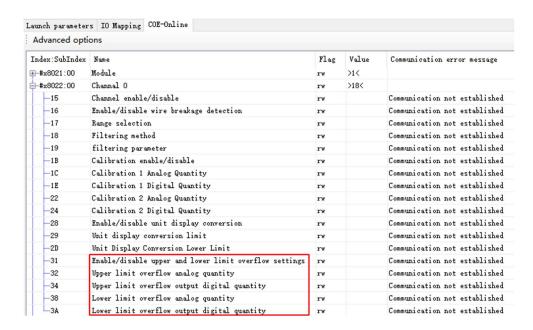
This function can directly display the output analog data as the actual output unit required by the customer.

Due to the fact that customers use analog expansion module DA to output analog signals that correspond to the outputs of some instruments or sensors. For example, controlling the frequency output range of a frequency converter to be 0-50Hz, and controlling the output frequency of the frequency converter to control the analog signal to be 4-20mA, the existing DA module will output 4-20mA analog signal to the analog acquisition terminal of the frequency converter. Customers need to convert the digital signal from 0 to 65535 to 0 to 50Hz for the actual output frequency of the frequency converter. It is possible to automatically convert the analog output of module DA into the actual output frequency value of the frequency converter by setting the conversion value range.



■ Up and down overflow settings

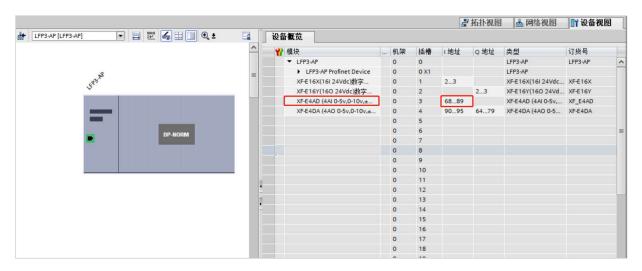
When the AD channel sampling is greater than the Upper limit/Lower limit set value, an alarm log is triggered and the set value is output.



5.2.7 Usage of XF-E4AD and LFP3-AP

5.2.7.1 Process data mapping

In the device view, the mapping address of module process data can be viewed, and the case mapping address is IB68-IB89.



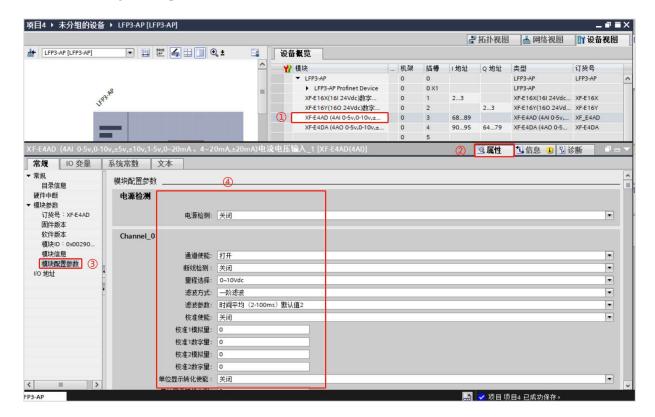
Name	Туре	Explanation
XF_E4AD	Stuct	4-channel input module
ID68(IB68~IB71)	DINT	Channel 0 input value
ID72(IB72~IB75)	DINT	Channel 1 input value
ID76(IB76~IB79)	DINT	Channel 2 input value
ID80(IB80~IB83)	DINT	Channel 3 input value
ID84(IB84~IB85)	WORD	Module level error codes
ID86(IB86~IB89)	DWORD	Channel level error code

■ Error code parameters

Module level error codes (ErrCode_module)			
Bit position Meaning Error			
0	The 24V input power supply of the module is abnormal	Important	
2	2 Internal module error occurred and cannot be fixed by the user layer Import		
3	Version mismatch	Important	
4	ADC/DAC read/write failure	Important	

	Channel level error code (ErrCode_CH)		
Bit position	Meaning Error		
0	Channel 0 upper limit overflow Ger		
1	Channel 0 lower limit overflow	General	
2	Channel 0 disconnected	Important	
3	Reserve	-	
4	Channel 1 upper limit overflow	General	
5	Channel 1 lower limit overflow General		
6	Channel 1 disconnected Impor		
7	Reserve -		
8	Channel 2 upper limit overflow Gener		
9	9 Channel 2 lower limit overflow Gene		
10 Channel 2 disconnected Impe		Important	
11 Reserve -		-	
12	12 Channel 3 upper limit overflow Gener		
13	13 Channel 3 lower limit overflow Genera		
14	14 Channel 3 disconnected Importa		

5.2.7.2 Module configuration parameters



- Module power supply detection
- Check if the external 24V power supply of the module is normal:
- Normal: The module is running normally.
- Exception: The module channel cannot be used but can be configured, configured, and scanned normally.
- Parameters can be set: enable or disable (default is disabled).
- Channel enable/disable

Enable or disable AD sampling channels to save module sampling time.

Cattable managestana	Enable/disable (in disable mode, subsequent software functions for the				
Settable parameters	corresponding channel cannot be set)				
Default parameters	Enable				
	The conversion time for each channel is 60us, total time=on/off conversion speed *				
Note	number of enabled channels, if this channel is not used, it can be set to "disable" to				
	reduce the total conversion time of the module				

- Wire breakage detection
- Detect abnormal disconnection of AD input channel and configure alarm logs. If there is no current flowing through the module or the current flowing is too low (the measurement range is 4-20 mA or 1-5V), the corresponding alarm log will be triggered, which can activate both circuit breaker detection and underflow simultaneously.
- Parameters can be set: enable or disable (default is disabled).



This function is only supported when the "measurement range" is set to " $4mA\sim20mA$ " and " $1V\sim5V$ ".

■ Sampling type/range

Can choose different types and ranges of sampling analog signals.

Settable parameters	The following table pulling method reflects the adjustable parameters: voltage,
Settable parameters	current
Default parameters	0V~10V
77.1	0V~5V, 0V~10V, -5V~5V, -10V~10V, 1V~5V
Voltage measurement range	Default: 0V~10V
Current measuring range	0mA~20mA, 4mA~20mA, -20mA~20mA

■ Channel filtering parameters

First order filtering

The first-order low-pass filtering method uses the weighting of the current sampling value and the output value of the previous filtering to obtain the effective filtering value. The filtering coefficient is set by the user to $0\sim254$. The smaller the value, the more stable the data will be, but it may cause data lag. Therefore, when set to 1, the filtering effect is strongest and the data is most stable. When set to 254, the filtering effect is weakest. The default is 0 (not filtered).

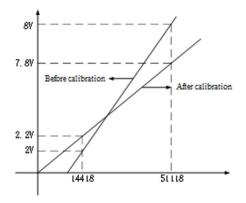
• Average filter

Time average	Functional actions	Perform A/D conversion according to the set time, and average the total value after removing the maximum and minimum values. The average processed value is stored in the corresponding output buffer memory. The number of processing times within the set time varies depending on the number of channels allowed for A/D conversion.
	Set range	$2\sim$ 100ms (Default value 2)
Frequency average	Functional actions	Perform A/D conversion according to the set number of times, and average the total value after removing the maximum and minimum values. The average processed value is stored in the corresponding channel variable. The time it takes for the average of the number of times to be stored in the corresponding channel variable varies depending on the number of channels allowed for A/D conversion.
	Set range	$4\sim$ 500 (Default value 4)
Move average times	Functional actions	After averaging the specified number of digital output values obtained in each sampling cycle, store them in the corresponding output register/variable. Due to moving average processing in each sampling process, the latest digital output values can be obtained.
	Set range	$2\sim$ 500 (Default value 2)

Settable parameters

- Filter mode (selected from dropdown menu): " first order filtering", "time average filtering", "frequency average filtering", and "moving average filtering" (default: first order filtering).
- Filter parameters (selected using input box): in the "first-order filtering" mode, it can be set to 0~254 (default value: 0), in the "Time Average Filtering" mode, it can be set to 2ms~100ms (default value: 2), in the "average filtering" mode, you can set: 4~500 (default value: 4), in the "moving average filtering" mode, it can be set to 2~500 (default value: 2).

Calibration function



Due to the possibility of drift between the digital signals obtained from AD acquisition and conversion and the analog signals received after the product has been used for a period of time at the factory, customers can calibrate by setting the AD calibration function, immediately reflect to the scaling value (numerical operation value), you can easily complete the calibration during system startup on your own.

Unit display conversion

This function can directly display the output analog data as the actual output unit required by the customer. Due to the fact that the customer's use of analog expansion module DA outputs mostly analog signals corresponding to the outputs of some instruments or sensors. For example, controlling the frequency output range of a frequency converter to be 0~50Hz, the frequency control analog signal of the frequency converter is 4~20mA. The existing DA module will output the 4~20mA analog signal to the analog acquisition terminal of the frequency converter, and the customer needs to convert the digital signal from 0~65535 to 0~50Hz for the actual output frequency of the frequency converter. It is possible to automatically convert the analog output of module DA into the actual output frequency value of the frequency converter by setting the conversion value range.

■ Up and down overflow setting

Trigger an alarm log and output the set value when the AD channel sampling is greater than the Upper limit/Lower limit setting value.

5.3 Analog output unit XF-E4DA

5.3.1 Overview

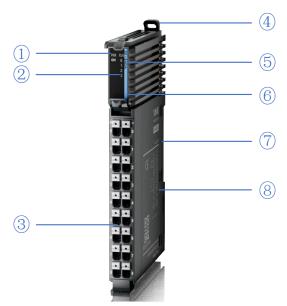
XF-E4DA series analog output expansion module, which has 4 channels of analog input, supporting current and voltage inputs, adapt to XF, XSF series CPU unit products and XF series communication coupler units.

- 4-channel analog output.
- Channel conversion speed 60us/channel.
- Maximum error of 0.2%.
- Voltage and current input.
- Designed with a width of 12mm.
- Module version

Hardware version	Firmware version	Function
H2.0	V2.0	Basic functions for the first official production

5.3.2 Module view

1) Description of each section

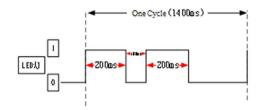


No.	Name	No.	Name
1	System LED indicator lights	2	Channel LED indicator light
3	Detachable terminal block	4	Snap
5	Model indication	6	Color identification indicating module type
7	Module hardware and firmware versions	8	Wiring diagram

2) System indicator

System indicator	Explanation		
	Extinguish	Module not powered on	
	Light	All external power supplies of the module are normal (backplane bus	
PWR (Green)		power supply&external input 24V)	
	Flash1Hz*1	Abnormal power supply in the module and inability to operate	
		normally	
	Light	The module is running normally	
	Flash1Hz*1	General errors in module logs	
RUN (Green)	Extinguish	Important errors in module logs	
	Flash10Hz*2	Module establishing communication	
	Double flashing*3	Module firmware update	

- *1: A square wave with a duty cycle of 50% and a frequency of 1Hz.
- *2: A square wave with a duty cycle of 50% and a frequency of 10Hz.
- *3: As shown in the following figure:



3) Channel indicator light

Model	Channel indicator light		
XF-E4DA	СН0~СН3	Light (Green)	Channel enabled and configured correctly
		Extinguish	Mute channel

4) Color identification

No.	Colour		Module type
1		White	Digital input
2		Grey	Digital output&digital mixing module
3		Light blue	Analog input
4		Deep blue	Analog output

5.3.3 General specification

General specification				
Project		Specifications		
On anoting tames and true	Maximum temperature	55°C		
Operating temperature	Minimum temperature	-20°C		
Transportation/Storage	Maximum temperature	70°C		
Temperature	Minimum temperature	-40°C		

General specification			
Project		Specifications	
Environmental	Upper limit	95%	
humidity (including operation/storage)	Lower limit	10%	
IP code		IP20	
Anti vibration		Compliant with IEC61131-2 Under intermittent vibration (frequency 5-9Hz, constant amplitude 3.5mm peak displacement) and (frequency 9-150Hz, constant acceleration 1.0g peak acceleration) Under continuous intermittent vibration (frequency 5-9Hz half amplitude 1.75mm displacement) and (frequency 9-150Hz constant acceleration 0.5g constant frame amplitude) Scan 10 times in X, Y, and Z directions	
Impact resistance		Complies with IEC61131-2 standard The impact strength is 15G (peak) and the duration is 11ms. It is applied to three mutually perpendicular axes, and each axis is impacted 3 times (a total of 18 impacts)	
Using environment		Non corrosive gas	
Using altitude		0-2000 m	
Overvoltage level		II: Compliant with IEC61131-2	
Pollution level		2: Compliant with IEC61131-2	
Anti interference EMC		Compliant with IEC 61131-2 IEC61000-6-4 Type B	
Related certifications		CE	

5.3.4 Technical specifications

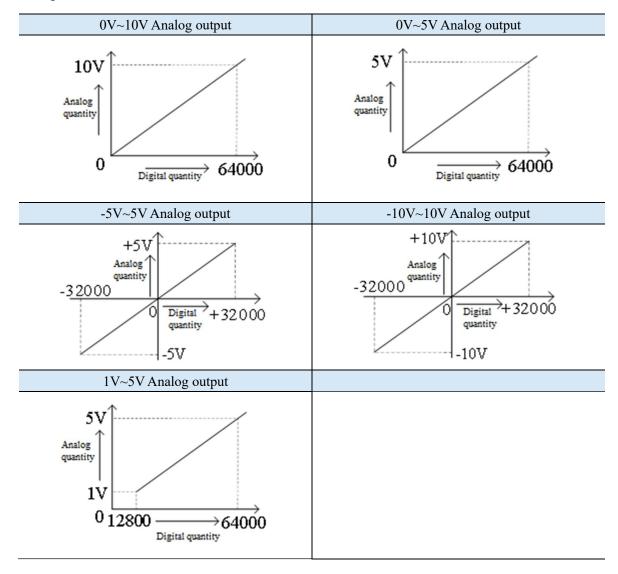
5.3.4.1 Module performance

Project		Specifications
Input channel		4
Analog input range (rated)		0V~5V (0~64000)
		0V~10V (0~64000)
	Voltage output range	-5V~5V (-32000~32000)
		-10V~10V (-32000~32000)
		1v~5v (12800~64000)
	Comment extens and	0mA~20mA (0~64000)
	Current output range	4mA~20mA (12800~64000)
Maximum	Voltage input	DC±15V
input range	Current input	-40~40mA
Conversion speed		60us/CH
Resolution ratio		1/64000 (16Bit)
Module	Rated input	DC24V±10%, 150mA
power supply	Protect	Reverse polarity protection
Error	Room temperature 25°C±5°C	±0.1% (25±5 °C)
	Full temperature end -20~55°C	±0.2%
Isolated		Channel non isolated, power isolated
Module power consumption		0.8W (backplane bus)+0.8W (external input)

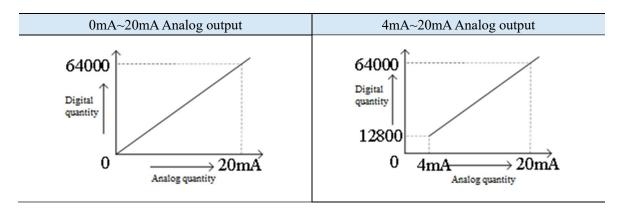
Module weight 80g

5.3.4.2 Analog-to-digital conversion diagram

■ Voltage



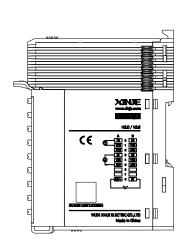
■ Current

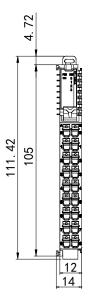


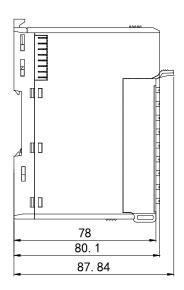
5.3.5 Terminal definition&Wiring

5.3.5.1 Appearance dimension diagram

(Unit: mm)





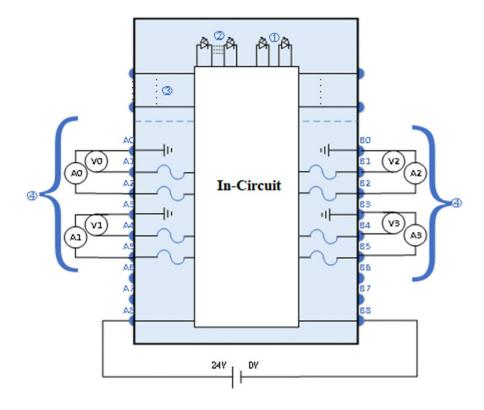


5.3.5.2 Terminal definition&Wiring

■ Terminal definition

XF-E4DA					
Meaning	A-column terminal	Terminal layout	B-column terminal	Meaning	
CH0- output ground	0		0	CH2- output ground	
CH0-DA analog voltage output terminal	1		1	CH2-DA analog voltage output terminal	
CH0-DA analog current output terminal	2	1 1	2	CH2-DA analog current output terminal	
CH1- output ground	3		3	CH3- output ground	
CH1-DA analog voltage output terminal	4	4	4	CH3-DA analog voltage output terminal	
CH1-DA analog current output terminal	5		5	CH3-DA analog current output terminal	
Empty	6		6	Empty	
Empty	7		7	Empty	
External 24V power supply for module positive	8		8	External power supply to the module 24V power supply negative	

■ External wiring

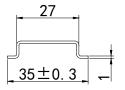


①System indicator ②Channel indicator light ③Backplane bus ④Output Channel&Wiring

5.3.5.3 Installation method

1) Installation requirements

The module is installed using DIN rails, which must comply with the IEC 60715 standard (35mm wide, 1mm thick), the size information is shown in the following figure, in millimeters.

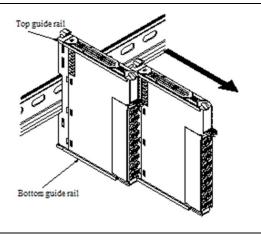




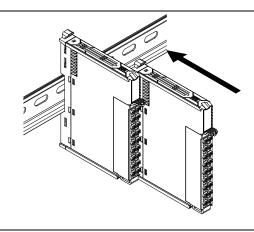
Note

When the module is installed on a non recommended DIN rail, the DIN rail latch may not lock properly.

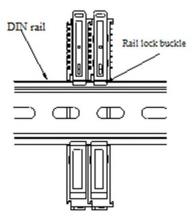
2) Installation steps



1. The assembly between IO modules is installed by sliding through the top and bottom guide rails of the modules, as shown in the left figure:

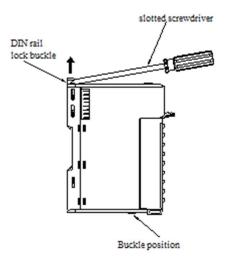


2. The module is installed on the guide rail. When installing, align the module with the DIN guide rail and press the module in the direction indicated by the arrow. After installation, there is a clear sound of engagement, as shown in the left figure:

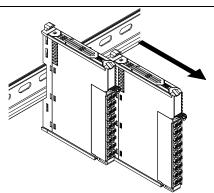


Explanation: After the module installation is completed, the locking buckle will automatically move downwards for locking, if the latch does not move downwards, press down on the top of the latch, ensure proper installation.

3) Disassembly steps



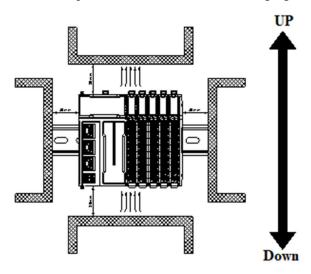
1. Use a flat screwdriver or similar tool to pry the rail lock upwards, as shown in the left figure:



2. Pull the module straight forward at the buckle position (raised part), and then press down on the top of the latch, as shown in the left figure:

5.3.5.4 Installation environment

This product can be installed in four positions (i.e. installation direction): horizontal, vertical, top of cabinet, and bottom of cabinet. It is recommended to install in the horizontal direction, and the heat dissipation design is through natural convection. To ensure normal ventilation and heat dissipation and reserve sufficient wiring space, the minimum gap must be left around this product, as shown in the following figure:



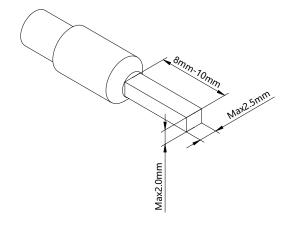
If there are high-temperature heat source equipment (heaters, transformers, large resistors, etc.) around this product, leave at least 100mm gap between the equipment and the high-temperature heat source.

5.3.5.5 Equipment wiring

When wiring the module, its terminal must meet the following requirements:

Adaptor diameter			
National standard/mm ²	American standard/AWG		
0.3	22		
0.5	20		
0.75	18		
1.0	18		
1.5	16		

If using other tube type wire ears, please crimp them to the twisted wire. The shape and size requirements are shown in the following figure:



5.3.6 Usage of XF-E4DA and LFC3-AP

5.3.6.1 Process data mapping (PDO)

Name	Type	Explanation
XF_E4DA	Stuct	4-channel output module
СН0	DINT	Channel 0 output value
——— CH1	DINT	Channel 1 output value
——— CH2	DINT	Channel 2 output value
CH3	DINT	Channel 3 output value
ErrCode_module	WORD	Module level error codes
ErrCode_CH	DWORD	Channel level error code

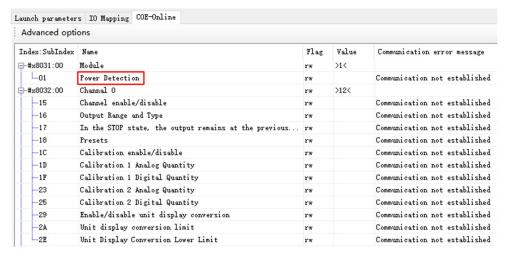
■ Error code parameters

Module level error codes (ErrCode_module)			
Bit position	Meaning	Error level	
0	The 24V input power supply of the module is abnormal	Important	
2	Internal module error occurred and cannot be fixed by the user layer	Important	
3	Version mismatch	Important	
4	ADC/DAC read/write failure	Important	

5.3.6.2 Module configuration parameters (SDO)

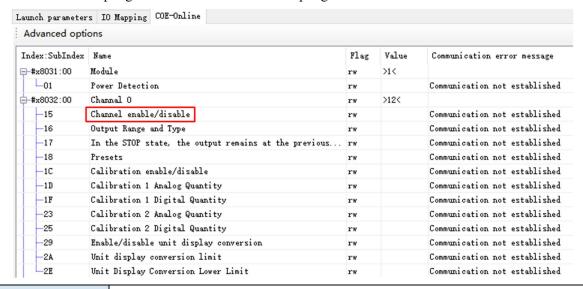
Parameter	Туре	Channel	No	te
Power detection	Enumeration of BYTE		0: Close	1: Open
Channel enable/disable	BYTE		0: Close	1: Open
Output type and range	ВҮТЕ		0: 0~10V (Default) 1: 0~5V 2: -10~10V 3: -5~5V	4: 1~5V 5: 0~20mA 6: 4~20mA
In the STOP state, the output remains at the previous value/preset value	Enumeration of BYTE		0: Keep the previous value	1: Set value
Presets	DINT	1	-32000~64000	
Calibration enable/disable	Enumeration of BYTE		0: Close	1: Open
Calibration 1 analog quantity	INT		Voltage output 0~10V:	
Calibration 1 digital quantity	DINT		Analog range: 0-1000 Digital range: 0-6400	
Calibration 2 Analog Quantity	INT		0~5V: Analog range: 0-5000)mV
Calibration 2 Digital Quantity	DINT	Channel 0-4	Digital range: 0-6400 -10~10V: Analog range: -10000 Digital range: -32000 -5~5V: Analog range: -5000- Digital range: -32000 1~5V: Analog range: 0mV-5 Digital range: 12800- Current output 0~20mA: Analog range: 0-2000 Digital range: 0-6400 4~20mA: Analog range: 0-2000 Digital range: 12800-	0 0-10000mV -32000 5000mV -32000 5000mV 64000
Enable/disable unit display conversion	Enumeration of BYTE		0: Close	1: Open
Unit display conversion limit Unit Display Conversion Lower Limit	DINT		Range: -100000000~ And after enabling ur (Upper Lower Limit)	it conversion,

- Module power supply detection
- Check if the external 24V power supply of the module is normal:
- Normal: The module is running normally.
- Exception: The module channel cannot be used but can be configured, configured, and scanned normally.
- Can set parameters: enable or disable (default is disabled).



■ Channel enable/disable

Enable or disable AD sampling channels to save module sampling time.



Settable parameters	Enable/disable (in disable mode, subsequent software functions for the corresponding channel cannot be set)				
Default parameters Enable					
	The conversion time for each channel is 60us, Total time=On/Off conversion speed *				
Note	Number of enabled channels, if this channel is not used, it can be set to "disable" to				
	reduce the total conversion time of the module				

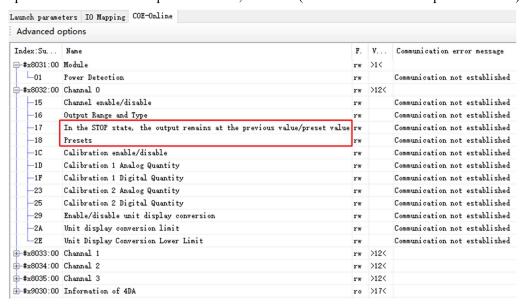
■ Output type/range

Can choose different output types and output ranges.

	ons			
Index:SubIndex	Name	Flag	Value	Communication error message
#x8031:00	Module	rw	>1<	
L ₀₁	Power Detection	rw		Communication not established
-#x8032:00	Channal 0	rw	>12<	
-15	Channel enable/disable	rw		Communication not established
-16	Output Range and Type	rw		Communication not established
-17	In the STOP state, the output remains at the previous	rw		Communication not established
-18	Presets	rw		Communication not established
-1C	Calibration enable/disable	rw		Communication not established
—1D	Calibration 1 Analog Quantity	rw		Communication not established
—1F	Calibration 1 Digital Quantity	rw		Communication not established
-23	Calibration 2 Analog Quantity	rw		Communication not established
-25	Calibration 2 Digital Quantity	rw		Communication not established
-29	Enable/disable unit display conversion	rw		Communication not established
-2A	Unit display conversion limit	rw		Communication not established
_2E	Unit Display Conversion Lower Limit	rw		Communication not established

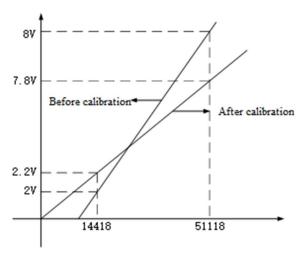
Settable parameters	Configure the corresponding index objects in COE-Online, startup parameters, or
Settable parameters	SDO read and write instructions: voltage, current
Default parameters	0V~10V
Voltage measurement	0V~5V, 0V~10V, -5V~5V, -10V~10V, 1V~5V
range	Default: 0V~10V
Current measuring range	0mA~20mA, 4mA~20mA

- STOP output
- When the CPU unit is in STOP mode or abnormal error mode, the corresponding DA channel of the module outputs according to the set parameters.
- Can set parameters: maintain the previous value, set value (default to maintain the previous value).



Calibration function

Index:Su	Name	F.	٧	Communication error message
-#x8031:00	Module	rw	>1<	
L ₀₁	Power Detection	rw		Communication not establish
-#x8032:00	Channal O	rw	>12<	
-15	Channel enable/disable	rw		Communication not establish
-16	Output Range and Type	rw		Communication not establish
-17	In the STOP state, the output remains at the previous value/preset value	rw		Communication not establish
-18	Presets	rw		Communication not establish
-1C	Calibration enable/disable	rw		Communication not establish
-1D	Calibration 1 Analog Quantity	rw		Communication not establish
-1F	Calibration 1 Digital Quantity	rw		Communication not establish
-23	Calibration 2 Analog Quantity	rw		Communication not establish
-25	Calibration 2 Digital Quantity	rw		Communication not establish
-29	Enable/disable unit display conversion	rw		Communication not establish
-2A	Unit display conversion limit	rw		Communication not establish
_2E	Unit Display Conversion Lower Limit	rw		Communication not establish



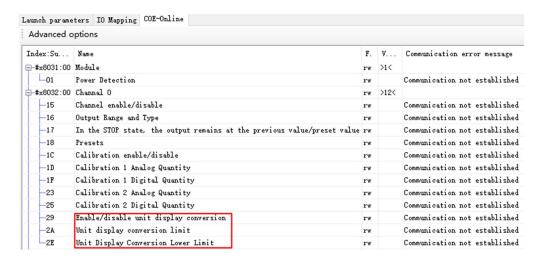
Due to the possibility of drift between the analog quantity obtained from DA output conversion and the set digital quantity after the product leaves the factory or has been used for a period of time, customers can set the DA offset calibration function, immediately reflect to the scaling value (numerical operation value), can easily complete the calibration during system startup on your own.

For example, if DA1 Analog output is set to 0-10V output, and 51118 is assigned to the output channel, the output voltage is 8V. When a value of 14418 is assigned to the output channel, the output voltage is 2V. At this point, set 8000mV in the analog setting of DA1 calibration 1, set 51118 in the DA1 calibration 1 digital quantity setting value, set 2000mV in the analog settings of DA1 calibration 2, set 14418 in the digital quantity settings of DA1 calibration 2, the calibration function can be achieved.

Unit display conversion

This function can directly display the output analog data as the actual output unit required by the customer.

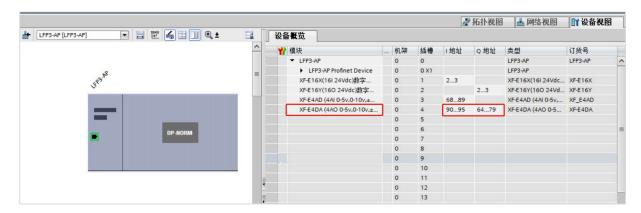
Due to the fact that the customer's use of analog expansion module DA outputs mostly analog signals corresponding to the outputs of some instruments or sensors. For example, controlling the frequency output range of a frequency converter to be 0-50Hz, and controlling the output frequency of the frequency converter to control the analog signal to be 4-20mA, the existing DA module will output a 4-20mA analog signal to the analog acquisition terminal of the frequency converter, the customer needs to convert the digital quantity from 0 to 65535 to 0 to 50Hz for the actual output frequency of the frequency converter. It is possible to automatically convert the analog output of module DA into the actual output frequency value of the frequency converter by setting the conversion value range.



5.3.7 Usage of XF-E4DA and LFP3-AP

5.3.7.1 Process data mapping

In the device view, the mapping addresses of module process data can be viewed, and the case mapping addresses are IB90-IB95 and QB64-QB79.



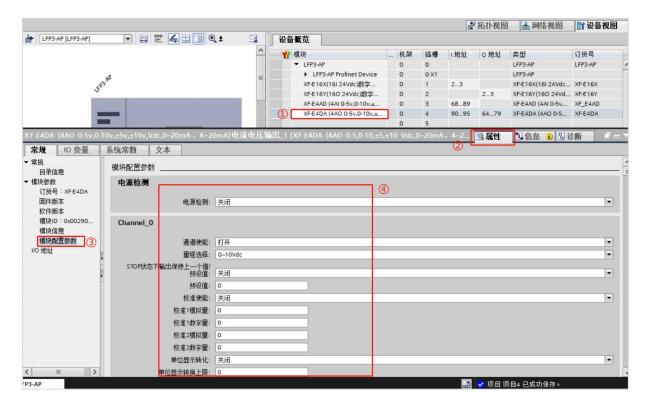
Name	Type	Explanation	
XF_E4DA	Stuct	4-channel output module	
QD64(QB64-QB67)	DINT	Channel 0 output value	
QD68(QB68-QB71)	DINT	Channel 1 output value	
QD72(QB72-QB75)	DINT	Channel 2 output value	
QD76(QB76-QB79)	DINT	Channel 3 output value	
ID90(IB90-IB91)	WORD	Module level error codes	
ID92(IB92-IB95)	DWORD	Channel level error code	

■ Error code parameters

Module level error codes (ErrCode_module)			
Bit position	Meaning	Error level	
0	The 24V input power supply of the module is abnormal	Important	
2	Internal module error occurred and cannot be fixed by the user layer	Important	

Module level error codes (ErrCode_module)			
Bit position	Meaning	Error level	
3	Version mismatch	Important	
4	ADC/DAC read/write failure	Important	

5.3.7.2 Module configuration parameters



- Module power supply detection
- Check if the external 24V power supply of the module is normal:
- Normal: The module is running normally;
- Exception: The module channel cannot be used but can be configured, configured, and scanned normally.
- Parameters can be set: enable or disable (default is disabled).
- Channel enable/disable

Enable or disable AD sampling channels to save module sampling time.

Settable parameters	Enable/disable (in disable mode, subsequent software functions for the corresponding channel cannot be set)
Default parameters	Enable
Note	The conversion time for each channel is 60us, total time=On/Off conversion speed *
	Number of enabled channels, if this channel is not used, it can be set to "disable" to
	reduce the total conversion time of the module.

■ Output type/range

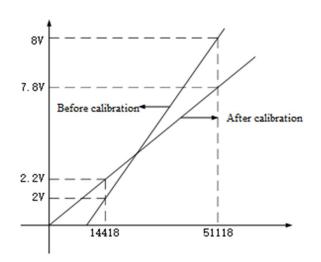
Can choose different output types and output ranges.

Settable parameters	The following table pulling method reflects the adjustable parameters: voltage, current
Default parameters	0V~10V
Voltage measurement range	0V~5V, 0V~10V, -5V~5V, -10V~10V, 1V~5V
	Default: 0V~10V
Current measuring range	0mA~20mA, 4mA~20mA

■ STOP output

- When the CPU unit is in STOP mode or abnormal error mode, the corresponding DA channel of the module outputs according to the set parameters.
- Can be set parameters: Keep the previous value, set value (default to keep the previous value).

■ Calibration function



Due to the possibility of drift between the analog quantity obtained from DA output conversion and the set digital quantity after the product leaves the factory or has been used for a period of time, customers can set the DA offset calibration function, immediately reflect to the proportional scaling value (numerical operation value), and you can easily complete the calibration at system startup on your own.

For example, setting the DA1 analog output to 0-10V output, when a value of 51118 is assigned to the output channel, the output voltage is 8V. When a value of 14418 is assigned to the output channel, the output voltage is 2V. At this point, set 8000mV in the analog setting of DA1 calibration 1, set 51118 in the DA1 calibration 1 digital quantity setting value, set 2000mV in the analog settings of DA1 calibration 2, set 14418 in the digital quantity settings of DA1 calibration 2, the calibration function can be achieved.

■ Unit display conversion

This function can directly display the output analog data as the actual output unit required by the customer.

Due to the fact that the customer's use of analog expansion module DA outputs mostly analog signals corresponding to the outputs of some instruments or sensors. For example, controlling the frequency output range of a frequency converter to be 0-50Hz, and controlling the output frequency of the frequency converter to control the analog signal to be 4-20mA, the existing DA module will output a 4-20mA analog signal to the analog acquisition terminal of the frequency converter, the customer needs to convert the digital quantity from 0 to 65535 to 0 to 50Hz for the actual output frequency of the frequency converter. It is possible to automatically convert the analog output of module DA into the actual output frequency value of the frequency converter by setting the conversion value range.





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