

XSF series PLC

User manual 【Hardware】

Data No. PF 01 20230801 1.0

Basic description

- Thank you for purchasing the XINJE XSF series programmable controller.
- This manual mainly introduces the hardware features of XSF series programmable controllers.
- Before using the product, please read this manual carefully and conduct wiring on the premise of fully understanding the contents of the manual.
- For software and programming, please refer to the relevant manuals.
- Please deliver this manual to the end user.

Notes to users

- Only operators with certain electrical knowledge can conduct wiring and other operations on the product. If there is any unknown place, please consult our technical department.
- The examples listed in the manual and other technical data are only for users' understanding and reference, and do not guarantee certain actions.
- When using this product in combination with other products, please confirm whether it conforms to relevant specifications and principles.
- When using this product, please confirm whether it meets the requirements and is safe.
- Please set up backup and safety functions by yourself to avoid possible machine failure or loss caused by the failure of this product.

Statement of responsibility

- Although the contents of the manual have been carefully checked, errors are inevitable, and we cannot guarantee complete consistency.
- We will often check the contents of the manual and make corrections in subsequent versions. We welcome
 your valuable comments.
- The contents described in the manual are subject to change without notice.

Contact us

If you have any questions about the use of this product, please contact the agent and office who purchased the product, or you can directly contact the company.

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September 2023

Safety precautions

Before using this product, please read this part carefully and operate after fully understanding the use, safety, precautions, etc. of the product. Please correctly conduct product wiring under the premise of paying great attention to safety.

The problems that may arise during the use of the product are basically included in the safety precautions, which are indicated in two levels of attention and danger. For other unfinished matters, please follow the basic electrical operation procedures.



Attension

When used incorrectly, it may cause danger, moderate injury or minor injury, and property damage.



Danger

When it is used incorrectly, it may cause danger, cause personal injury or serious injury, and may cause serious property damage.

Confirmation upon receiving the product



Attention

Do not install damaged controllers, controllers with missing parts, or controllers with unqualified models. Danger of injury.

Product system design



Danger

Please design a safety circuit outside the controller to ensure that the whole system can operate safely when the controller operates abnormally.

There is a risk of misoperation and failure.



Attention

Do not tie the control wiring and power wiring together. In principle, they should be separated by 10cm. It may cause malfunction and product damage.

Product installation



Danger

Before installing the controller, be sure to disconnect all external power supplies.

Danger of electric shock.



Attention

1. Please install and use this product under the environmental conditions specified in the general specifications of the manual.

Do not use in damp, high temperature, places with dust, smoke, conductive dust, corrosive gas, flammable gas, vibration and impact.

It may cause electric shock, fire, misoperation, product damage, etc.

2. Do not directly touch the conductive part of the product.

It may cause malfunction and fault.

3. Please use DIN46277 guide rail, M3 screw or Xinje XG-EB to fix the product and install it on a flat surface.

Incorrect installation may cause malfunction and product damage.

4. When processing the screw hole, please do not let the cutting powder and wire debris fall into the product cover.

It may cause malfunction and fault.

5. when connecting the expansion module with the expansion cable, please confirm that the connection is tight and the contact is good.

It may lead to poor communication and misoperation.

6. when connecting peripheral devices, expansion devices, batteries and other devices, be sure to cut off power for operation.

It may cause malfunction and fault.

Product wiring



Danger

1. Before wiring the controller, be sure to disconnect all external power supplies.

Danger of electric shock.

2. Please correctly connect the AC/DC power supply to the dedicated power terminal of the controller.

If the power supply is connected incorrectly, the controller may be burned.

3. Before the controller is powered on and operated, please cover the cover plate on the terminal block.

Danger of electric shock.



Attention

1. Do not use external 24V power supply to connect to 24V and 0V terminals of the controller or expansion module.

It may cause damage to the product.

2. Please use 2mm² wire to carry out the third kind of grounding for the grounding terminal of the controller and expansion equipment, and do not share the grounding with the strong current system.

It may cause failure, product damage, etc.

3. Do not make external wiring to the empty terminal.

It may cause malfunction and product damage.

4. When processing the screw hole, please do not let the cutting powder and wire debris fall into the product

cover.

May cause malfunction, fault, etc.

5. When using wires to connect terminals, be sure to tighten them, and do not make conductive parts contact other wires or terminals.

It may cause malfunction and product damage.

• Operation and maintenance of products



Danger

1. Do not touch the terminal after the controller is powered on.

Danger of electric shock.

2. Do not connect or remove the terminal with electricity.

Danger of electric shock.

3. Please stop the program in the controller before changing it.

It may cause malfunction.



Attention

1. Do not disassemble or assemble this product without authorization.

It may cause damage to the product.

2. Please plug and unplug the connecting cable in case of power failure.

It may cause cable damage and malfunction.

3. Do not make external wiring to the empty terminal.

It may cause malfunction and product damage.

4. Please cut off the power before removing the expansion device, peripheral device and battery.

It may cause malfunction, fault, etc.

5. When the product is discarded, please treat it as industrial waste.

Preface

Sincerely thank you for purchasing the Xinjie Programmable Controller XSF series products.

This manual is convenient for users to understand and use the necessary precautions, specifications, functions, and other contents of XSF-CPU units.

Before use, one should thoroughly read this manual and related manuals, and correctly use this product based on a thorough understanding of the functions/performance of the XSF series programmable controller.

Catalog

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1. Document Guide

1-1. Related manual

(1) CPU unit

Manual name	Main content
XSF series hardware user manual	It mainly records the hardware specifications and hardware maintenance information of XSF series CPU units.
XS series PLCopen controller instruction manual (XS Studio)	It mainly records XS series instruction section.

(2) I/O unit

Manual name Main content	
VF C	It mainly records the product specifications and maintenance
XF Series expansion module user manual	information of the XF series IO unit.

1-2. Reading method of the manual

The page composition and symbols of this manual are described below.

The following is a description of the manual reading method, which is different from the actual recorded content.

2. Terminology

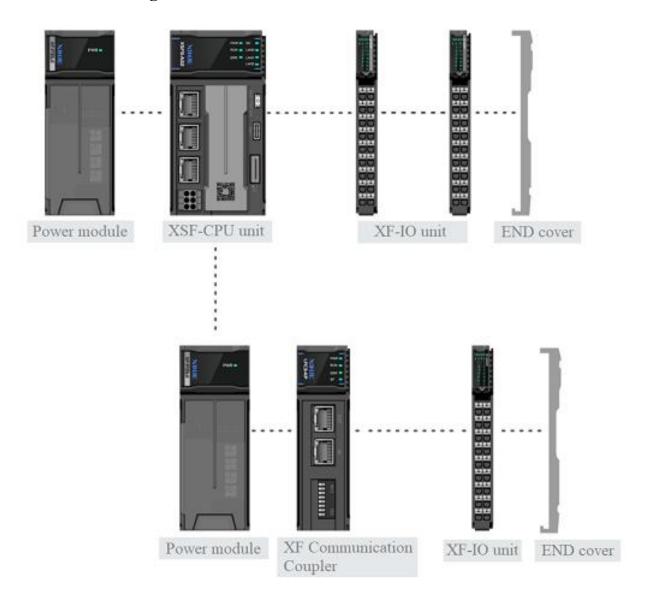
In this manual, unless otherwise specified, the following terms will be used for explanation.

Terminology	Instructions	
CPU unit	General term for XF/XSF series CPU units	
Power module unit	ale unit General term for XF series power modules	
ID20	Protection level according to DIN 40050: protection against finger contact and intrusion	
IP20	of particles with a diameter greater than 12mm	
	The backplane bus is a serial data bus used by various modules to communicate with	
Backplane bus	each other. The backplane bus is also used to provide some necessary power supply for	
	each module. Each module is connected through a bus connector.	

3. Product System Configuration

In this chapter, the overall configuration, precautions during configuration, and peripheral device related content are explained.

3-1. Overall configuration



3-2. Major event

- Different CPU units are used, and the corresponding expandable IO units are also different.
- The I/O units that can be powered through the backplane bus vary according to the power supply units used.

The types and quantities of CPU units, power units, and expandable IO units are as follows:

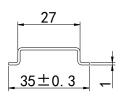
Power unit model	CPU unit model	Scalable basic I/O unit
VE D25 E	XSF5-A32	10
XF-P35-E	XSF5-A64	18

4. Installation&Wiring

4-1. CPU installation method

(1) Installation requirements

The host is installed using DIN rails, which must comply with the IEC 60715 standard (35mm wide and 1mm thick). The size information is shown in the following figure, in millimeters (mm).

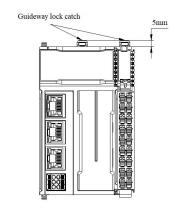


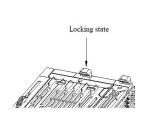


Attention

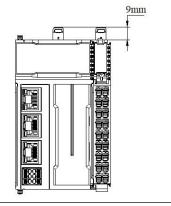
When installing this product on non recommended DIN rails (especially when the thickness of the DIN rail is not 1.0mm), it will cause the DIN rail latch to fail, prevent the product from being installed in place, and thus prevent the product from working properly.

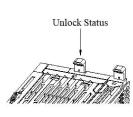
(2) Installation procedure





During installation, align the main engine with the DIN rail and press the module in the direction indicated by the arrow. After the module is installed in place, the clamping sound is obvious, as shown on the left:





Confirm that the DIN rail lock of the main engine is locked, and the lock and unlock state of the rail lock are shown on the left:



If the DIN guideway lock catch is below, it is locked.

If the DIN guideway lock catch is on top, it is unlocked. When in the unlocked position, press down on the DIN guideway lock catch to make it locked.

4-2. Network cable installation method

(1) Network cable requirements

To improve the reliability of device communication, the Ethernet cable must be shielded twisted pair cables with iron injection molding wires.

- Connection: Hold the RJ45 connector with the cable and insert it into the Ethernet port (RJ45 port) until the sound clicks
- Detach: Press and hold the crystal head and tail mechanism to pull out the connector horizontally from the product.

(2) Signal pin assignment

Connector View	Pin	Signal
	1	TD+
	2	TD-
	3	RD+
	4	-
	5	-
	6	RD-
	7	-
	8	-

4-3.485&CAN

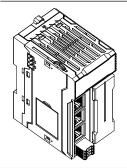
When the XSF5-A32 and XSF5-A64 CPU units leave the factory, the 485&CAN terminals have been inserted. The following table lists the signal names and pin assignment instructions for 485&CAN terminals:

Connector View	Connector View Number Signal name		Instructions	
	1	CAN+	CAN+ wiring terminal of CAN	
	2	CAN-	CAN- wiring terminal of CAN	
	3	GND	Ground terminal of CAN	
CAN B	4	A	A-phase wiring terminal of 485	
	5	В	B-phase wiring terminal of 485	
	6	GND	Ground terminal of GND	
	-	-	-	

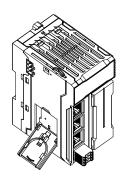
4-4. Battery maintenance and replacement

- (1) The function of batteries
- XSF5-A32 and XSF5-A64 are delivered without batteries by default. If you need to add batteries later, use standard CR2032 batteries.
- The battery is only used to maintain RTC clock data in the event of a power outage.

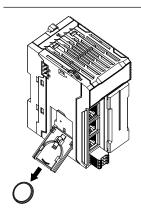
(2) Battery replacement procedure



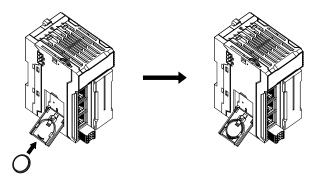
- 1. Please complete the following steps before replacing:
- ① Record RTC data.
- $\ \, \textcircled{2}\ \,$ Set the power supply of the CPU module to ON for 10 minutes or more.



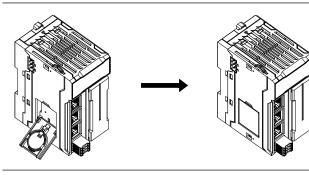
2. Open the side cover of the CPU unit (battery box)



3. Remove the currently in use battery from the battery box (default to no battery at the factory, this step can be omitted).



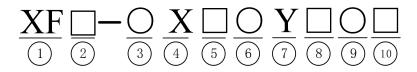
4. Insert a new battery.



5. Close the cover plate.

5. Naming convention

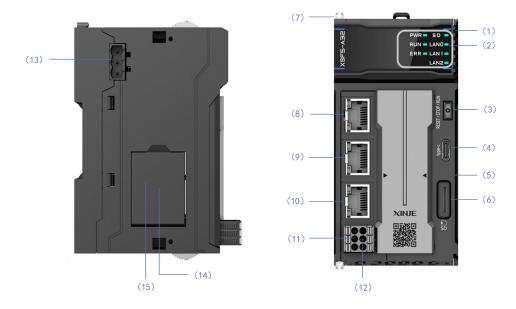
CPU unit



	G : N	XF:	XF series	
1	Series Name	XSF:	XSF series	
		1:	Basic type	
		2:	Ethernet type	
2	Serial number	3:	Entry level motion control type	
	5: Motion control type		Motion control type	
		7:	Advanced motion control type	
		4:	4 channels	
(3)	T.,	8:	8 channels	
(3)	Input channel	16:	16 channels	
		32:	32 channels	
4	Type	X:	Digital input	
		4:	4 channels	
(E)	Output alsome al	8:	8 channels	
(3)	⑤ Output channel	Output channel 16: 16 channels		16 channels
		32:	32 channels	
(6)	Output a sint true	Empty:	Digital output NPN type	
	Output point type	P:	Digital output PNP type	
7	Type	Y:	Digital output	
		T:	Digital output transistor type	
8	8 Output point type	R:	Digital output relay type	
	Output point type	RT:	The first two channels are transistor outputs, and the others are	
		KI.	relay types.	
	High anged mulas	Empty:	2 channels	
	High speed pulse output channel (only	4:	4 channels	
9	effective when output	6:	6 channels	
	type is T)	8:	8 channels	
		10:	10 channels	
		A8:	8 axes	
	Axis capacity (only	A16:	16 axes	
10	applicable to series 3,	A32:	32 axes	
	5, and 7) A64: 64 axes		64 axes	
		A128:	128 axes	

6. Names of each part

XSF5-A32 & XSF5-A64



Number	Name	Purpose		
(1)	Extended Connection	Used for connecting to XF-IO units.		
		DW/D (cmaca)	On: With power input	
		PWR(green)	Off: No power input	
		DIIN(ome om)	On: User program running	
		RUN(green)	Off: User program stopping	
		ERR(red)	On: System critical error	
		EKK(Ied)	Off: System normal	
			On: SD card pending access status	
(2)	Pilot lamp		Flashing 1Hz: Accessing SD card	
		SD(graan)	Flashing 10Hz: Software access failure,	
		SD(green)	unsupported SD card format.	
			Off: SD card not detected, inserted or hardware	
			damaged.	
		LAN0	Blinking: Change the IP address of the	
		LAN1		
		LAN2	corresponding network interface.	
(3)	System dialing	Used to contro	ol CPU unit to allow stopping and IP recovery.	
(4)	USB interface	Used to connect to the upper computer.		
(5)	Slide cover	It can move left and right to protect the system dialing, TF card		
(5)	Slide cover	slot, and USB interface.		
(6)	TF card interface	TF card can b	e used to import and export data (supported in Q3 of	
(6)	1 r card interface	2023).		
(7)	Sliding latch	Used to fix the XF power module and CPU unit.		
(8)	ENET0	Used to connect to the upper computer or other network nodes.		
(9)	ENET1 ECAT1	Used to connect network nodes or ECAT nodes.		
(10)	ECAT0	Used to connect the ECAT node		

(11)	CAN	1 channel isolated CAN port (reserved)	
(12)	485	1 channel isolated 485 port	
(13)	Power module connection port	Connect and use with the XF power module.	
(14) Battery holder		The effective time of RTC can be increased by adding standard	
		CR2032 batteries.	
(15)	Auxiliary dialing	Control the load resistance of CAN and 485.	

7. CPU unit specifications

7-1. General specifications

General specifications				
Project		Content		
On a wating tamp a watuwa	Max temperature	55°C		
Operating temperature	Min temperature	-20°C		
Transportation/storage	Max temperature	70°C		
temperature	Min temperature	-40°C		
Environmental humidity	Upper limit	95%		
(including operation/storage)	lower limit	10%		
Protection gr	ade	IP20		
		Accord with IEC61131-2		
		Under intermittent vibration (frequency 5-9Hz, constant		
		amplitude 3.5mm peak displacement) and (frequency		
Anti vibratio	~ 	9-150Hz, constant acceleration 1.0g peak acceleration)		
And violado	J11	Under continuous vibration (frequency 5-9Hz, half amplitude		
		1.75mm displacement) and (frequency 9-150Hz, constant		
		acceleration 0.5g, constant frame amplitude)		
		Scan 10 times in X, Y, and Z directions		
		Accord with IEC61131-2		
Impact resistance		Impact strength of 15G (peak) with a duration of 11ms is		
impact resista	ince	applied to three mutually perpendicular axes, with 3 impacts		
		per axis (a total of 18 impacts)		
Use environn	nent	Non corrosive gas		
Use altitude		0-2000 meters		
Over voltage level		II: Accord with IEC61131-2		
Pollution level		2: Accord with IEC61131-2		
Anti interference	e EMC	Accord with IEC 61131-2 IEC61000-6-4 B type		
Related certifications		CE		

7-2. Technical specification

Project		XSF-A32	XSF-A64
LD Bit		15ns	
Processing time	Mov Double	25	ōns
	Program capacity	32MB	32MB
	Non persistent data	32MB	32MB
D-4	capacity	32IVIB	
Data capacity	Maintain data capacity	10M	10M
	Storage capacity	512MB	512MB
	(files/formulas)	3121 VID	
SD card extension		Used for downloading programs and firmware upgrades on PLC	
		Storage capacity ≥ 2GB (Q3 support in 2023)	
USB interface	Type-C type	Used for downloading programs, firmware upgrades, and program	

		monitoring on PLC		
		USB drive connection, download program (supported in Q3 of 2023)		
Internal I/O	function in the body	None		
Exter	nsion quantity	32		
Powe	er outage hold	Non battery retention type		
	C11-11-14	Super capacitors ensure RTC availability for at least 14 days		
	Clock Hold	Optional CR2032 battery module for RTC clock only		
		Year, month, day, hour, minute, second, week (automatically		
Clock		recognized in leap years)		
	Precision	Ambient temperature 55 °C: -13.20~+2.12s/1 day		
		Ambient temperature 25 °C: -3.18~+3.74s/1 day		
		Ambient temperature 0 °C : -2.96~+3.74s/1 day		
		The dial switch adopts a 3-segment type, named RUN, STOP, and		
		RESET.		
D	oial switch	RUN and STOP control RTE enable status, and STOP -> RES		
		enable default IP and other functions.		
		Isolation type, with terminals A, B, and SG. Among them, A is		
		RS485+, B is RS485-, and SG is the signal ground.		
		Communication mode: half duplex		
		The maximum number of slave stations is 32		
		Transmission distance: 1000m		
COM	RS485	Terminal resistance: 120Ω		
		Baud rate: 2400bps~115200bps		
		Mode: ModbusRTU (default), ModbusASCII, free format.		
		The maximum number of bytes for free format communication is		
		1000 bytes.		
		0#ENET		
	Port	1 # Configurable ENET&ECAT, which can be used to		
		independently connect network nodes or redundant buses during		
		ECAT		
		Physical layer 10Base-T or 100Base-TX		
		Media access method CSMA/CD		
		Modulation baseband		
		Topological Star		
		Transmission speed 100Mbps(100Base-TX)		
ENET	Parameter	STP (shielded twisted pair) cables with transmission medium		
EI LI		Ethernet Class 5, 5e or higher		
		The maximum transmission distance between Ethernet switches and		
		nodes is 100m. There is no limit to the maximum number of serial		
		connections when using the Ethernet switch.		
	Function	ModbusTCP		
		Support at least 32 servers		
		Supports a minimum of 32 clients		
		2. TCP/IP, UDP/IP		
		Supports a minimum of 32		
		Dupports a minimum of 32		

		2 EthonNot/ID E1:-it Ethon Not	/ID Insuliait	
		3. EtherNet/IP Explicit, EtherNet/IP Implicit		
		Implicit (I/O) message communication supports scanners and		
		adapters.		
		Supports 128 devices and 256 connections.		
		Minimum release cycle 1ms.		
		Single connection supports a maximum of 1448 bytes.		
		4. OPC UA		
		Supports a minimum of 8 client connections.		
		Support sampling period of 50ms to 10s.		
		Supports a maximum number of 5	-	
		Can specify NTP server information	on and automatically synchronize	
		the clock.		
		2 # can be configured with ENET&ECAT, which can be used to		
	Port	independently connect network nodes or redundant buses during		
		ECAT; 3 # independent ECAT dedicated port		
			•	
	Parameter	Topological linearity, daisy chains, and branches Twisted pair cable with transmission medium category 5 or higher		
		_	- · · · · · · · · · · · · · · · · · · ·	
		(aluminum foil+woven mesh double shielded direct connected cable)		
		The maximum transmission distance between nodes is 100m		
		Maximum number of slave stations 128 (SM mode)		
ECAT		Maximum process data		
		Input: 5,736 byte		
		Output: 5,736 byte(The maximum number of frames for process		
		data is 4)		
		Maximum process data for each slave station		
		Input: 1,434 byte		
		Output: 1,434 byte		
		Synchronization cycle 125~4000us		
	ECAT node(DC mode)	32 1000us	64 1000us	
		64 4000us	128 4000us	
	Single axis	32	64	
	Master slave instance	32	64	
Motion	Axis Group instance	16	32	
	NC (G code DIN6602)	16 32	32	
	multi channels	10	34	
Weight		267g		
Power		10W		

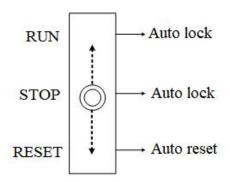
7-3. Functional specifications

(1) Auxiliary dialing specifications

Dial position				Definition	Commont
S1(obligate)	S2(obligate)	S3	S4	Definition	Comment
-	-	0	0	Empty	Set ON is 1
-	-	1	0	Use 485 terminal resistor	Set OFF is 0

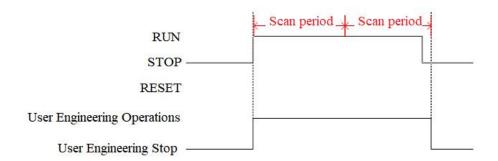
-	-	0	1	Use CAN terminal resistor
-	-	1	1	Use 485 and CAN terminal resistor

(2) System dialing specifications



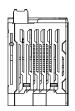
Dial	Function Description		
RUN	Dial to RUN, PLC switches to running state		
STOP	Dial to STOP, PLC switches to stop state		
	Dial to RESET and hold for 11s-20s, immediately restore the default IP and		
RESET	release the corresponding connection		
	(ENET0:192.168.6.6, ENET1: Automatically obtain IP address).		

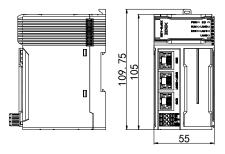
Note: When the device leaves the factory, the system dials the code to the "STOP" mode by default.

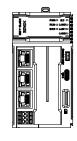


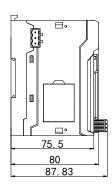
7-4. Apparent dimension

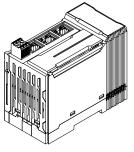
(1) XSF5-A32: unit: mm

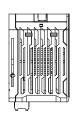




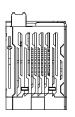


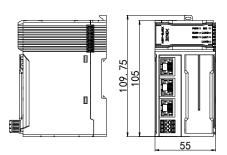




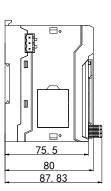


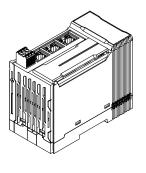
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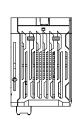














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