



XL series PLC extension module

User manual

Wuxi XINJE Electric Co., Ltd.

Data No. PL04 20231101EN 1.2

This manual includes some basic precautions which you should follow to keep you safe and protect the products. These precautions are underlined with warning triangles in the manual. About other manuals that we do not mention please follow basic electric operating rules.

Precautions



Please follow the precautions. If not, it may lead the control system incorrect or abnormal, even cause fortune lose.

Correct Application



The models could only be used according to the manual, and an only be used along with the peripheral equipment recognized or recommended by X Company. They could only work normally in the condition of be transported, kept and installed correctly, also please operate and maintain them according to the recommendation.

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Without exact paper file allowance, copy, translate or using the manual is not allowed. Disobey this, people should take the responsibility of loss. We reserve all the right of expansions and their design patent.

Duty Declare

We have checked the manual; its content fits the hardware and software of the products. As mistakes are unavoidable, we couldn't promise all correct. However, we would check the data in the manual frequently, and in the next edition, we will correct the necessary information. Your recommendation would be highly appreciated

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1. Module information summary

This chapter introduces the model, appearance, general specification, installation method, software configuration and PID function of XL series expansion module. This series of modules are suitable for XL series PLC models.

1-1. Module model and configuration

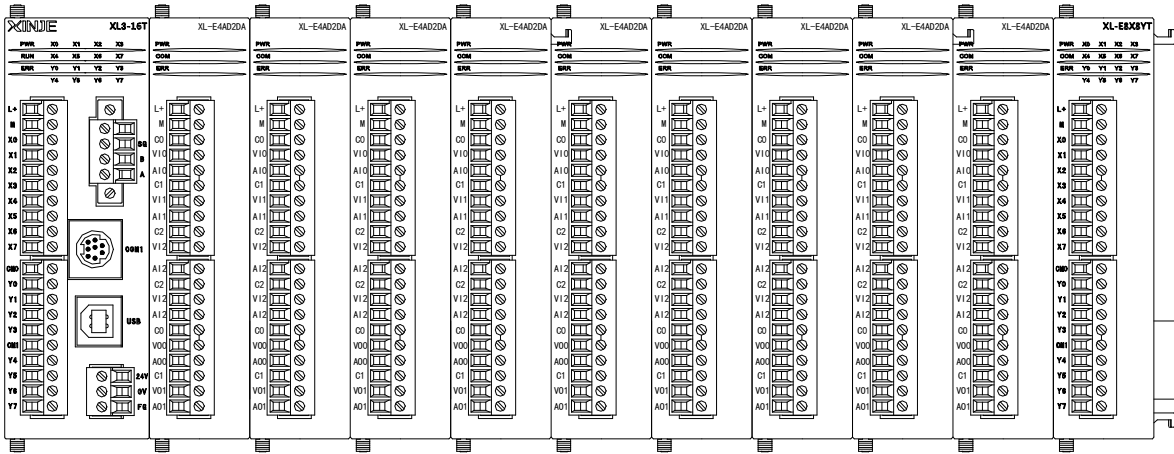
XL series PLC not only has powerful functions of logic processing, data operation and high-speed processing, but also has functions of A/D and D/A conversion. By using input-output expansion module and analog module, XL series PLC has been widely used in process control systems such as temperature, flow and liquid level.

Model and function

| Model | Function |
|--------------|---|
| XL-EnXmY | N inputs, m outputs, NPN input, relay/transistor output |
| XL-E4AD | 4-channel analog input (14 bits), current and voltage bipolar input |
| XL-E4AD2DA | 4 channels analog input (14 bits), 2 channels analog output (12 bits). Input output is voltage/current optional |
| XL-E8AD-A | 8 channels analog input (14 bits), current bipolar input |
| XL-E8AD-V | 8 channels analog input (14 bits), voltage bipolar input |
| XL-E8AD-A-S | 8 channels analog input (16 bits), current bipolar input |
| XL-E8AD-V-S | 8 channels analog input (16 bits), voltage bipolar input |
| XL-E4DA | 4 channels analog output (12 bits), current/voltage optional |
| XL-E4PT3-P | 4 channels PT100, PT1000 temperature measurement, with PID function |
| XL-E4PT3-P-H | 4 channels PT100, PT1000 temperature measurement, with PID function |
| XL-E4TC-P | 4 channels thermocouple temperature measurement, with PID function |
| XL-EnWT-D | N-channel pressure sensor input (23bit), detection range DC-20mV~20mV |

Module configuration

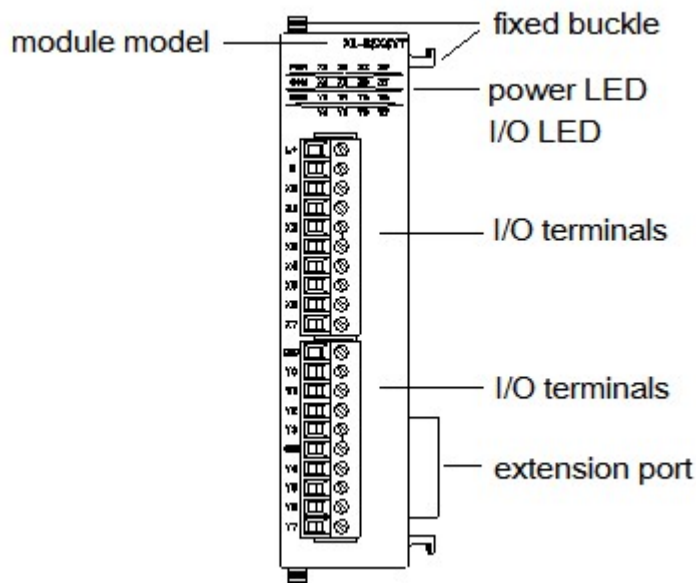
XL series expansion module can be installed on the right side of the main unit and expansion module of XL series PLC.



- The number of digital input and output is octal.
- The number of analog input and output is decimal.
- The XL3 series can connect up to 10 expansion modules, while the XL5/XL5E/XL5N/XL5H/XLME/XLH/XSLH series can connect up to 16 expansion modules. XL1 does not support expansion modules. There are no restrictions on the types, which can be input/output switch quantities, analog quantities, temperature control modules, etc.

Note: When the number of right extension modules connected by XL series PLC is more than 5, it is necessary to connect a terminal resistance module XL-ETR to the right of the last module (requiring the hardware version of XL series right extension module to be H3.1 or more).

1-2. Part name and function



| Name | Function | |
|----------------|--|---|
| Fixed buckle | fix the PLC unit and extension module | |
| Module model | The extension module model | |
| Extension port | To connect other modules | |
| I/O terminal | Connect analog input and output, external devices, removable | |
| Power LED | PWR | The LED lights up when the module has power supply. |
| | COM | When the module communication port communicates normally, the LED lights on. |
| | ERR | When there is an error in the module, the LED is always on or flickering (red). When the ERR LED is always on, it indicates that the module has serious application errors and can not be used. It is necessary to adjust the mode of use and switch the PLC to STOP state. When the ERR LED flickers, there are application errors, abnormal work and abnormal data in the module, but the PLC is still RUN. |
| I/O LED | Input output ON indicator | |

1-3. General specification

| | |
|-----------------------|------------------|
| Operating Environment | No corrosive gas |
| Ambient Temperature | 0°C~60°C |
| Store Temperature | -20~70°C |
| Ambient Humidity | 5~95% RH |
| Store Humidity | 5~95% RH |
| Operating Environment | No corrosive gas |

1-4. Module installation

Installation environment

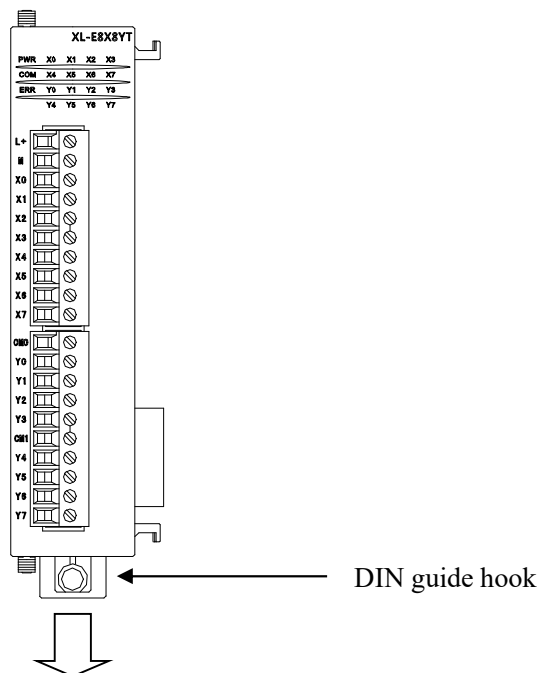
Do not install in the following environments:

- Places in direct sunlight
- Environment temperature exceeded 0-50 centigrade
- Environment humidity exceeded 35-85%
- Where dew occurs because of dramatic changes in temperature
- Places with corrosive and flammable gases
- Dust, iron scraps, salt, smoky places
- Places directly affected by vibration and shock
- Places for spraying water, oil and medicine
- A place where a strong magnetic field or electric field is produced

Installation

XL series analog input and output, temperature control module can be installed on the right side of the main unit and expansion module of XL series PLC. The installation can use DIN46277 guideway (35 mm wide).

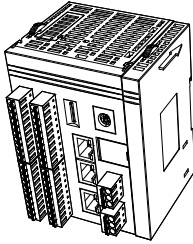
- Use DIN46277 guideway



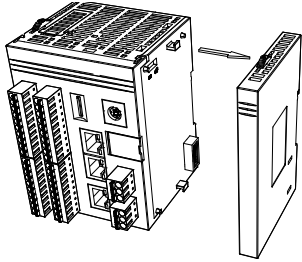
The basic unit and expansion module are installed on the DIN46277 guideway (35 mm wide). To dismantle, just pull down the assembly hook of DIN guide rail and take off the product.

- Installation process

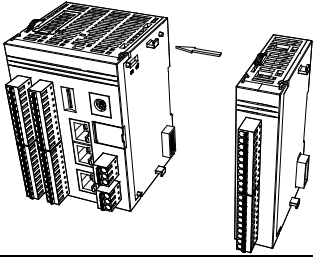
Taking the first expansion module as an example, explain the installation steps below:



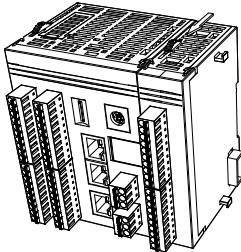
1. Find the back cover on the right side of the PLC, and push the back cover in the direction of the arrow shown in the diagram;



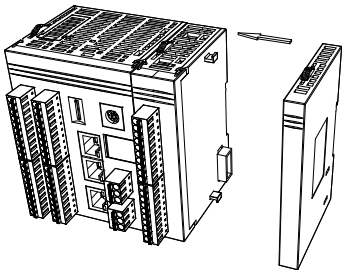
2. Take off the back cover



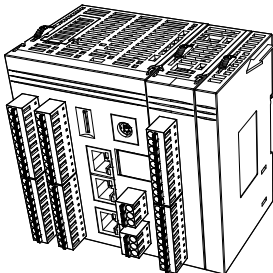
3. There is a expansion port on the right side of the PLC. Align it with the access port on the left side of the module to be installed and install it



4. Push the fixing clip of the module in the direction of the arrow shown in the diagram to fix the module.



5. Install the back cover removed in step 2 on the right side of the expansion module.



6. Push the upper and lower fixing clips of the back cover in the direction of the arrow shown in the diagram to fix the back cover.
-

Wiring requirement

Apart from the XL series 32-point extension module, which needs to use an external terminal for wiring, other modules can directly insert the cable into the corresponding wiring hole.

Cautions:

1. Please confirm the specifications and select the appropriate modules.
2. When processing screw holes and wiring, do not let chips and wire chips fall into the module.
3. Before connecting, please reconfirm the specifications of modules and connecting equipment to ensure that there is no problem.
4. When connecting, please pay attention to whether the connection is firm or not. If the connection falls off, it will cause data incorrect, short circuit and other faults.
5. Installation, wiring and other operations must be carried out after cutting off all the power supply.

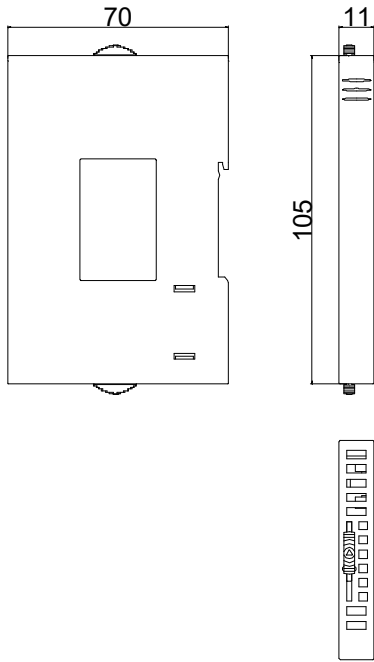
1-5. Terminal resistance module XL-ETR

When the number of right extension modules of XL series PLC is more than 5, the terminal resistance module XL-ETR must be used together.

XL-ETR is only applicable to XL series right extension modules of hardware version H3.1 and above.

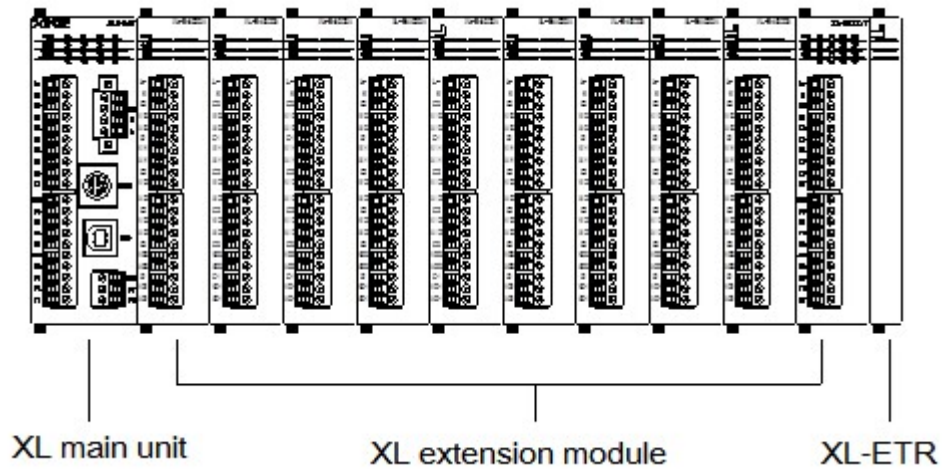
Dimension

Unit: mm



Installation

When using, please install XL-ETR on the right side of the last extension module and connect the interface slot of the module as shown in the following figure:

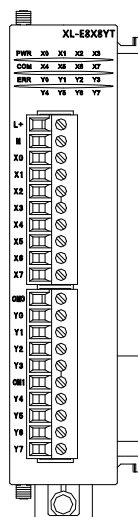


2. I/O extension module XL-EnXmY

This chapter mainly introduces the specification of XL-EnXmY module, terminal description, input definition number assignment, external connection, appearance size diagram and related programming examples.

2-1. Module features and specifications

XL series PLC can expand XL-EnXmY input and output module externally. Each XL3 series PLC can expand 10 modules, XL5/XL5E can expand 16 modules, XL1 does not support expansion module. The module is rich in types and compact in shape, which makes it possible for more input and output points and meets the actual production needs.



Naming rule

$\text{XL} - \text{E} \begin{matrix} \bigcirc \\ \square \end{matrix} \begin{matrix} \bigcirc \\ \square \end{matrix} - \begin{matrix} \square \\ \square \end{matrix}$
 ① ② ③ ④ ⑤ ⑥ ⑦

| | | |
|---|------------------|---|
| ① | Series name | XL: XL series expansion module |
| ② | Expansion module | E: expansion module |
| ③ | Input points | 8/16/32 |
| ④ | Input type | X: NPN type input PX: PNP type input |
| ⑤ | Output points | 8/16/32 |

| | | |
|---|----------------|---|
| ⑥ | Output type | YT: Transistor output YR: Relay output |
| ⑦ | Interface type | No: European terminal A: Horn terminal, requires external terminal block |

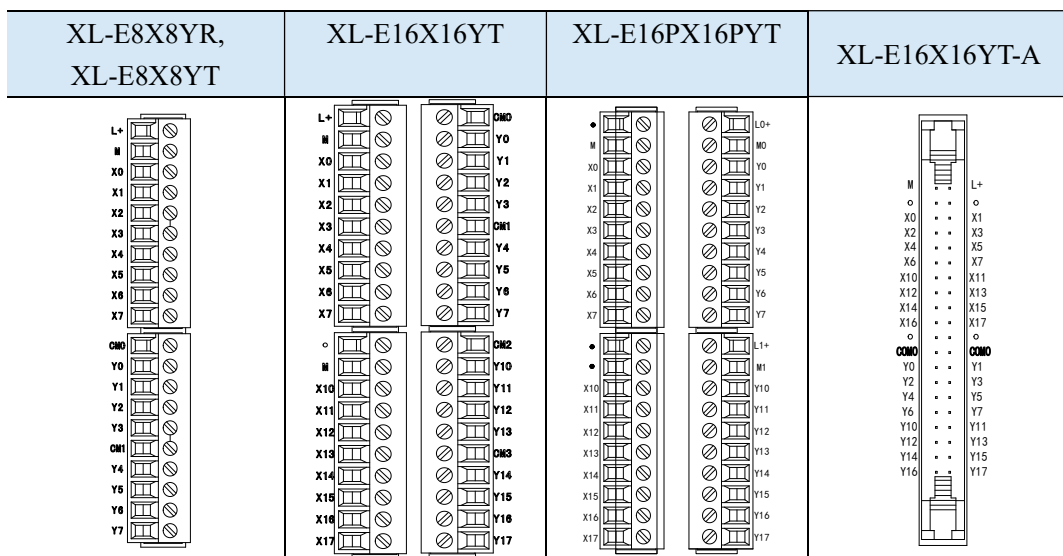
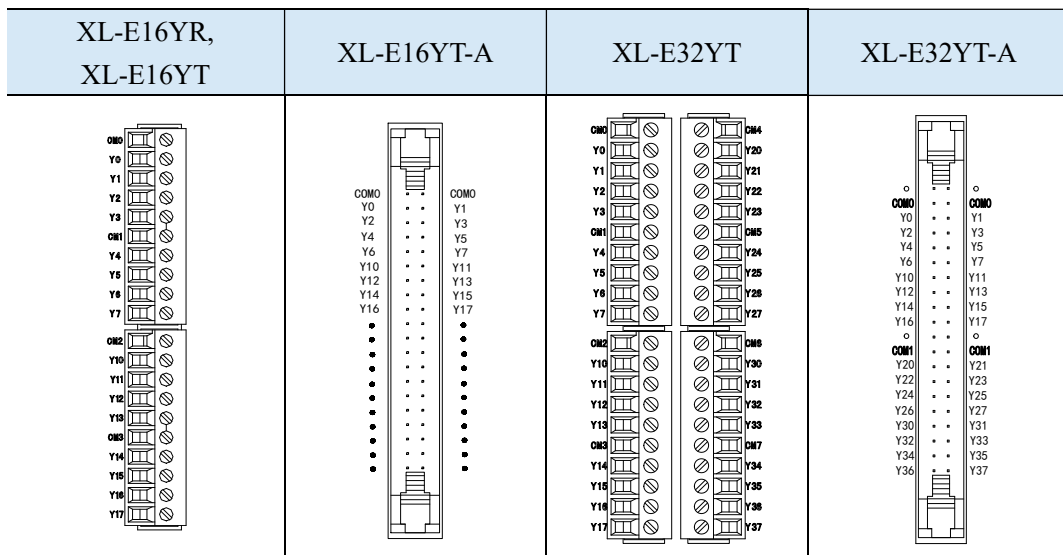
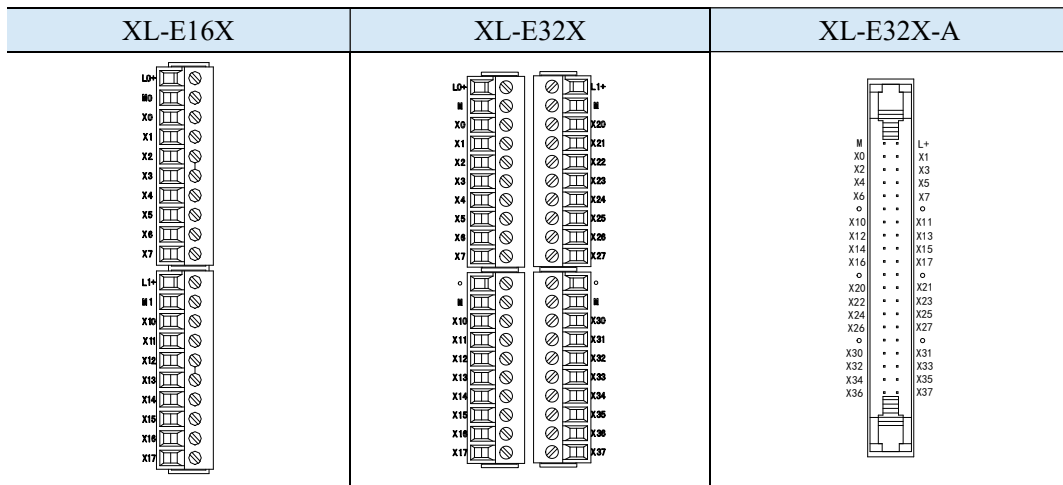
Models

| Model | | Function |
|---------------|----------------|--|
| NPN input | PNP input | |
| XL-E8X8YR | XL-E8PX8YR | 8 channels digital input, 8 channels relay output |
| XL-E8X8YT | XL-E8PX8YT | 8 channels digital input, 8 channels transistor output |
| XL-E16X | XL-E16PX | 16 channels digital input |
| XL-E16YR | - | 16 channels relay output |
| XL-E16YT | - | 16 channels transistor output |
| XL-E16YT-A | - | 16 channels transistor output (horn terminals) |
| XL-E16X16YT | XL-E16PX16YT | 16 channels digital input, 16 channels transistor output |
| - | XL-E16PX16PYT | 16 channels PNP digital input, 16 channels PNP transistor output |
| XL-E16X16YT-A | XL-E16PX16YT-A | 16 channels digital input, 16 channels transistor output (horn terminal) |
| XL-E32X | XL-E32PX | 32 channels digital input |
| XL-E32X-A | XL-E32PX-A | 32 channels digital input (horn terminals) |
| XL-E32YT | - | 32 channels transistor output |
| XL-E32YT-A | - | 32 channels transistor output (horn terminals) |

Module specification

| Item | Specification |
|--------------|---|
| Power supply | DC24V±10% |
| Environment | Non-corrosive gas |
| Temperature | 0°C~60°C |
| Humidity | 5~95% |
| Installation | Direct mounting on DIN46277 (35 mm wide) rail |

2-2. Terminal descriptions



Wiring head specifications

The wiring must be consistent with the following requirements in connection with the X-E8X8YR, XL-E8PX8YR, XL-E8PX8YT, XL-E16X, XL-E16PX, XL-E16YR, XL-E16YT modules:

- (1) The stripping length is 9 mm;
- (2) Flexible conductors with bare tubular ends are 0.25-1.5 square meter.
- (3) Flexible conductor with tubular pre-insulated end is 0.25-0.5 square meter.

2-3. I/O definition number

The addresses of the input and output terminals of the XL Series I/O Extension Module are as follows:

Note: The terminal definitions and addresses of NPN and PNP type modules are the same.

- **#1~#16 extension module input terminal X0~X37 definition:**

| | #1 | #2 | #3 | #4 | #5 | #6 | #7 | #8 |
|-----|--------|--------|--------|--------|--------|--------|--------|--------|
| X0 | X10000 | X10100 | X10200 | X10300 | X10400 | X10500 | X10600 | X10700 |
| X1 | X10001 | X10101 | X10201 | X10301 | X10401 | X10501 | X10601 | X10701 |
| ... | ... | ... | ... | ... | ... | ... | ... | ... |
| X7 | X10007 | X10107 | X10207 | X10307 | X10407 | X10507 | X10607 | X10707 |
| X10 | X10010 | X10110 | X10210 | X10310 | X10410 | X10510 | X10610 | X10710 |
| ... | ... | ... | ... | ... | ... | ... | ... | ... |
| X17 | X10017 | X10117 | X10217 | X10317 | X10417 | X10517 | X10617 | X10717 |
| X20 | X10020 | X10120 | X10220 | X10320 | X10420 | X10520 | X10620 | X10720 |
| ... | ... | ... | ... | ... | ... | ... | ... | ... |
| X27 | X10027 | X10127 | X10227 | X10327 | X10427 | X10527 | X10627 | X10727 |
| X30 | X10030 | X10130 | X10230 | X10330 | X10430 | X10530 | X10630 | X10730 |
| ... | ... | ... | ... | ... | ... | ... | ... | ... |
| X36 | X10036 | X10136 | X10236 | X10336 | X10436 | X10536 | X10636 | X10736 |
| X37 | X10037 | X10137 | X10237 | X10337 | X10437 | X10537 | X10637 | X10737 |
| | #9 | #10 | #11 | #12 | #13 | #14 | #15 | #16 |
| X0 | X11000 | X11100 | X11200 | X11300 | X11400 | X11500 | X11600 | X11700 |
| X1 | X11001 | X11101 | X11201 | X11301 | X11401 | X11501 | X11601 | X11701 |
| ... | ... | ... | ... | ... | ... | ... | ... | ... |
| X7 | X11007 | X11107 | X11207 | X11307 | X11407 | X11507 | X11607 | X11707 |
| X10 | X11010 | X11110 | X11210 | X11310 | X11410 | X11510 | X11610 | X11710 |
| ... | ... | ... | ... | ... | ... | ... | ... | ... |
| X17 | X11017 | X11117 | X11217 | X11317 | X11417 | X11517 | X11617 | X11717 |
| X20 | X11020 | X11120 | X11220 | X11320 | X11420 | X11520 | X11620 | X11720 |

| | | | | | | | | |
|-----|--------|--------|--------|--------|--------|--------|--------|--------|
| ... | ... | ... | ... | ... | ... | ... | ... | ... |
| X27 | X11027 | X11127 | X11227 | X11327 | X11427 | X11527 | X11627 | X11727 |
| X30 | X11030 | X11130 | X11230 | X11330 | X11430 | X11530 | X11630 | X11730 |
| ... | ... | ... | ... | ... | ... | ... | ... | ... |
| X36 | X11036 | X11136 | X11236 | X11336 | X11436 | X11536 | X11636 | X11736 |
| X37 | X11037 | X11137 | X11237 | X11337 | X11437 | X11537 | X11637 | X11737 |

● #1~#16 extension module output terminal Y0~Y37 definition:

| | #1 | #2 | #3 | #4 | #5 | #6 | #7 | #8 |
|-----|--------|--------|--------|--------|--------|--------|--------|--------|
| Y0 | Y10000 | Y10100 | Y10200 | Y10300 | Y10400 | Y10500 | Y10600 | Y10700 |
| Y1 | Y10001 | Y10101 | Y10201 | Y10301 | Y10401 | Y10501 | Y10601 | Y10701 |
| ... | ... | ... | ... | ... | ... | ... | ... | ... |
| Y7 | Y10007 | Y10107 | Y10207 | Y10307 | Y10407 | Y10507 | Y10607 | Y10707 |
| Y10 | Y10010 | Y10110 | Y10210 | Y10310 | Y10410 | Y10510 | Y10610 | Y10710 |
| ... | ... | ... | ... | ... | ... | ... | ... | ... |
| Y17 | Y10017 | Y10117 | Y10217 | Y10317 | Y10417 | Y10517 | Y10617 | Y10717 |
| Y20 | Y10020 | Y10120 | Y10220 | Y10320 | Y10420 | Y10520 | Y10620 | Y10720 |
| ... | ... | ... | ... | ... | ... | ... | ... | ... |
| Y27 | Y10027 | Y10127 | Y10227 | Y10327 | Y10427 | Y10527 | Y10627 | Y10727 |
| Y30 | Y10030 | Y10130 | Y10230 | Y10330 | Y10430 | Y10530 | Y10630 | Y10730 |
| ... | ... | ... | ... | ... | ... | ... | ... | ... |
| Y36 | Y10036 | Y10136 | Y10236 | Y10336 | Y10436 | Y10536 | Y10636 | Y10736 |
| Y37 | Y10037 | Y10137 | Y10237 | Y10337 | Y10437 | Y10537 | Y10637 | Y10737 |
| | #9 | #10 | #11 | #12 | #13 | #14 | #15 | #16 |
| Y0 | Y11000 | Y11100 | Y11200 | Y11300 | Y11400 | Y11500 | Y11600 | Y11700 |
| Y1 | Y11001 | Y11101 | Y11201 | Y11301 | Y11401 | Y11501 | Y11601 | Y11701 |
| ... | ... | ... | ... | ... | ... | ... | ... | ... |
| Y7 | Y11007 | Y11107 | Y11207 | Y11307 | Y11407 | Y11507 | Y11607 | Y11707 |
| Y10 | Y11010 | Y11110 | Y11210 | Y11310 | Y11410 | Y11510 | Y11610 | Y11710 |
| ... | ... | ... | ... | ... | ... | ... | ... | ... |
| Y17 | Y11017 | X11117 | X11217 | X11317 | X11417 | X11517 | X11617 | X11717 |
| Y20 | Y11020 | Y11120 | Y11220 | Y11320 | Y11420 | Y11520 | Y11620 | Y11720 |
| ... | ... | ... | ... | ... | ... | ... | ... | ... |
| Y27 | Y11027 | Y11127 | Y11227 | Y11327 | Y11427 | Y11527 | Y11627 | Y11727 |
| Y30 | Y11030 | Y11130 | Y11230 | Y11330 | Y11430 | Y11530 | Y11630 | Y11730 |
| ... | ... | ... | ... | ... | ... | ... | ... | ... |
| Y36 | Y11036 | Y11136 | Y11236 | Y11336 | Y11436 | Y11536 | Y11636 | Y11736 |
| Y37 | Y11037 | Y11137 | Y11237 | Y11337 | Y11437 | Y11537 | Y11637 | Y11737 |

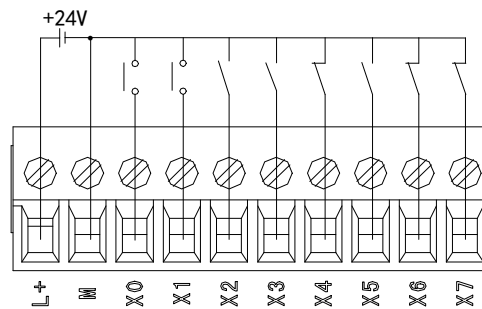
2-4. External connection

2-4-1. Input wiring

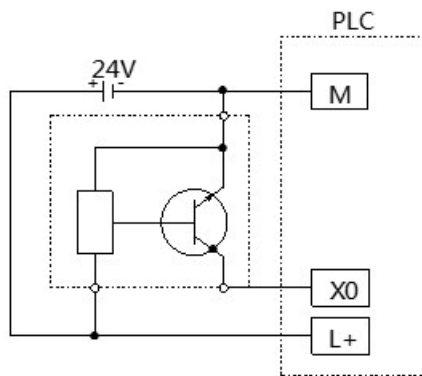
NPN input specification:

| | |
|----------------------|--|
| Input signal voltage | DC24V±10% |
| Input signal current | 7mA/DC24V |
| Input ON current | Below 4.5mA |
| Input OFF current | Below 1.5mA |
| Input response time | About 10ms |
| Input signal form | Contact input or NPN open collector transistor |
| Circuit insulation | Optoelectronic coupling insulation |
| Input action display | LED lights up when input is ON |

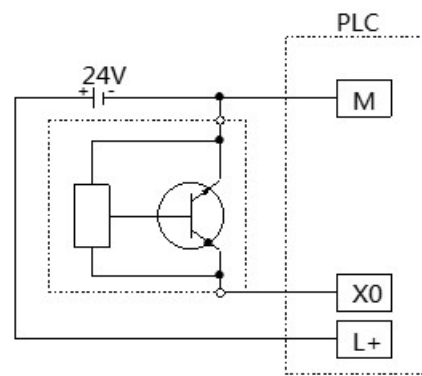
NPN input terminal wiring method:



Button wiring example



3-wire (NPN) proximity switch wiring



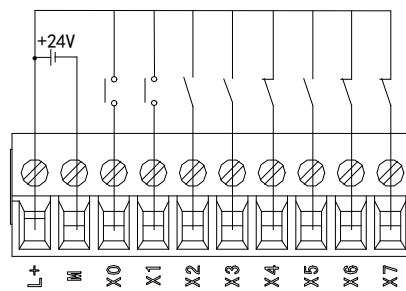
2-wire (NO/NC) proximity switch wiring

PNP input specification:

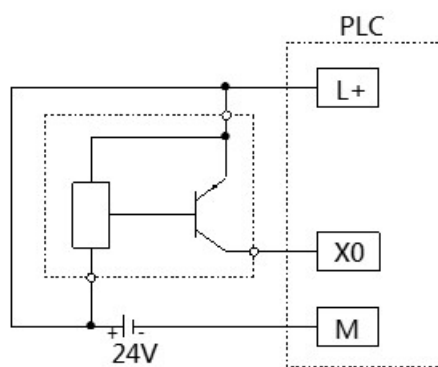
| | |
|----------------------|--|
| Input signal voltage | DC24V±10% |
| Input signal current | 7mA/DC24V |
| Input ON current | Below 4.5mA |
| Input OFF current | Below 1.5mA |
| Input response time | About 10ms |
| Input signal form | Contact input or PNP open collector transistor |
| Circuit insulation | Optoelectronic coupling insulation |
| Input action display | LED lights up when input is ON |

PNP input terminal wiring method:

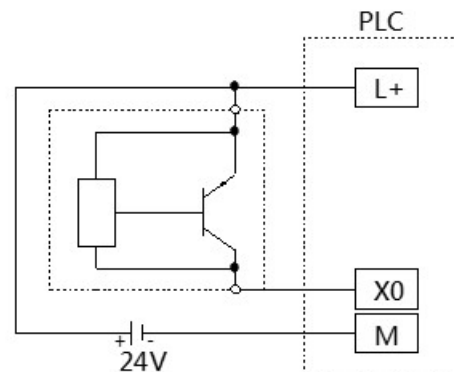
General models:



Button wiring example

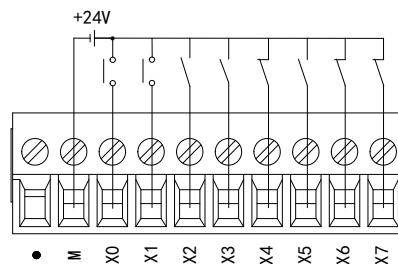


3-wire (PNP) proximity switch wiring

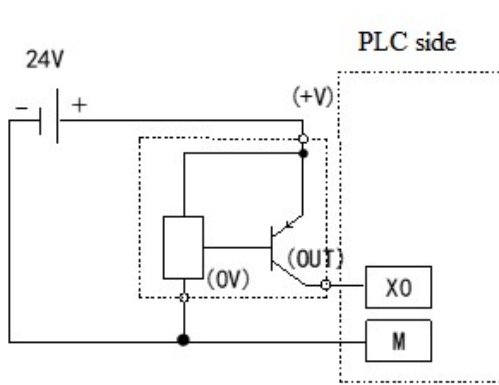


2-wire (NO/NC) proximity switch wiring

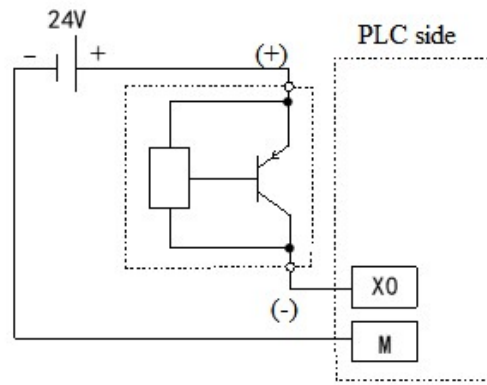
XL-E16PX16PYT:



Button wiring example



3-wire proximity switch wiring



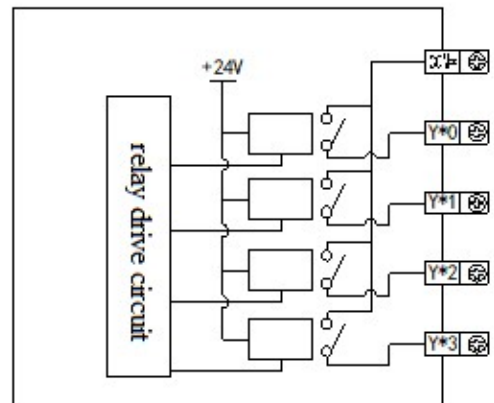
2-wire proximity switch wiring

2-4-2. Output wiring

Output specification:

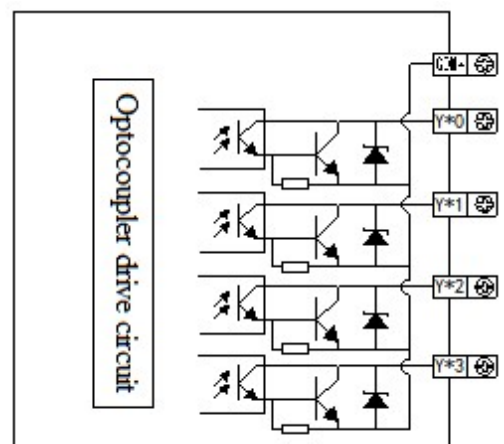
(1) Relay output

| | | |
|-----------------------|-----------------------|------|
| External power supply | Below AC250V, DC30V | |
| Circuit insulation | Mechanical insulation | |
| Action display | LED light | |
| Max load | Resistive | 3A |
| | Inductive | 80VA |
| | Light | 100W |
| Min load | DC5V 2mA | |
| Response time | OFF→ON | 10ms |
| | ON→OFF | 10ms |



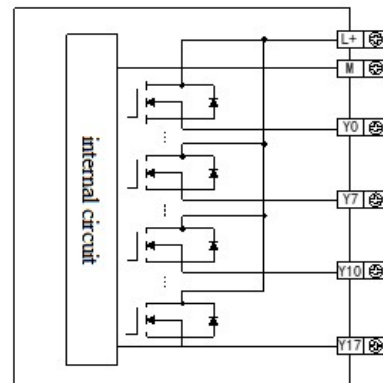
(2) General transistor output (NPN)

| | | |
|------------------------------|------------------------|-------------|
| External power supply | Below DC5~30V | |
| Circuit insulation | Optocoupler insulation | |
| Action display | LED light | |
| Max load | Resistive | 0.3A |
| | Inductive | 7.2W/DC24V |
| | Light | 1.5W/DC24V |
| Min load | DC5V 2mA | |
| Open circuit leakage current | Below 0.1mA | |
| Response time | OFF→ON | Below 0.2ms |
| | ON→OFF | Below 0.2ms |



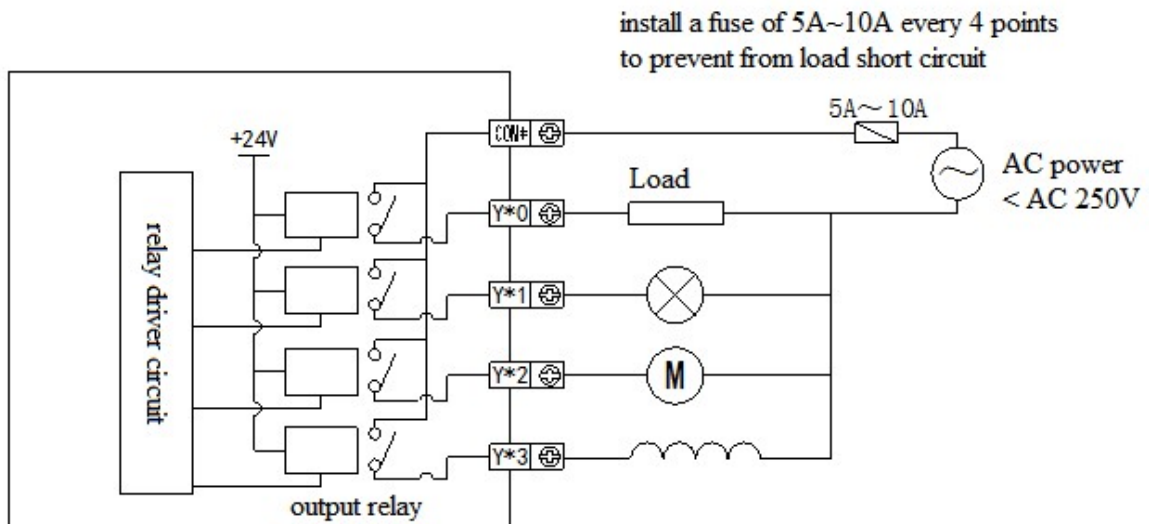
(3) General transistor output (PNP)

| | | |
|------------------------------|-----------|------------------------|
| External power supply | | Below DC5~30V |
| Circuit insulation | | Optocoupler insulation |
| Action display | | LED light |
| Max load | Resistive | 0.3A |
| Min load | | DC5V 2mA |
| Open circuit leakage current | | Below 0.1mA |
| Response time | OFF→ON | Below 0.2ms |
| | ON→OFF | Below 0.2ms |

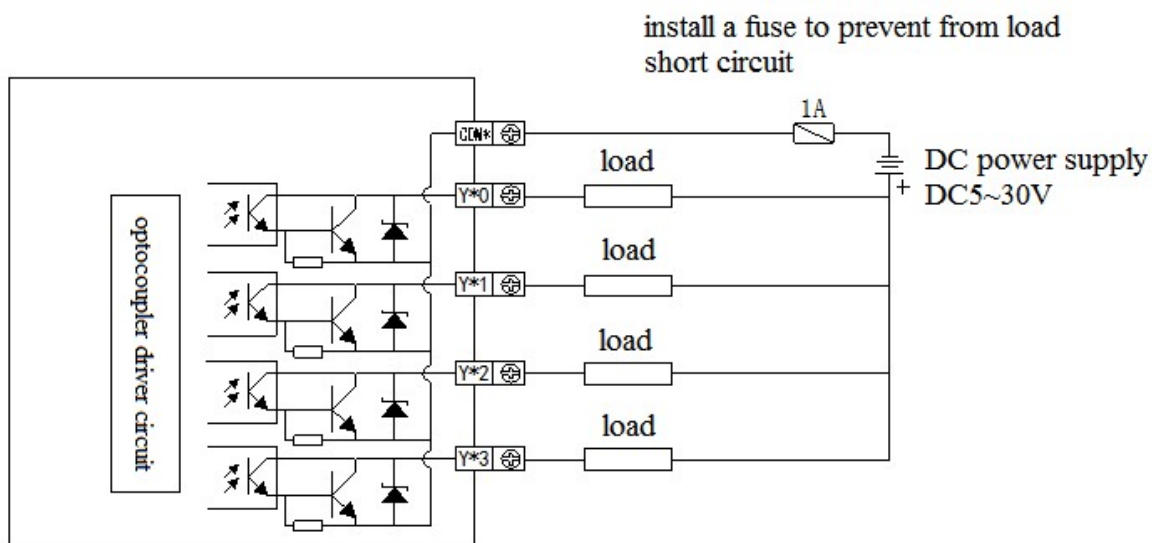


Output wiring method:

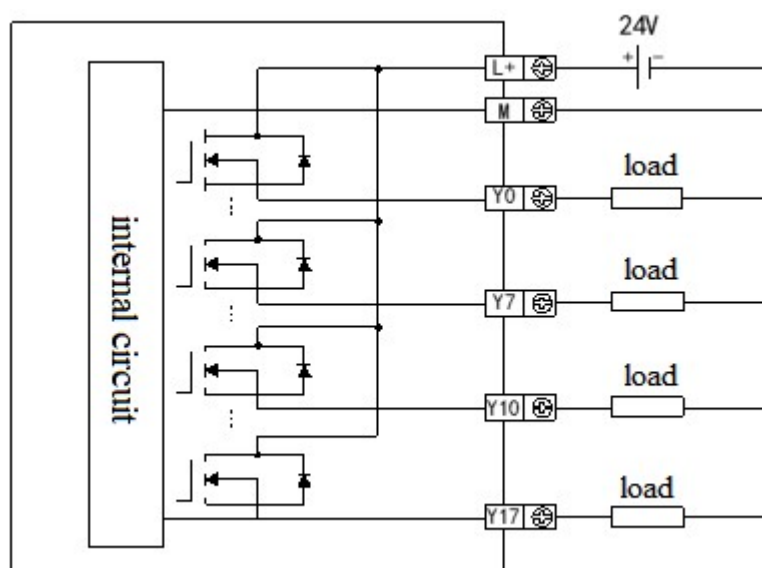
Relay type



Transistor type (NPN)



Transistor type (PNP)



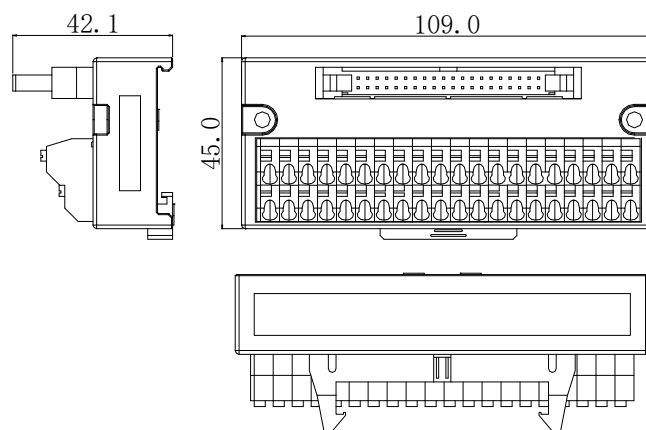
2-4-3. External terminal block

XL-A modules have horn terminals, which need external terminals. Xinje provides adapter terminals and connection cables for users to choose from. A list of module models and adapter terminals and connecting cables:

| Module | Terminal | Cable |
|----------------|-------------|---|
| XL-E16YT-A | JT-E16YT-A | JC-TE32-NN05 (0.5m) JC-TE32-NN10 (1.0m) JC-TE32-NN15 (1.5m) |
| XL-E16X16YT-A | JT-E16X16YT | |
| XL-E16PX16YT-A | | |
| XL-E32X-A | JT-E32X | |
| XL-E32PX-A | | |
| XL-E32YT-A | JT-E32YT | |

- Terminal appearance

(Unit: mm)



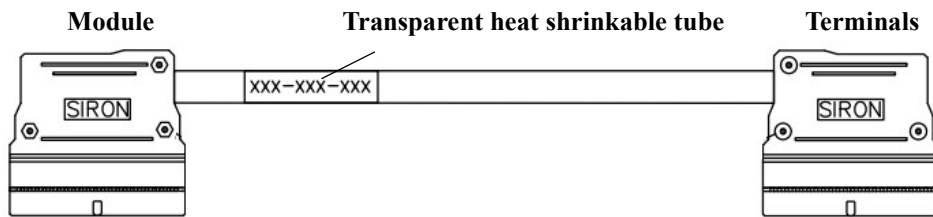
- **Wiring method**

When wiring, press the spring switch with the slotted screwdriver, insert the wire into the corresponding holes, and loosen the spring switch. The length of the cable skin stripping is 1.5 cm.

- **Connection cable**

External terminals need to cooperate with the use of connecting cables, Xinje provides JC-TE32-NNN05, JC-TE32-NN10, JC-TE32-NN15 three different length of cables for users to choose and purchase. When connecting, please note that the end closing to the transparent heat shrinkable tube connects the module, the other end connects to the terminals, can not be reversed!!!

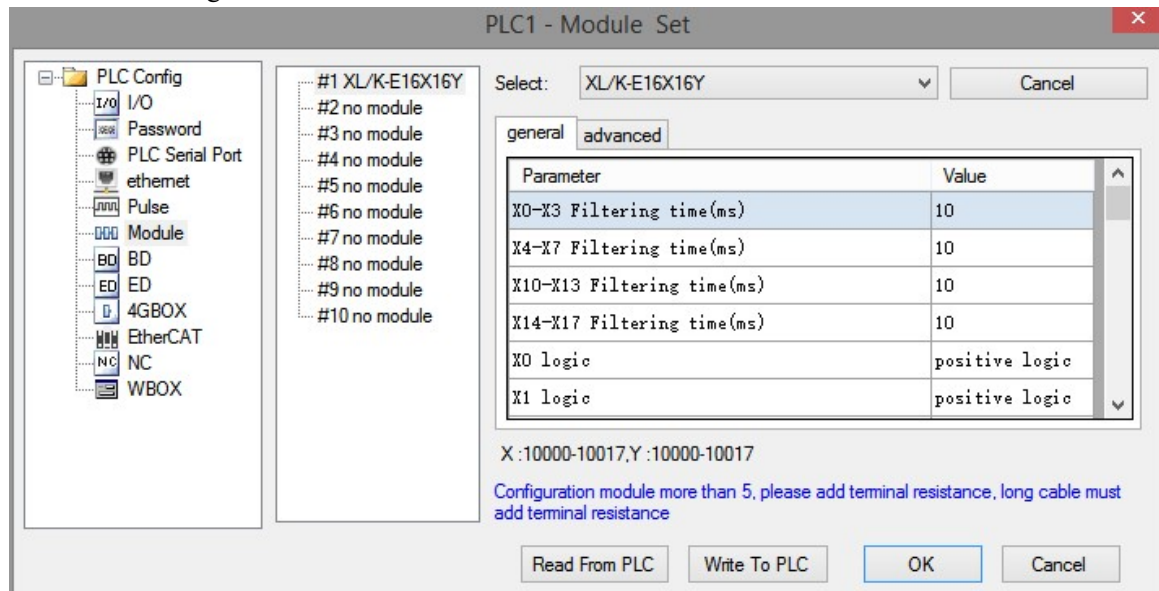
Wiring diagram:



2-5. Module parameters

Positive and negative logic can be adjusted and filtering time can be adjusted. There are two configuration modes:

A. Set through the software



B. Set through SFD register

| Module number | SFD address | Module number | SFD address |
|---------------|---------------|---------------|---------------|
| #1 | SFD350~SFD359 | #9 | SFD430~SFD439 |
| #2 | SFD360~SFD369 | #10 | SFD440~SFD449 |

| | | | |
|----|---------------|-----|---------------|
| #3 | SFD370~SFD379 | #11 | SFD450~SFD459 |
| #4 | SFD380~SFD389 | #12 | SFD460~SFD469 |
| #5 | SFD390~SFD399 | #13 | SFD470~SFD479 |
| #6 | SFD400~SFD409 | #14 | SFD480~SFD489 |
| #7 | SFD410~SFD419 | #15 | SFD490~SFD499 |
| #8 | SFD420~SFD429 | #16 | SFD500~SFD509 |

The first 20 bytes of OMMAND information are allocated as follows:

● **XL-E8X8Y**

| | Byte0 | Byte1 | Byte2 | Byte3 | Byte4 | Byte5 | Byte6~ Byte19 |
|-------|---|-------------------------|---|----------|----------|----------|------------------|
| Bit7 | X0~X3 filtering time | X4~X7 filtering time | - | - | - | - | - |
| Bit6 | | | X3 logic | X7 logic | Y3 logic | Y7 logic | - |
| Bit5 | | | - | - | - | - | - |
| Bit4 | | | X2 logic | X6 logic | Y2 logic | Y6 logic | - |
| Bit3 | | | - | - | - | - | - |
| Bit2 | | | X1 logic | X5 logic | Y1 logic | Y5 logic | - |
| Bit1 | | | - | - | - | - | - |
| Bit0 | | | X0 logic | X4 logic | Y0 logic | Y4 logic | - |
| Notes | Filtering time (unit: ms): 1~5, 10(default), 15, 20, 25, 30, 35, 40, 45, 50 | | Note: 0 is positive logic, 1 is negative logic | | | | - |

● **XL-E16X**

| | Byte0 | Byte1 | Byte2 | Byte3 | Byte 4 | Byte 5 | Byte 6 | Byte 7 | Byte8~ Byte19 |
|-------|--|----------------------------|------------------------------|------------------------------|---|-------------|--------------|--------------|------------------|
| Bit7 | X0~X3 filtering time | X4~X7 filtering time | X10~X13 filtering time | X14~X17 filtering time | - | - | - | - | - |
| Bit6 | | | | | X3 logic | X7 logic | X13 logic | X17 logic | - |
| Bit5 | | | | | - | - | - | - | - |
| Bit4 | | | | | X2 logic | X6 logic | X12 logic | X16 logic | - |
| Bit3 | | | | | - | - | - | - | - |
| Bit2 | | | | | X1 logic | X5 logic | X11 logic | X15 logic | - |
| Bit1 | | | | | - | - | - | - | - |
| Bit0 | | | | | X0 logic | X4 logic | X10 logic | X14 logic | - |
| Notes | Filtering time (unit: ms): 1~5, 10(default), 15, 20, 25, 30, 35, 40, 45, 50 | | | | Note: 0 is positive logic, 1 is negative logic | | | | - |

● **XL-E16X16Y**

| | Bit0 | Bit1 | Bit2 | Bit3 | Bit4 | Bit5 | Bit6 | Bit7 | Explanation |
|------------|------------------------|------|--------------|------|--------------|------|--------------|------|--|
| Byte0 | X0~X3 filtering time | | | | | | | | Filtering time (unit: ms): 1~5, 10(default), 15, 20, 25, 30, 35, 40, 45, 50 |
| Byte1 | X4~X7 filtering time | | | | | | | | |
| Byte2 | X10~X13 filtering time | | | | | | | | |
| Byte3 | X14~X17 filtering time | | | | | | | | |
| Byte4 | X0 logic | - | X1 logic | - | X2 logic | - | X3 logic | - | Note: 0 is positive logic, 1 is negative logic |
| Byte5 | X4 logic | - | X5 logic | - | X6 logic | - | X7 logic | - | |
| Byte6 | X10 logic | - | X11 logic | - | X12 logic | - | X13 logic | - | |
| Byte7 | X14 logic | - | X15 logic | - | X16 logic | - | X17 logic | - | |
| Byte8 | Y0 logic | - | Y1 logic | - | Y2 logic | - | Y3 logic | - | |
| Byte9 | Y4 logic | - | Y5 logic | - | Y6 logic | - | Y7 logic | - | |
| Byte10 | Y10 logic | - | Y11 logic | - | Y12 logic | - | Y13 logic | - | |
| Byte11 | Y14 logic | - | Y15 logic | - | Y16 logic | - | Y17 logic | - | |
| Byte 12~19 | - | - | - | - | - | - | - | - | |

● **XL-E16Y/XL-E32Y**

| | Bit0 | Bit1 | Bit2 | Bit3 | Bit4 | Bit5 | Bit6 | Bit7 | Explanation |
|----------|--------------|------|--------------|------|--------------|------|--------------|------|--|
| Byte0 | Y0 logic | - | Y1 logic | - | Y2 logic | - | Y3 logic | - | Note: 0 is positive logic, 1 is negative logic |
| Byte1 | Y4 logic | - | Y5 logic | - | Y6 logic | - | Y7 logic | - | |
| Byte2 | Y10 logic | - | Y11 logic | - | Y12 logic | - | Y13 logic | - | |
| Byte3 | Y14 logic | - | Y15 logic | - | Y16 logic | - | Y17 logic | - | |
| Byte4 | Y20 logic | - | Y21 logic | - | Y22 logic | - | Y23 logic | - | |
| Byte5 | Y24 logic | - | Y25 logic | - | Y26 logic | - | Y27 logic | - | |
| Byte6 | Y30 logic | - | Y31 logic | - | Y32 logic | - | Y33 logic | - | |
| Byte7 | Y34 logic | - | Y35 logic | - | Y36 logic | - | Y37 logic | - | |
| Byte8~19 | - | - | - | - | - | - | - | - | |

● **XL-E32X**

| | Bit0 | Bit1 | Bit2 | Bit3 | Bit4 | Bit5 | Bit6 | Bit7 | Explanation |
|---------------|------------------------|------|--------------|------|--------------|------|--------------|------|--|
| Byte0 | X0~X3 filtering time | | | | | | | | Filtering time (unit: ms): 1~5, 10(default), 15, 20, 25, 30, 35, 40, 45, 50 |
| Byte1 | X4~X7 filtering time | | | | | | | | |
| Byte2 | X10~X13 filtering time | | | | | | | | |
| Byte3 | X14~X17 filtering time | | | | | | | | |
| Byte4 | X20~X23 filtering time | | | | | | | | |
| Byte5 | X24~X27 filtering time | | | | | | | | |
| Byte6 | X30~X33 filtering time | | | | | | | | |
| Byte7 | X34~X37 filtering time | | | | | | | | |
| Byte8 | X0 logic | - | X1 logic | - | X2 logic | - | X3 logic | - | Note: 0 is positive logic, 1 is negative logic |
| Byte9 | X4 logic | - | X5 logic | - | X6 logic | - | X7 logic | - | |
| Byte10 | X10 logic | - | X11 logic | - | X12 logic | - | X13 logic | - | |
| Byte11 | X14 logic | - | X15 logic | - | X16 logic | - | X17 logic | - | |
| Byte12 | X20 logic | - | X21 logic | - | X22 logic | - | X23 logic | - | |
| Byte13 | X24 logic | - | X25 logic | - | X26 logic | - | X27 logic | - | |
| Byte14 | X30 logic | - | X31 logic | - | X32 logic | - | X33 logic | - | |
| Byte15 | X34 logic | - | X35 logic | - | X36 logic | - | X37 logic | - | |
| Byte 16~19 | - | - | - | - | - | - | - | - | |

Note:

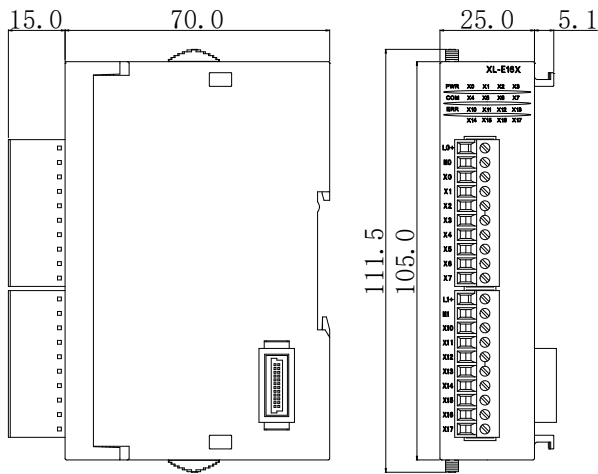
In positive logic, X terminal is ON, X-terminal signal is ON, X terminal is OFF and X-terminal signal is OFF.

In negative logic, X terminal is ON, X terminal signal is OFF, X terminal is OFF, X-terminal signal is ON.

Default is positive logic, usually without modification.

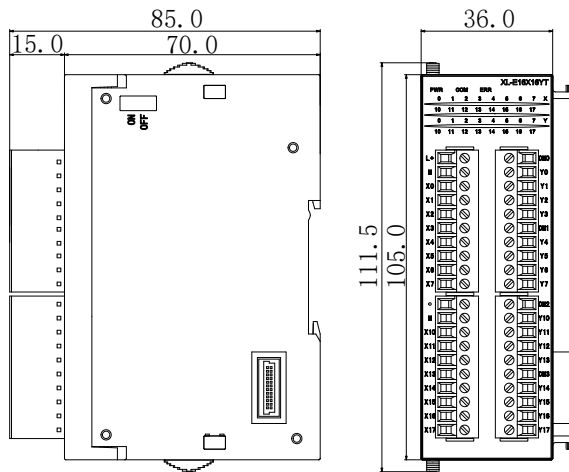
2-6. Dimension

Unit: mm



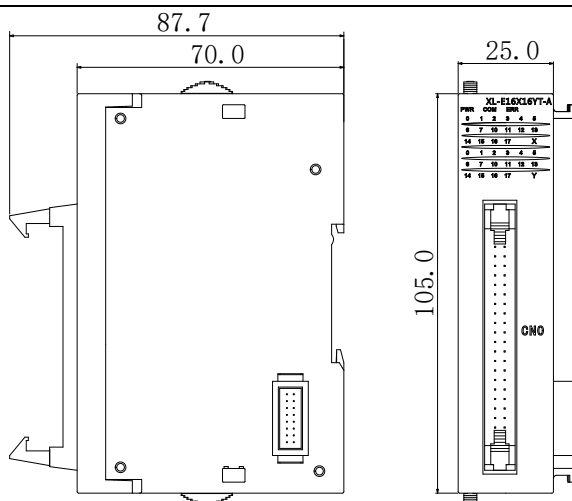
Suitable modules

| Input | Output | Input/output |
|----------|------------|--------------|
| XL-E16X | XL-E8X8YR | XL-E16YR |
| XL-E16PX | XL-E8PX8YR | XL-E16YT |
| | XL-E8X8YT | |
| | XL-E8PX8YT | |



Suitable modules

| Input | Output | Input/output |
|---------|---------------|--------------|
| XL-E32X | XL-E16X16YT | XL-E32YT |
| | XL-E16PX16PYT | |



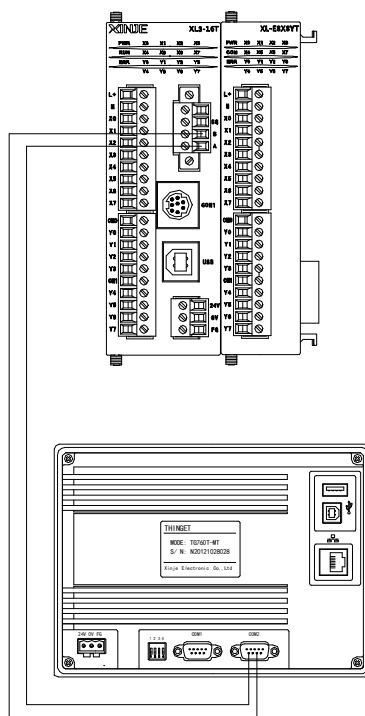
Suitable modules

| Input | Output | Input/output |
|-----------|---------------|--------------|
| XL-E32X-A | XL-E16X16YT-A | XL-E16YT-A |
| | | XL-E32YT-A |

2-7. Application

In this chapter, the application of this module will be exemplified. XL3-16R is slave station with an extended XL-E8X8YR to communicate with XINJE HMI.

Communication between Extended Module XL-E8X8YR and Xinje TG765 HMI.



In this example, as the main communication station, the HMI reads the input point state of the extended module to the local coil state of the HMI, and writes the coil state of the internal HMI to the output point of the extended module. The corresponding relationship is as follows:

Hardware connection:

The module XL-E8X8YR is attached to XL3-16R, and the RS485 communication terminal AB of XL3-16R is connected to the AB terminal of the PLC port of TG765 respectively.

Communication parameter settings: the baud rate is 19200 bps, 8 data bits, 1 stop bit, even parity, PLC Modbus station number is 1, then cut the power supply and power on again.

For TG765 HMI: please set the PLC type to Modbus RTU (panel is master). The baud rate is 19200 bps, 8 data bits, 1 stop bit, even parity.

Program application:

The corresponding relationship between the module input and output address and the local coil address is as follows:

| Local coil address | Module I/O | Related modbus address |
|--------------------|------------|------------------------|
| PSB500 | X10000 | K20736 |
| PSB501 | Y10000 | K24832 |

HMI screen:

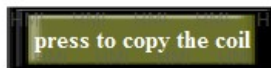
Extension module X10000



HMI internal coil PSB500



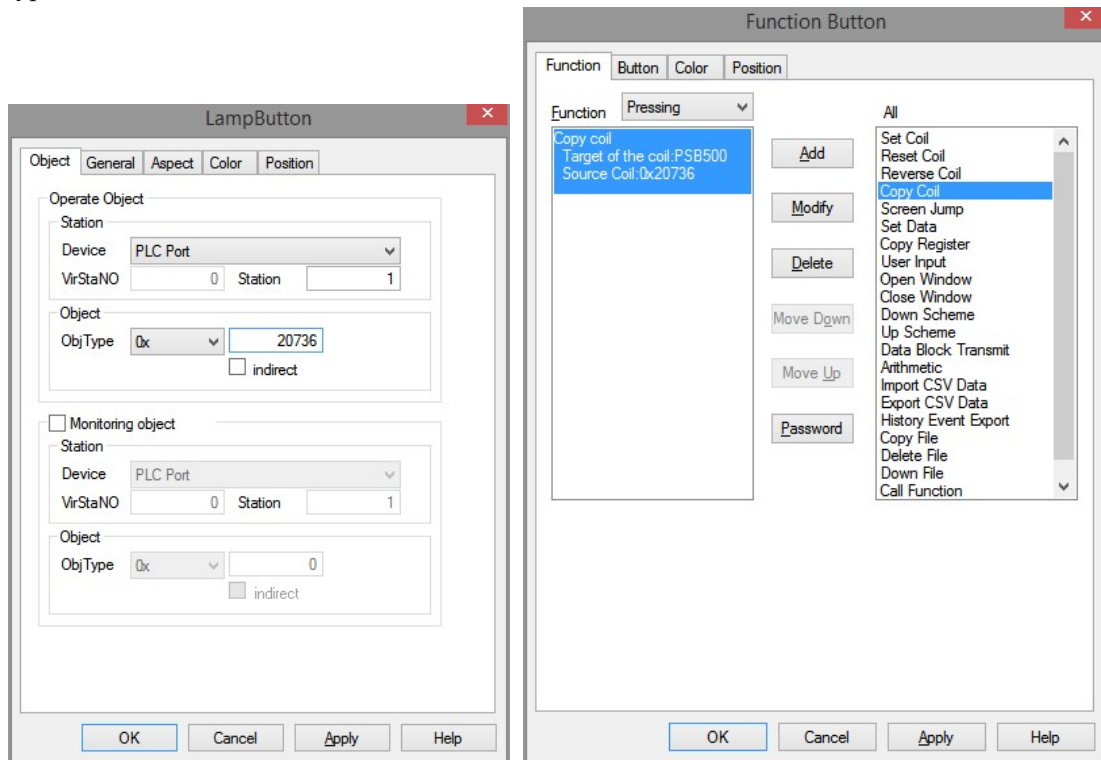
HMI internal coil PSB501

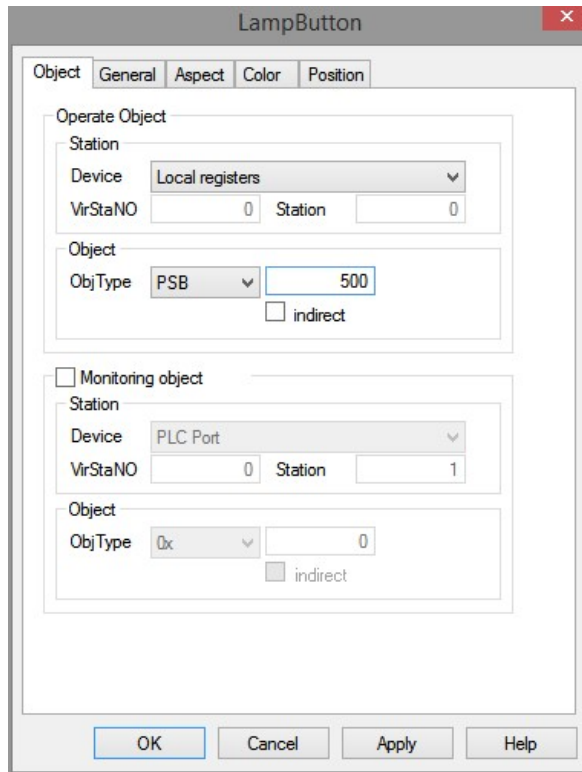


Extension module Y10000

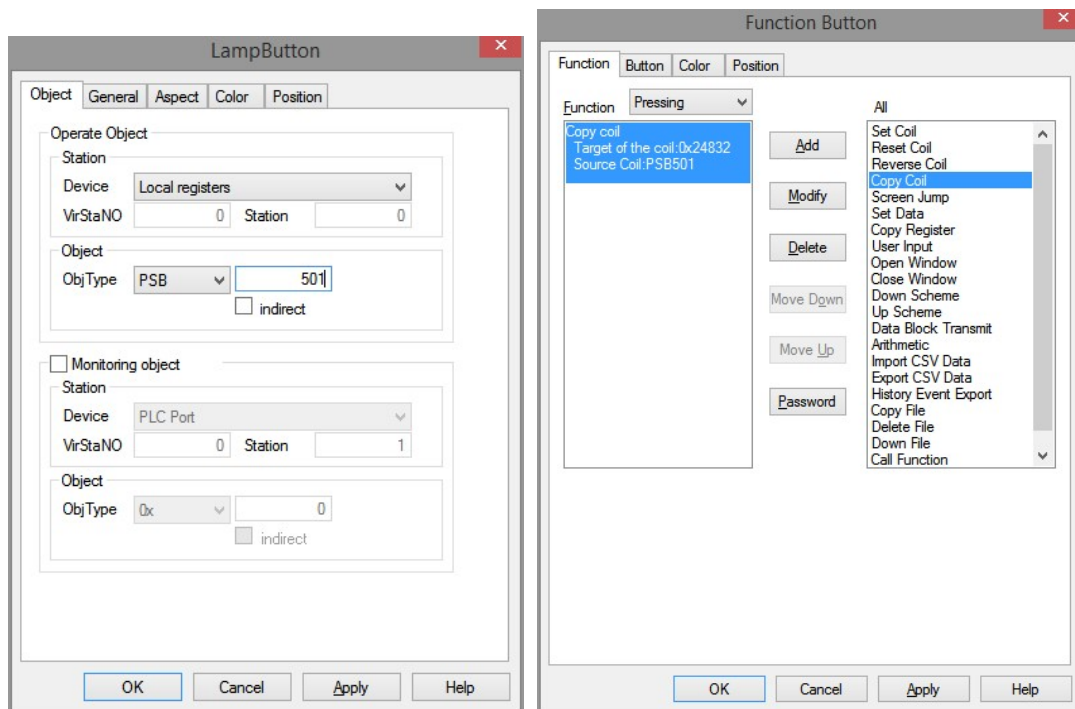


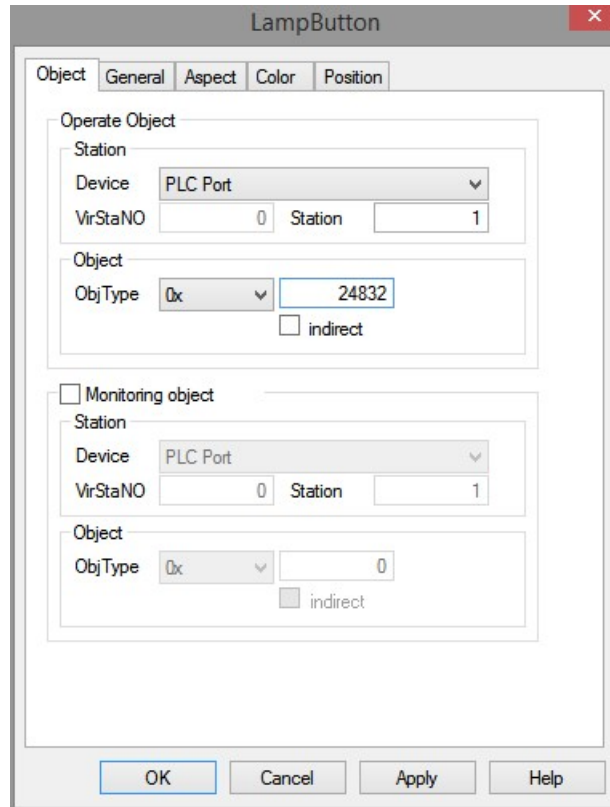
Edit the status of extension module X10000, place a lamp, the object type of lamp is 0X, corresponding Modbus address coil is 20736; select function button, button function is to copy the coil status of X10000 to PSB500 when pressing the button; edit PSB500 lamp, the lamp object type is PSB, the coil number is 500.





Edit the PSB501 status, place a lamp, the lamp object type is PSB, the coil number is 501. When the function button is pressed, copy the status of PSB501 to extension module Y10000. Edit the status of extension module Y10000, the lamp object type is 0x, the modbus address is 24832.





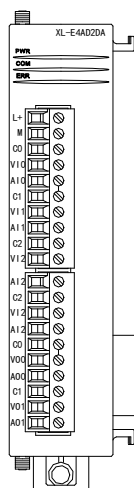
Download the program into the HMI. Then make them to communicate.

3. Analog I/O module XL-E4AD2DA

This chapter mainly introduces XL-E4AD2DA module specifications, terminal, input definition number allocation, working mode settings, external connections, analog-to-digital conversion diagrams, appearance size diagrams and related programming examples.

3-1. Module features and specifications

XL-E4AD2DA analog input and output module converts four channels of analog input values into digital values, two channels of digital values into analog values, and transmits them to the main unit of PLC, and real-time data interaction with the main unit of PLC.



Module features

- Four-channel analog input: Voltage input and current input can be selected.
- 14-bit high-precision analog input.
- 2-channel 12-bit analog output.
- As an expansion module of the XL series, XL3 can connect up to 10 modules, XL5/XL5E/XL5N/XL5H/XLME/XLH/XSLH can expand 16 modules, and XL1 does not support expansion modules.

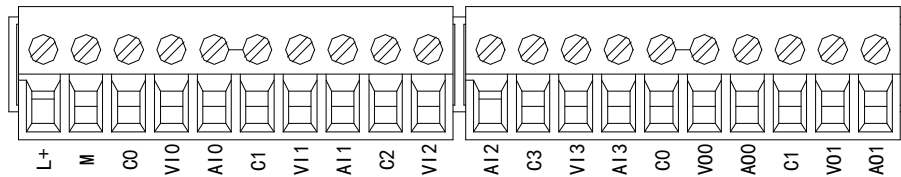
Module specification

| Items | Analog input (AD) | | Analog output (DA) | |
|---------------------|--------------------------------|--------------------------------|--|---|
| | Voltage input | Current input | Voltage output | Current output |
| Analog input range | 0~5V, 0~10V, -5~5V, -10~10V | 0~20mA, 4~20mA, -20~20mA | - | - |
| Max input range | DC ±15V | -40~40mA | - | - |
| Analog output range | - | - | 0~5V, 0~10V, -5~5V, -10~10V (Exterior load resistance 2KΩ~1MΩ) | 0~20mA, 4~20mA (Exterior load resistance is less than 500Ω) |

| | | |
|----------------------|---|---|
| Digital input range | - | 12 bits binary data (0~4095 or -2048~2047) |
| Digital output range | 14 bits binary data (0~16383 or -8192~8191) | - |
| Resolution | 1/16383(14Bit) | 1/4095(12Bit) |
| Integrated precision | ±1% | |
| Conversion speed | 2ms per channel | 2ms per channel |
| Module power supply | DC24V±10%,150mA | |
| Installation | Fixed with M3 screws or directly installed on orbit of DIN46277 (Width: 35mm) | |

3-2. Terminal description

Terminal arrangement



Terminal signal

| Name | Function |
|-----------------|---|
| Indicator light | PWR The indicator lights up when the module has a power supply. |
| | COM When the module port communicates normally, the indicator lights on. |
| | ERR When there is an error in the module, the indicator is always on or flickering (red). When the ERR LED is always on, it indicates that the module has serious application errors and can not be used. It is necessary to adjust the mode of use and switch the PLC to STOP state. When the ERR LED flickers, there are application errors, abnormal work and abnormal data in the module, but the PLC is still RUN. |
| Terminal | L+ Module 24V power supply input + |
| | M Module 24V power supply input - |
| | C0 VI0, AI0 input ground |
| | VI0 Channel 1 AD voltage input |
| | AI0 Channel 1 AD current input |

| | |
|-----|-----------------------------|
| C1 | VI1, AI1 input ground |
| VI1 | Channel 2 AD voltage input |
| AI1 | Channel 2 AD current input |
| C2 | VI2, AI2 input ground |
| VI2 | Channel 3 AD voltage input |
| AI2 | Channel 3 AD current input |
| C3 | VI3, AI3 input ground |
| VI3 | Channel 4 AD voltage input |
| AI3 | Channel 4 AD current input |
| C0 | VO0, AO0 output ground |
| VO0 | Channel 1 DA voltage output |
| AO0 | Channel 1 DA current output |
| C1 | VO1, AO1 output ground |
| VO1 | Channel 2 DA voltage output |
| AO1 | Channel 2 DA current output |

Wiring head specification

When wiring the module, its wiring head should meet the following requirements:

- (1) The stripping length is 9 mm;
- (2) Flexible wires with bare tubular ends are 0.25-1.5 square.
- (3) Flexible wires with tubular pre-insulated end is 0.25-0.5 square.

3-3. I/O address

XL series analog module does not occupy I/O unit, the converted value is directly sent to the PLC register, the corresponding channel definition number of the PLC register is as follows:

Module 1 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10000 | Y10000 |
| 1CH | ID10001 | Y10001 |
| 2CH | ID10002 | Y10002 |
| 3CH | ID10003 | Y10003 |
| Channel | DA signal | |
| 0CH | QD10000 | Y10004 |
| 1CH | QD10001 | Y10005 |

Module 2 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10100 | Y10100 |
| 1CH | ID10101 | Y10101 |
| 2CH | ID10102 | Y10102 |
| 3CH | ID10103 | Y10103 |
| Channel | DA signal | |
| 0CH | QD10100 | Y10104 |
| 1CH | QD10101 | Y10105 |

Module 3 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10200 | Y10200 |
| 1CH | ID10201 | Y10201 |
| 2CH | ID10202 | Y10202 |
| 3CH | ID10203 | Y10203 |
| Channel | DA signal | |
| 0CH | QD10200 | Y10204 |
| 1CH | QD10201 | Y10205 |

Module 4 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10300 | Y10300 |
| 1CH | ID10301 | Y10301 |
| 2CH | ID10302 | Y10302 |
| 3CH | ID10303 | Y10303 |
| Channel | DA signal | |
| 0CH | QD10300 | Y10304 |
| 1CH | QD10301 | Y10305 |

Module 5 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10400 | Y10400 |
| 1CH | ID10401 | Y10401 |

| | | |
|---------|-----------|--------|
| 2CH | ID10402 | Y10402 |
| 3CH | ID10403 | Y10403 |
| Channel | DA signal | |
| 0CH | QD10400 | Y10404 |
| 1CH | QD10401 | Y10405 |

Module 6 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10500 | Y10500 |
| 1CH | ID10501 | Y10501 |
| 2CH | ID10502 | Y10502 |
| 3CH | ID10503 | Y10503 |
| Channel | DA signal | |
| 0CH | QD10500 | Y10504 |
| 1CH | QD10501 | Y10505 |

Module 7 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10600 | Y10600 |
| 1CH | ID10601 | Y10601 |
| 2CH | ID10602 | Y10602 |
| 3CH | ID10603 | Y10603 |
| Channel | DA signal | |
| 0CH | QD10600 | Y10604 |
| 1CH | QD10601 | Y10605 |

Module 8 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10700 | Y10700 |
| 1CH | ID10701 | Y10701 |
| 2CH | ID10702 | Y10702 |
| 3CH | ID10703 | Y10703 |
| Channel | DA signal | |
| 0CH | QD10700 | Y10704 |
| 1CH | QD10701 | Y10705 |

Module 9 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10800 | Y11000 |
| 1CH | ID10801 | Y11001 |
| 2CH | ID10802 | Y11002 |
| 3CH | ID10803 | Y11003 |
| Channel | DA signal | |
| 0CH | QD10800 | Y11004 |
| 1CH | QD10801 | Y11005 |

Module 10 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10900 | Y11100 |
| 1CH | ID10901 | Y11101 |
| 2CH | ID10902 | Y11102 |
| 3CH | ID10903 | Y11103 |
| Channel | DA signal | |
| 0CH | QD10900 | Y11104 |
| 1CH | QD10901 | Y11105 |

Module 11 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID11000 | Y11200 |
| 1CH | ID11001 | Y11201 |
| 2CH | ID11002 | Y11202 |
| 3CH | ID11003 | Y11203 |
| Channel | DA signal | |
| 0CH | QD11000 | Y11204 |
| 1CH | QD11001 | Y11205 |

Module 12 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID11100 | Y11300 |
| 1CH | ID11101 | Y11301 |

| | | |
|---------|-----------|--------|
| 2CH | ID11102 | Y11302 |
| 3CH | ID11103 | Y11303 |
| Channel | DA signal | |
| 0CH | QD11100 | Y11304 |
| 1CH | QD11101 | Y11305 |

Module 13 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID11200 | Y11400 |
| 1CH | ID11201 | Y11401 |
| 2CH | ID11202 | Y11402 |
| 3CH | ID11203 | Y11403 |
| Channel | DA signal | |
| 0CH | QD11200 | Y11404 |
| 1CH | QD11201 | Y11405 |

Module 14 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID11300 | Y11500 |
| 1CH | ID11301 | Y11501 |
| 2CH | ID11302 | Y11502 |
| 3CH | ID11303 | Y11503 |
| Channel | DA signal | |
| 0CH | QD11300 | Y11504 |
| 1CH | QD11301 | Y11505 |

Module 15 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID11400 | Y11600 |
| 1CH | ID11401 | Y11601 |
| 2CH | ID11402 | Y11602 |
| 3CH | ID11403 | Y11603 |
| Channel | DA signal | |
| 0CH | QD11400 | Y11604 |
| 1CH | QD11401 | Y11605 |

Module 16 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID11500 | Y11700 |
| 1CH | ID11501 | Y11701 |
| 2CH | ID11502 | Y11702 |
| 3CH | ID11503 | Y11703 |
| Channel | DA signal | |
| 0CH | QD11500 | Y11704 |
| 1CH | QD11501 | Y11705 |

Note:

- (1) Banning unused channels can improve the scanning speed of input/output.
- (2) When the input enable switch is turned off during operation, the corresponding input channel will not collect data. (Data display is 0)
- (3) When the enable switch of output is turned off during operation, the corresponding output channel keeps the original data unchanged.

3-4. Working mode settings

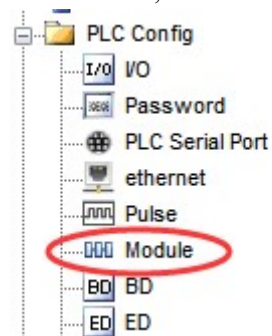
There are two ways to set the working mode (the effect of these two ways is equivalent):

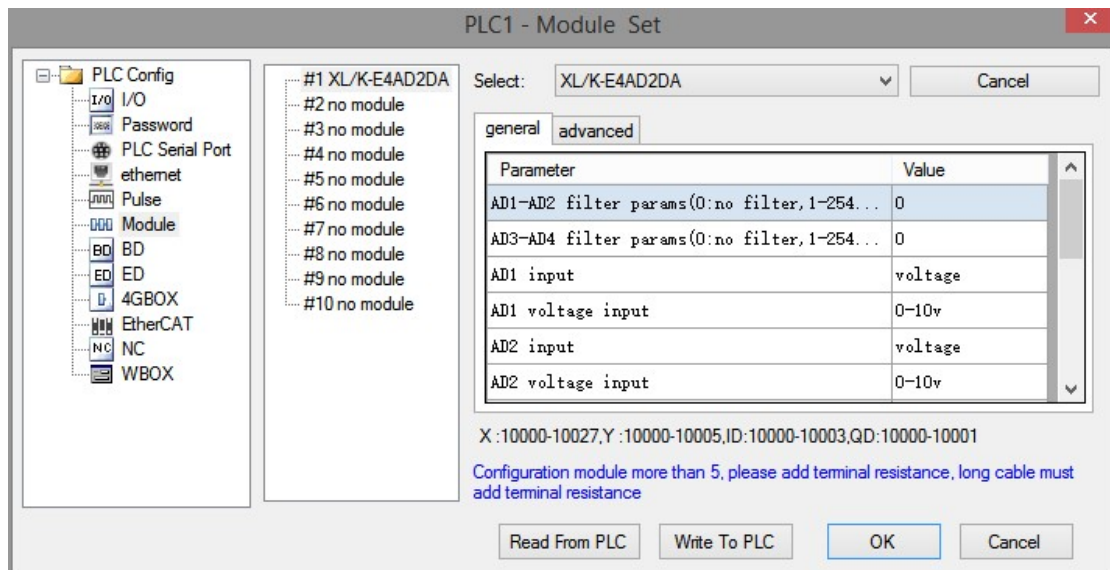
- (1) Configuration through the software
- (2) Setting up by Flash Register

Set through the software

Please use XDPpro v3.5.1 or higher version software to configure the module.

Open the software, click module in the left menu,





Choose the module type, and set each channel's parameters in the above window. Then click write to PLC, cut the power supply and power on again to make the settings effective.

Note: The first-order low-pass filtering method weighs this time sampling value and the output value of the last filtering to get the effective filtering value; the filter coefficient is set by the user to 0-254, the smaller the value, the more stable the data, but may lead to data lag; therefore, when set to 1, the filtering effect is strongest and the data is the most stable; when set to 254, the filtering effect is the weakest; default is 0 (no filtering).

Set by Flash register

The input and output channels of the expansion module can be selected in two modes: voltage and current. Current is 0-20mA, 4-20mA, and -20-20mA. Voltage is 0-5V, 0-10V, -5-5V and -10-10V. It is set by special FLASH data register SFD in PLC. As follows:

| Module no. | SFD register | Module no. | SFD register |
|------------|---------------|------------|---------------|
| #1 | SFD350~SFD359 | #9 | SFD430~SFD439 |
| #2 | SFD360~SFD369 | #10 | SFD440~SFD449 |
| #3 | SFD370~SFD379 | #11 | SFD450~SFD459 |
| #4 | SFD380~SFD389 | #12 | SFD460~SFD469 |
| #5 | SFD390~SFD399 | #13 | SFD470~SFD479 |
| #6 | SFD400~SFD409 | #14 | SFD480~SFD489 |
| #7 | SFD410~SFD419 | #15 | SFD490~SFD499 |
| #8 | SFD420~SFD429 | #16 | SFD500~SFD509 |

Note: As shown above, each register sets four-channel modes. Each register has 16 bits. From low to high, each four bit will set four-channel modes in turn.

SFD bit definition

Take the first module as an example to illustrate how to set it up.

| | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | NOTE |
|----------------------|---|---|---|------|------|---|---|------|--|
| Byte0 | AD channel 1, channel 2 filtering parameter | | | | | | | | AD filtering parameter |
| Byte1 | AD channel 3, channel 4 filtering parameter | | | | | | | | |
| Byte2 | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | Set the AD and DA module input range, Byte2 low 4-bit set |
| | AD2 | | | | AD1 | | | | |
| | - | 000: 0~10V 001: 0~5V 100: -10~10V 101: -5~5V | 010: 0~20mA 011: 4~20mA 110: -20~20mA | | - | 000: 0~10V 001: 0~5V 100: -10~10V 101: -5~5V | 010: 0~20mA 011: 4~20mA 110: -20~20mA | | AD channel 1, high 4-bit set AD channel 2. Byte3 low 4-bit set AD channel 3, high 4-bit set AD channel 4. Byte4 low 4-bit set DA channel 1, High 4-bit set DA channel 2. |
| Byte3 | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | |
| | AD4 | | | | AD3 | | | | |
| | - | 000: 0~10V 001: 0~5V 100: -10~10V 101: -5~5V | 010: 0~20mA 011: 4~20mA 110: -20~20mA | | - | 000: 0~10V 001: 0~5V 100: -10~10V 101: -5~5V | 010: 0~20mA 011: 4~20mA 110: -20~20mA | | |
| Byte4 | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | Set the AD and DA module input range, Byte2 low 4-bit set |
| | DA2 | | | | DA1 | | | | |
| | - | 000: 0~10V 001: 0~5V 100: -10~10V 101: -5~5V | 010: 0~20mA 011: 4~20mA | | - | 000: 0~10V 001: 0~5V 100: -10~10V 101: -5~5V | 010: 0~20mA 011: 4~20mA | | |
| Byte5 ~ Byte19 | | | | | | | | | |

Example: the input channels of the first module are 0-20mA, 4-20mA, 0-10V and 0-5V respectively, the filter coefficients of the first and second channels are 254, the filter coefficients of the third and fourth channels are 100, and the output channels of the first and the zero channels are 0-10V and 0-20mA respectively.

Method 1:

You can configure it directly in the PLC software, as shown above.

Method 2:

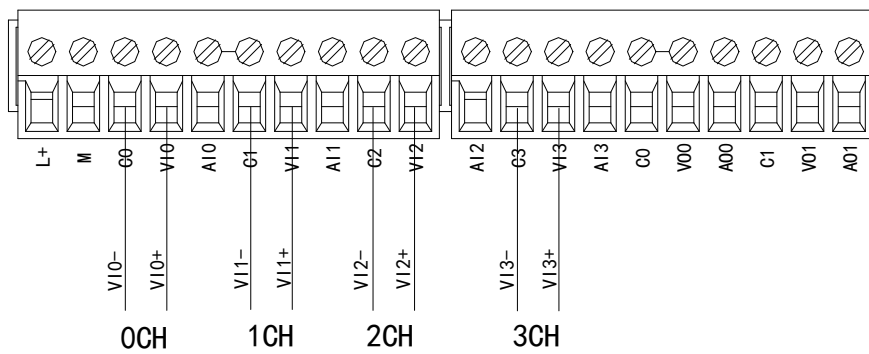
Set the SFD as follows:

SFD350=64FEH SFD351=2301H SFD352=0002H

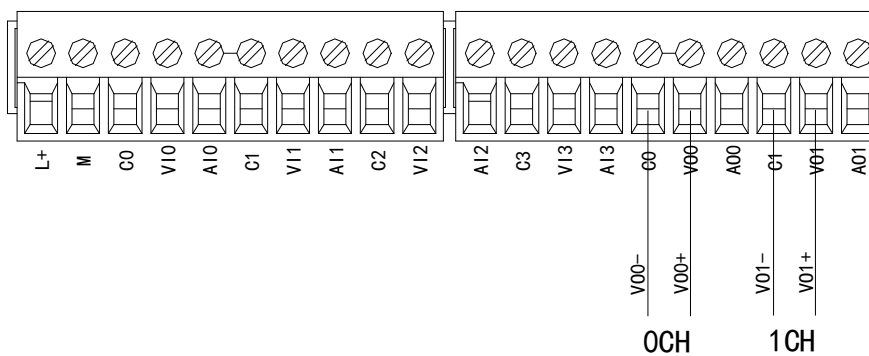
3-5. External wiring

For external connection, to avoid interference, use shielding wire and connect the ground to the single point of shielding layer.

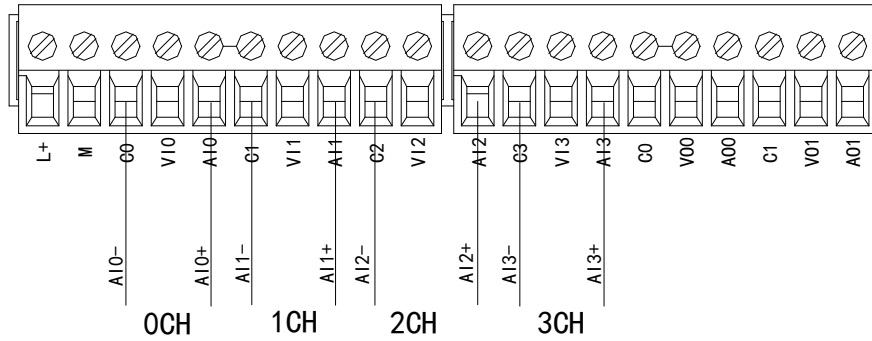
Voltage input



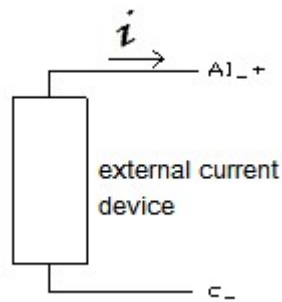
Voltage output



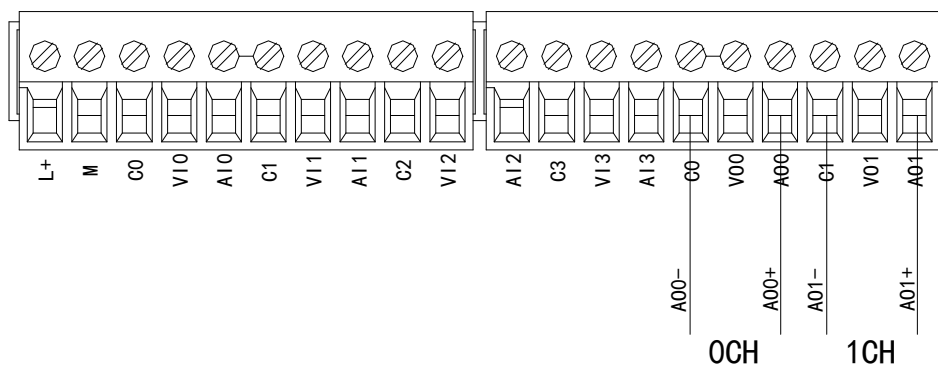
Current input



XL-E4AD2DA current input wiring:



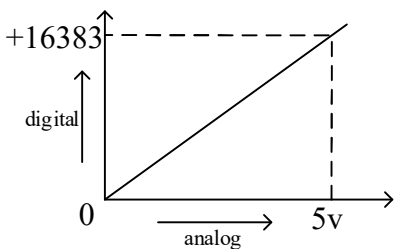
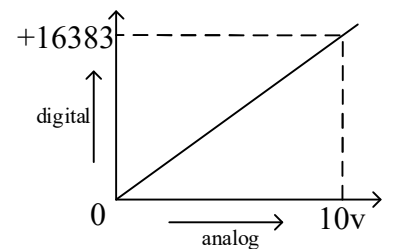
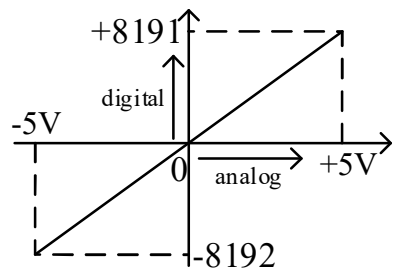
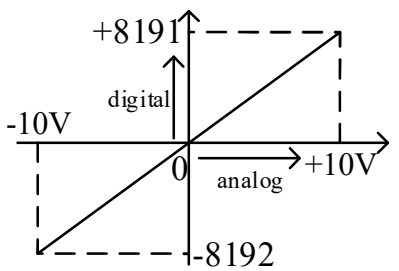
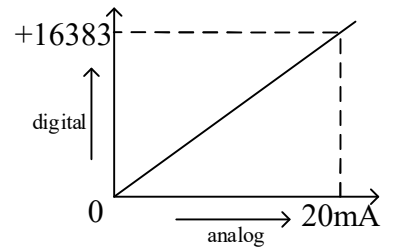
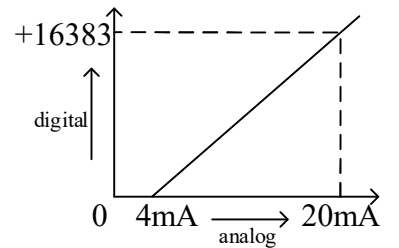
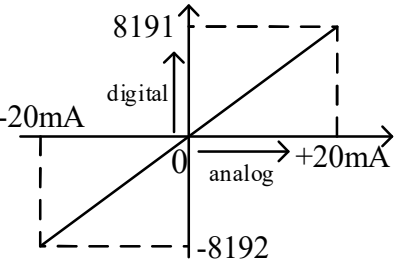
Current output



Note: current output no need DC24V power supply.

3-6. Analog digital conversion diagram

The relationship between input analog quantities and converted digital quantities is shown in the following table:

| 0~5V analog input | 0~10V analog input |
|---|--|
|  |  |
| -5~5V analog input | -10~10V analog input |
|  |  |
| 0~20mA analog input | 4~20mA analog input |
|  |  |
| -20~20mA analog input | |
|  | |

The relationship between the output digital quantity and its corresponding analog data is shown in the following table:

| 0~5V analog output | 0~10V analog output |
|----------------------|-----------------------|
| | |
| -5~5V analog output | -10~10V analog output |
| | |
| 0~20mA analog output | 4~20mA analog output |
| | |

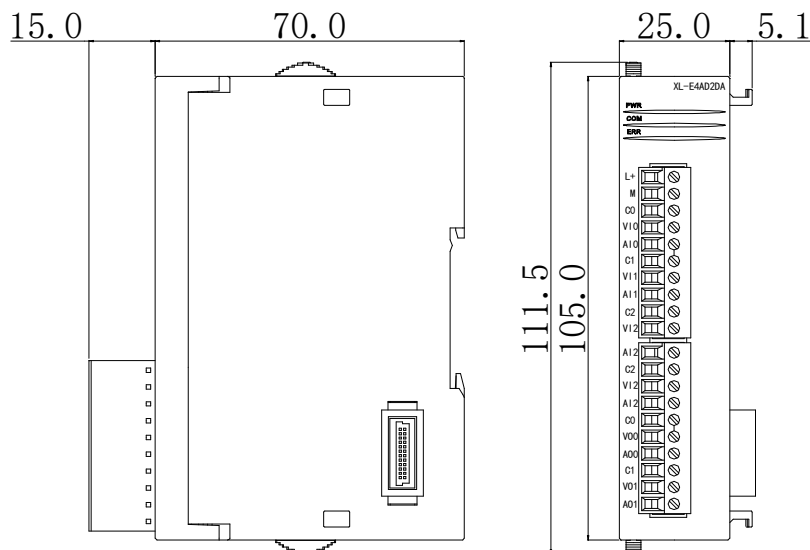
Note:

(1) When the AD voltage input is suspended, the corresponding ID register is 16383; when the AD current input is suspended, the corresponding ID register is 0.

(2) When the input data exceeds K4095, the analog data of DA conversion remains unchanged at 5V, 10V or 20mA.

3-7. Dimension

(Unit: mm)



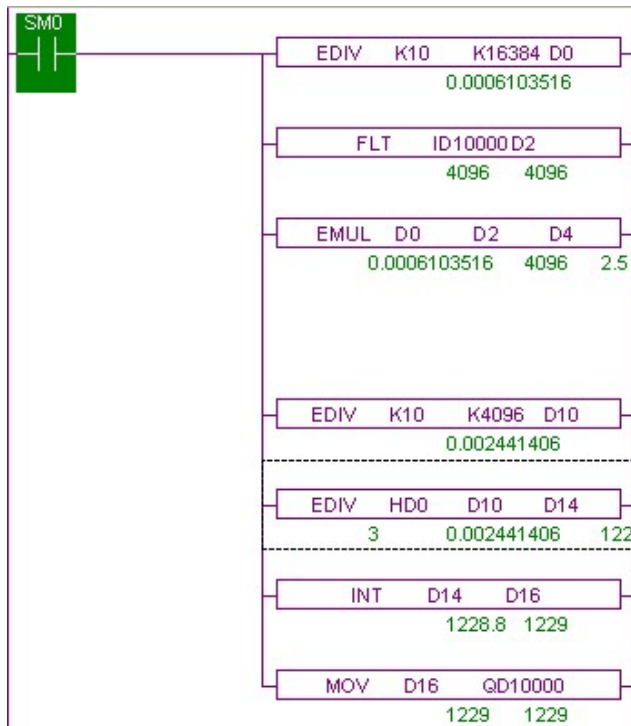
3-8. Application

Example: The output signal of one-channel pressure sensor needs to be collected (pressure sensor performance parameters: detection pressure range 0Mp~10Mp, output analog signal 4~20mA), and output one-channel 0V~10V voltage signal to frequency converter.

Analysis: As the pressure detection range of pressure sensor is 0Mp~10Mp, the analog output is 4~20mA, and the digital conversion range of expansion module is 0~16383, we can skip the analog amount of 4~20mA in the intermediate conversion process, which directly means that the pressure detection range is 0~16383 in the corresponding digital range of 0Mp~10Mp; $10\text{Mp}/16384=0.0006103515$ is pressure corresponding to each digital number 1. The real-time pressure of the current pressure sensor can be calculated by multiplying the real-time value collected in the ID register of the expansion module by 0.0006103515. For example, the ID register is 4096, and the corresponding pressure is 2.5Mp.

Similarly, the range of the set number in the extended module register QD is 0-4095 corresponding to the output voltage signal 0V-10V, $10\text{V}/4096=0.0024414$, which indicates the corresponding output voltage value for each set number in the extended module register QD; for example, it is now necessary to output 3V voltage value, $3\text{V}/0.0024414=1229$, and send the calculated value to the extended module register QD.

Note: Please use floating-point number to calculate, otherwise it will affect the accuracy of calculation and even can not be calculated!



Explanation:

SM0 is a constant ON coil and has been in ON state during the operation of PLC.

The PLC starts to run. The analog acquisition first calculates the pressure value corresponding to each digit 1 collected by the expansion module, and then converts the digital quantity (integer) collected in the ID10000 register into floating-point numbers. So as long as the real-time value collected in the expansion module ID10000 register is multiplied by the pressure value corresponding to each digit 1 collected by the expansion module, the real-time pressure values are calculated.

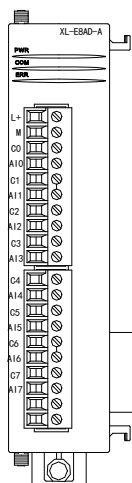
Similarly, the analog output first calculates the voltage value corresponding to each digit 1 collected by the expansion module, divides the set target voltage value by the voltage value corresponding to each digit 1 collected by the expansion module, and then obtains the required number (floating point number). As the QD10000 register can only store integers, it is necessary to convert the floating point number to integer and transmit to QD10000.

4. Analog input module XL-E8AD-A

This chapter mainly introduces XL-E8AD-A module specifications, terminal instructions, input definition number allocation, working mode settings, external connections, analog-to-digital conversion diagrams, appearance size diagrams and related programming examples.

4-1. Module features and specifications

XL-E8AD-A analog input module converts 8 analog current input values into digital values, and transmits them to the main unit of PLC, and interacts with the main unit of PLC in real time.



Module features

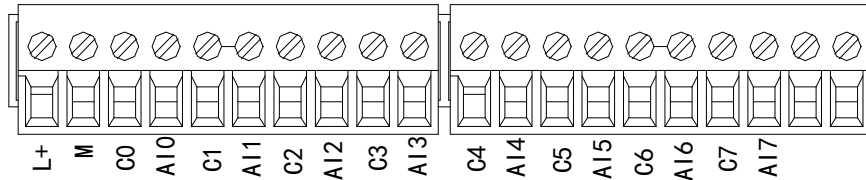
- 8-channel analog input: current input.
- 14-bit high-precision analog input.
- As an expansion module of the XL series, XL3 can connect up to 10 modules, XL5/XL5E/XL5N/XL5H/XLME/XLH/XSLH can expand 16 modules, and XL1 does not support expansion modules.

Module specification

| Item | Analog input |
|----------------------|--|
| | Current input |
| Analog input range | 0~20mA, 4~20mA, -20~20mA |
| Max input range | -40~40mA |
| Digital output range | 14 bits binary data (0~16383 or -8192~8191) |
| Resolution | 1/16383 (14Bit) |
| Integrated precision | 1% |
| Conversion speed | 2ms/1 channel |
| Module power supply | DC24V±10%, 150mA |
| Installation | Fixed with M3 screws or directly installed on rail of DIN46277 (Width: 35mm) |

4-2. Terminal descriptions

Terminal arrangement



Terminal signal

| Name | | Function |
|-----------------|----------------------------|---|
| Indicator light | PWR | The indicator lights up when the module has a power supply. |
| | COM | When the module port communicates normally, the indicator lights on. |
| | ERR | When there is an error in the module, the indicator is always on or flickering (red). When the ERR LED is always on, it indicates that the module has serious application errors and can not be used. It is necessary to adjust the mode of use and switch the PLC to STOP state. When the ERR LED flickers, there are application errors, abnormal work and abnormal data in the module, but the PLC is still RUN. |
| Terminal | L+ | Module 24V power supply input + |
| | M | Module 24V power supply input - |
| | C0 | AI0 output ground |
| | AI0 | Channel 1 AD current input |
| | C1 | AI1 output ground |
| | AI1 | Channel 2 AD current input |
| | C2 | AI2 output ground |
| | AI2 | Channel 3 AD current input |
| | C3 | AI3 output ground |
| | AI3 | Channel 4 AD current input |
| | C4 | AI4 output ground |
| | AI4 | Channel 5 AD current input |
| | C5 | AI5 output ground |
| AI5 | Channel 6 AD current input | |

| | |
|-----|----------------------------|
| C6 | AI6 output ground |
| AI6 | Channel 7 AD current input |
| C7 | AI7 output ground |
| AI7 | Channel 8 AD current input |

Wiring head specification

When wiring the module, its wiring head should meet the following requirements:

- (1) The stripping length is 9 mm;
- (2) Flexible wires with bare tubular ends are 0.25-1.5 square.
- (3) Flexible wires with tubular pre-insulated end is 0.25-0.5 square.

4-3. I/O address

XL series analog module does not occupy I/O unit, the converted value is directly sent to the PLC register, the corresponding channel definition number of the PLC register is as follows:

Module 1 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10000 | Y10000 |
| 1CH | ID10001 | Y10001 |
| 2CH | ID10002 | Y10002 |
| 3CH | ID10003 | Y10003 |
| 4CH | ID10004 | Y10004 |
| 5CH | ID10005 | Y10005 |
| 6CH | ID10006 | Y10006 |
| 7CH | ID10007 | Y10007 |

Module 2 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10100 | Y10100 |
| 1CH | ID10101 | Y10101 |
| 2CH | ID10102 | Y10102 |
| 3CH | ID10103 | Y10103 |
| 4CH | ID10104 | Y10104 |
| 5CH | ID10105 | Y10105 |

| | | |
|-----|---------|--------|
| 6CH | ID10106 | Y10106 |
| 7CH | ID10107 | Y10107 |

Module 3 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10200 | Y10200 |
| 1CH | ID10201 | Y10201 |
| 2CH | ID10202 | Y10202 |
| 3CH | ID10203 | Y10203 |
| 4CH | ID10204 | Y10204 |
| 5CH | ID10205 | Y10205 |
| 6CH | ID10206 | Y10206 |
| 7CH | ID10207 | Y10207 |

Module 4 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10300 | Y10300 |
| 1CH | ID10301 | Y10301 |
| 2CH | ID10302 | Y10302 |
| 3CH | ID10303 | Y10303 |
| 4CH | ID10304 | Y10304 |
| 5CH | ID10305 | Y10305 |
| 6CH | ID10306 | Y10306 |
| 7CH | ID10307 | Y10307 |

Module 5 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10400 | Y10400 |
| 1CH | ID10401 | Y10401 |
| 2CH | ID10402 | Y10402 |
| 3CH | ID10403 | Y10403 |
| 4CH | ID10404 | Y10404 |
| 5CH | ID10405 | Y10405 |
| 6CH | ID10406 | Y10406 |
| 7CH | ID10407 | Y10407 |

Module 6 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10500 | Y10500 |
| 1CH | ID10501 | Y10501 |
| 2CH | ID10502 | Y10502 |
| 3CH | ID10503 | Y10503 |
| 4CH | ID10504 | Y10504 |
| 5CH | ID10505 | Y10505 |
| 6CH | ID10506 | Y10506 |
| 7CH | ID10507 | Y10507 |

Module 7 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10600 | Y10600 |
| 1CH | ID10601 | Y10601 |
| 2CH | ID10602 | Y10602 |
| 3CH | ID10603 | Y10603 |
| 4CH | ID10604 | Y10604 |
| 5CH | ID10605 | Y10605 |
| 6CH | ID10606 | Y10606 |
| 7CH | ID10607 | Y10607 |

Module 8 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10700 | Y10700 |
| 1CH | ID10701 | Y10701 |
| 2CH | ID10702 | Y10702 |
| 3CH | ID10703 | Y10703 |
| 4CH | ID10704 | Y10704 |
| 5CH | ID10705 | Y10705 |
| 6CH | ID10706 | Y10706 |
| 7CH | ID10707 | Y10707 |

Module 9 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10800 | Y11000 |
| 1CH | ID10801 | Y11001 |
| 2CH | ID10802 | Y11002 |
| 3CH | ID10803 | Y11003 |
| 4CH | ID10804 | Y11004 |
| 5CH | ID10805 | Y11005 |
| 6CH | ID10806 | Y11006 |
| 7CH | ID10807 | Y11007 |

Module 10 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10900 | Y11100 |
| 1CH | ID10901 | Y11101 |
| 2CH | ID10902 | Y11102 |
| 3CH | ID10903 | Y11103 |
| 4CH | ID10904 | Y11104 |
| 5CH | ID10905 | Y11105 |
| 6CH | ID10906 | Y11106 |
| 7CH | ID10907 | Y11107 |

Module 11 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID11000 | Y11200 |
| 1CH | ID11001 | Y11201 |
| 2CH | ID11002 | Y11202 |
| 3CH | ID11003 | Y11203 |
| 4CH | ID11004 | Y11204 |
| 5CH | ID11005 | Y11205 |
| 6CH | ID11006 | Y11206 |
| 7CH | ID11007 | Y11207 |

Module 12 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID11100 | Y11300 |
| 1CH | ID11101 | Y11301 |
| 2CH | ID11102 | Y11302 |
| 3CH | ID11103 | Y11303 |
| 4CH | ID11104 | Y11304 |
| 5CH | ID11105 | Y11305 |
| 6CH | ID11106 | Y11306 |
| 7CH | ID11107 | Y11307 |

Module 13 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID11200 | Y11400 |
| 1CH | ID11201 | Y11401 |
| 2CH | ID11202 | Y11402 |
| 3CH | ID11203 | Y11403 |
| 4CH | ID11204 | Y11404 |
| 5CH | ID11205 | Y11405 |
| 6CH | ID11206 | Y11406 |
| 7CH | ID11207 | Y11407 |

Module 14 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID11300 | Y11500 |
| 1CH | ID11301 | Y11501 |
| 2CH | ID11302 | Y11502 |
| 3CH | ID11303 | Y11503 |
| 4CH | ID11304 | Y11504 |
| 5CH | ID11305 | Y11505 |
| 6CH | ID11306 | Y11506 |
| 7CH | ID11307 | Y11507 |

Module 15 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID11400 | Y11600 |
| 1CH | ID11401 | Y11601 |
| 2CH | ID11402 | Y11602 |
| 3CH | ID11403 | Y11603 |
| 4CH | ID11404 | Y11604 |
| 5CH | ID11405 | Y11605 |
| 6CH | ID11406 | Y11606 |
| 7CH | ID11407 | Y11607 |

Module 16 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID11500 | Y11700 |
| 1CH | ID11501 | Y11701 |
| 2CH | ID11502 | Y11702 |
| 3CH | ID11503 | Y11703 |
| 4CH | ID11504 | Y11704 |
| 5CH | ID11505 | Y11705 |
| 6CH | ID11506 | Y11706 |
| 7CH | ID11507 | Y11707 |

Note:

- (1) Banning unused channels can improve the scanning speed of input/output.
- (2) When the input enabling switch is turned off during operation, the corresponding input channel will not collect data. (Data display is 0)

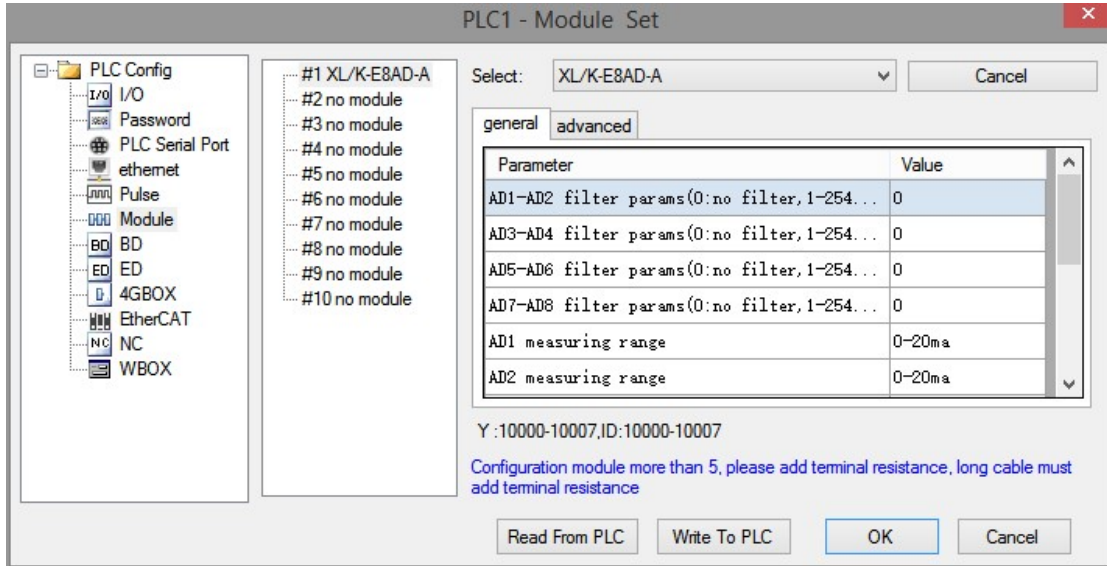
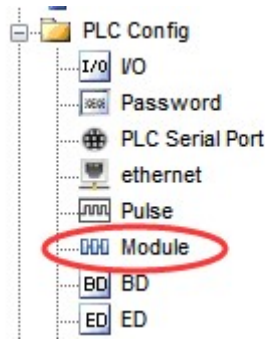
4-4. Working mode settings

There are two ways to set the working mode (the effect of these two ways is equivalent):

- (1) Configuration through the software
- (2) Setting up by Flash Register

Set through the software

Please use XDPpro v3.5.1 or higher version software to configure the module.
Open the software, click module in the left menu,



Choose the module type, and set each channel's parameters in the above window. Then click write to PLC, cut the power supply and power on again to make the settings effective.

Note: The first-order low-pass filtering method weighs this time sampling value and the output value of the last filtering to get the effective filtering value; the filter coefficient is set by the user to 0-254, the smaller the value, the more stable the data, but may lead to data lag; therefore, when set to 1, the filtering effect is strongest and the data is the most stable; when set to 254, the filtering effect is the weakest; default is 0 (no filtering).

Set by Flash register

The input channel of the extended module is current mode, with 0-20mA, 4-20mA and -20-20mA optional. It is set by special FLASH data register SFD in PLC. As follows:

| Module no. | SFD register | Module no. | SFD register |
|------------|---------------|------------|---------------|
| #1 | SFD350~SFD359 | #9 | SFD430~SFD439 |
| #2 | SFD360~SFD369 | #10 | SFD440~SFD449 |
| #3 | SFD370~SFD379 | #11 | SFD450~SFD459 |
| #4 | SFD380~SFD389 | #12 | SFD460~SFD469 |
| #5 | SFD390~SFD399 | #13 | SFD470~SFD479 |
| #6 | SFD400~SFD409 | #14 | SFD480~SFD489 |
| #7 | SFD410~SFD419 | #15 | SFD490~SFD499 |

| | | | |
|----|---------------|-----|---------------|
| #8 | SFD420~SFD429 | #16 | SFD500~SFD509 |
|----|---------------|-----|---------------|

Note: As shown above, each register sets four-channel modes. Each register has 16 bits. From low to high, each four bit will set four-channel modes in turn.

| |
|---------------------------|
| SFD bit definition |
|---------------------------|

| | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | NOTE |
|------------------|---|------|------|----------------|--------------|------|------|------|--|
| Byte0 | AD channel 2, channel 1 filtering parameter | | | | | | | | AD filtering parameter |
| Byte1 | AD channel 4, channel 3 filtering parameter | | | | | | | | |
| Byte2 | AD channel 6, channel 5 filtering parameter | | | | | | | | |
| Byte3 | AD channel 8, channel 7 filtering parameter | | | | | | | | |
| Byte4 | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | Set the AD module input range, Byte4 low 4-bit set AD channel1, high 4-bit set AD channel2. Byte5 low 4-bit set AD channel3, high 4-bit set AD channel4, Byte6 low 4-bit set AD channel5, high 4-bit set AD channel6, Byte7 low 4-bit set AD channel7, high 4-bit set AD channel8. |
| | AD2 | | | | AD1 | | | | |
| | 1000: 0~20mA | | | | 1000: 0~20mA | | | | |
| | 1001: 4~20mA | | | | 1001: 4~20mA | | | | |
| 1010: -20~20mA | | | | 1010: -20~20mA | | | | | |
| Byte5 | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | |
| | AD4 | | | | AD3 | | | | |
| | 1000: 0~20mA | | | | 1000: 0~20mA | | | | |
| | 1001: 4~20mA | | | | 1001: 4~20mA | | | | |
| 1010: -20~20mA | | | | 1010: -20~20mA | | | | | |
| Byte6 | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | |
| | AD6 | | | | AD5 | | | | |
| | 1000: 0~20mA | | | | 1000: 0~20mA | | | | |
| | 1001: 4~20mA | | | | 1001: 4~20mA | | | | |
| 1010: -20~20mA | | | | 1010: -20~20mA | | | | | |
| Byte7 | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | |
| | AD8 | | | | AD7 | | | | |
| | 1000: 0~20mA | | | | 1000: 0~20mA | | | | |
| | 1001: 4~20mA | | | | 1001: 4~20mA | | | | |
| 1010: -20~20mA | | | | 1010: -20~20mA | | | | | |
| Byte8~ Byte19 | - | | | | | | | | |

Take the first module as an example to illustrate how to set it up.

Example: To set the working modes of input channels 1 and 0 of the first module to be 0-20 mA, input channels 3 and 2 to be 4-20 mA, input channels 5 and 4 to be 0-20 mA, input channels 7 and 6 to be -20-20 mA, filter coefficients of channels 0, 1, 2 and 3 to be 254, filter coefficients of channels 4, 5, 6 and 7 to be 100.

Method 1:

You can configure it directly in the PLC software, as shown above.

Method 2:

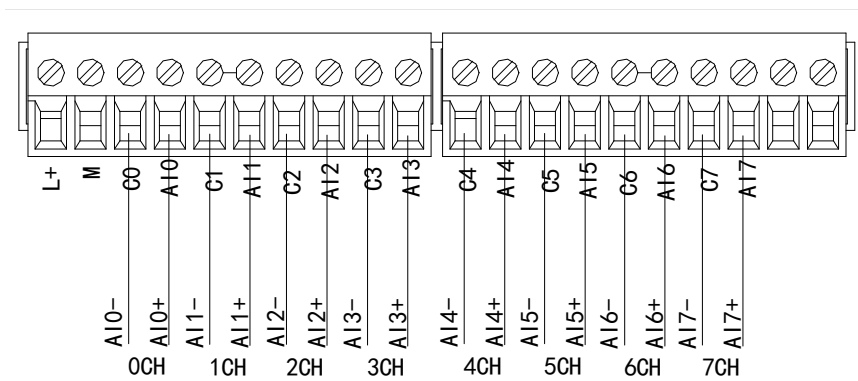
Set the SFD as follows:

SFD350=FEFEH SFD351=6464H SFD352=9988H SFD353=AA88H

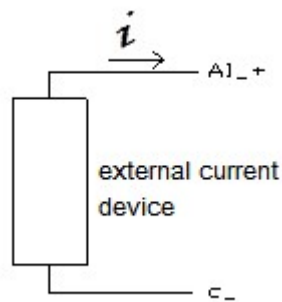
4-5. External wiring

For external connection, to avoid interference, use shielding wire and connect the ground to the single point of shielding layer.

Current input

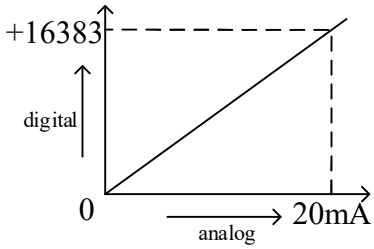
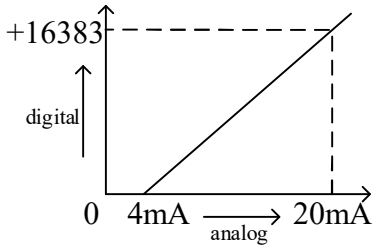
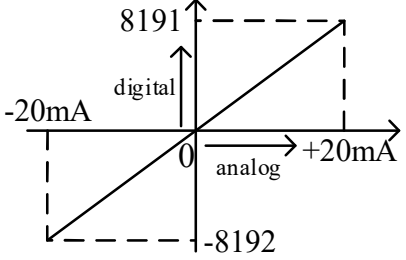


XL-E8AD-A current input wiring:



4-6. Analog digital conversion diagram

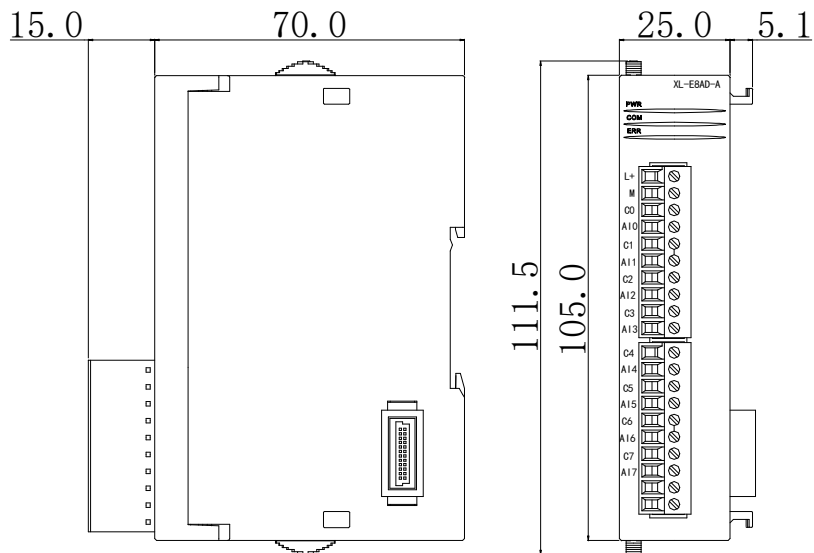
The relationship between input analog quantities and converted digital quantities is shown in the following table:

| 0~20mA analog input | 4~20mA analog input |
|--|--|
|  |  |
| -20~20mA analog input | |
|  | |

Note: When the channel enable switch is turned on and the AD current input is suspended, the ID register corresponding to the AD current input is displayed as 0. When the channel enable switch is turned off, the ID register corresponding to the AD current input is displayed as 0.

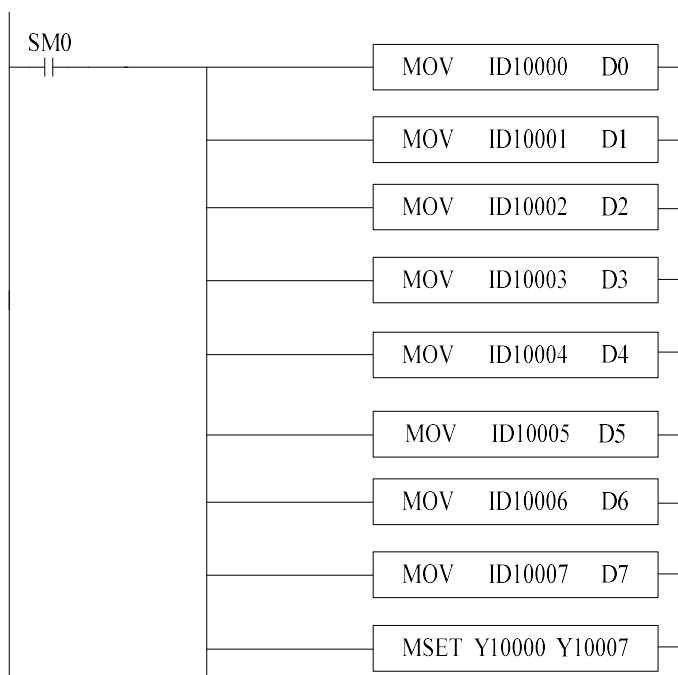
4-7. Dimension

(Unit: mm)



4-8. Application

Examples of real-time reading 8 channels of data (take Module 1 as an example)



Explain:

SM0 is a constant ON coil and has been in ON state during the operation of PLC.

The PLC starts to run, and continuously writes the data of channel 0 of the module 1 into the data register D0.

Data in channel 1 is written to data register D1;

Data in channel 2 is written to data register D2.

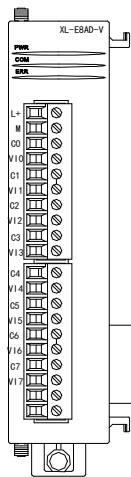
Data in channel 3 is written to data register D3.
Data in channel 4 is written to data register D4.
The data of channel 5 is written to the data register D5.
The data of channel 6 is written to the data register D6.
The data of channel 7 is written to the data register D7.
Since all channels are used, all the channel enablers are opened.

5. Analog input module XL-E8AD-V

This chapter mainly introduces XL-E8AD-V module specifications, terminal instructions, input definition number allocation, working mode settings, external connections, analog-to-digital conversion diagrams, appearance size diagrams and related programming examples.

5-1. Module features and specifications

XL-E8AD-V analog input module converts 8 analog current input values into digital values, and transmits them to the main unit of PLC, and interacts with the main unit of PLC in real time.



Module features

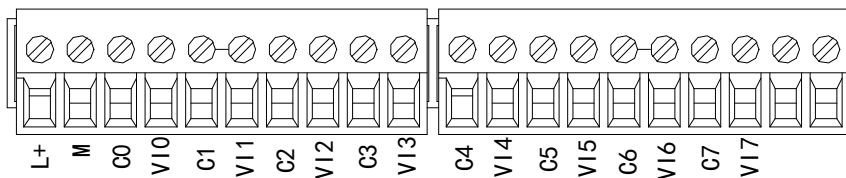
- 8-channel analog input: voltage input.
- 14-bit high-precision analog input.
- As a special functional module of the XL series, XL3 can connect up to 10 modules, XL5/XL5E/XL5N/XL5H/XLME/XLH/XSLH can expand 16 modules, and XL1 does not support expansion modules.

Module specification

| Item | Analog input |
|----------------------|--|
| | Voltage input |
| Analog input range | 0~5V, 0~10V, -5~5V, -10~10V |
| Max input range | DC±15V |
| Digital output range | 14 bits binary data (0~16383 or -8192~8191) |
| Resolution | 1/16383 (14Bit) |
| Integrated precision | 1% |
| Conversion speed | 2ms/1 channel |
| Module power supply | DC24V±10%, 150mA |
| Installation | Fixed with M3 screws or directly installed on rail of DIN46277 (Width: 35mm) |

5-2. Terminal descriptions

Terminal arrangement



Terminal signal

| Name | Function |
|-----------------|--|
| Indicator light | PWR The indicator lights up when the module has a power supply. |
| | COM When the module port communicates normally, the indicator lights on. |
| | ERR When there is an error in the module, the indicator is always on or flickering (red). When the ERR LED is always on, it indicates that the module has serious application errors and can not be used. It is necessary to adjust the mode of use and switch the PLC to STOP |

| | | |
|----------|----------------------------|---|
| | | state. When the ERR LED flickers, there are application errors, abnormal work and abnormal data in the module, but the PLC is still RUN. |
| Terminal | L+ | Module 24V power supply input + |
| | M | Module 24V power supply input - |
| | C0 | VI0 output ground |
| | VI0 | Channel 1 AD voltage input |
| | C1 | VI1 output ground |
| | VI1 | Channel 2 AD voltage input |
| | C2 | VI2 output ground |
| | VI2 | Channel 3 AD voltage input |
| | C3 | VI3 output ground |
| | VI3 | Channel 4 AD voltage input |
| | C4 | VI4 output ground |
| | VI4 | Channel 5 AD voltage input |
| | C5 | VI5 output ground |
| | VI5 | Channel 6 AD voltage input |
| | C6 | VI6 output ground |
| | VI6 | Channel 7 AD voltage input |
| C7 | VI7 output ground | |
| VI7 | Channel 8 AD voltage input | |

Wiring head specification

When wiring the module, its wiring head should meet the following requirements:

- (1) The stripping length is 9 mm;
- (2) Flexible wires with bare tubular ends are 0.25-1.5 square.
- (3) Flexible wires with tubular pre-insulated end is 0.25-0.5 square.

5-3. I/O address

XL series analog module does not occupy I/O unit, the converted value is directly sent to the PLC register, the corresponding channel definition number of the PLC register is as follows:

Module 1 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10000 | Y10000 |

| | | |
|-----|---------|--------|
| 1CH | ID10001 | Y10001 |
| 2CH | ID10002 | Y10002 |
| 3CH | ID10003 | Y10003 |
| 4CH | ID10004 | Y10004 |
| 5CH | ID10005 | Y10005 |
| 6CH | ID10006 | Y10006 |
| 7CH | ID10007 | Y10007 |

Module 2 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10100 | Y10100 |
| 1CH | ID10101 | Y10101 |
| 2CH | ID10102 | Y10102 |
| 3CH | ID10103 | Y10103 |
| 4CH | ID10104 | Y10104 |
| 5CH | ID10105 | Y10105 |
| 6CH | ID10106 | Y10106 |
| 7CH | ID10107 | Y10107 |

Module 3 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10200 | Y10200 |
| 1CH | ID10201 | Y10201 |
| 2CH | ID10202 | Y10202 |
| 3CH | ID10203 | Y10203 |
| 4CH | ID10204 | Y10204 |
| 5CH | ID10205 | Y10205 |
| 6CH | ID10206 | Y10206 |
| 7CH | ID10207 | Y10207 |

Module 4 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10300 | Y10300 |
| 1CH | ID10301 | Y10301 |
| 2CH | ID10302 | Y10302 |
| 3CH | ID10303 | Y10303 |
| 4CH | ID10304 | Y10304 |
| 5CH | ID10305 | Y10305 |

| | | |
|-----|---------|--------|
| 6CH | ID10306 | Y10306 |
| 7CH | ID10307 | Y10307 |

Module 5 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10400 | Y10400 |
| 1CH | ID10401 | Y10401 |
| 2CH | ID10402 | Y10402 |
| 3CH | ID10403 | Y10403 |
| 4CH | ID10404 | Y10404 |
| 5CH | ID10405 | Y10405 |
| 6CH | ID10406 | Y10406 |
| 7CH | ID10407 | Y10407 |

Module 6 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10500 | Y10500 |
| 1CH | ID10501 | Y10501 |
| 2CH | ID10502 | Y10502 |
| 3CH | ID10503 | Y10503 |
| 4CH | ID10504 | Y10504 |
| 5CH | ID10505 | Y10505 |
| 6CH | ID10506 | Y10506 |
| 7CH | ID10507 | Y10507 |

Module 7 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10600 | Y10600 |
| 1CH | ID10601 | Y10601 |
| 2CH | ID10602 | Y10602 |
| 3CH | ID10603 | Y10603 |
| 4CH | ID10604 | Y10604 |
| 5CH | ID10605 | Y10605 |
| 6CH | ID10606 | Y10606 |
| 7CH | ID10607 | Y10607 |

Module 8 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10700 | Y10700 |
| 1CH | ID10701 | Y10701 |
| 2CH | ID10702 | Y10702 |
| 3CH | ID10703 | Y10703 |
| 4CH | ID10704 | Y10704 |
| 5CH | ID10705 | Y10705 |
| 6CH | ID10706 | Y10706 |
| 7CH | ID10707 | Y10707 |

Module 9 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10800 | Y11000 |
| 1CH | ID10801 | Y11001 |
| 2CH | ID10802 | Y11002 |
| 3CH | ID10803 | Y11003 |
| 4CH | ID10804 | Y11004 |
| 5CH | ID10805 | Y11005 |
| 6CH | ID10806 | Y11006 |
| 7CH | ID10807 | Y11007 |

Module 10 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID10900 | Y11100 |
| 1CH | ID10901 | Y11101 |
| 2CH | ID10902 | Y11102 |
| 3CH | ID10903 | Y11103 |
| 4CH | ID10904 | Y11104 |
| 5CH | ID10905 | Y11105 |
| 6CH | ID10906 | Y11106 |
| 7CH | ID10907 | Y11107 |

Module 11 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID11000 | Y11200 |

| | | |
|-----|---------|--------|
| 1CH | ID11001 | Y11201 |
| 2CH | ID11002 | Y11202 |
| 3CH | ID11003 | Y11203 |
| 4CH | ID11004 | Y11204 |
| 5CH | ID11005 | Y11205 |
| 6CH | ID11006 | Y11206 |
| 7CH | ID11007 | Y11207 |

Module 12 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID11100 | Y11300 |
| 1CH | ID11101 | Y11301 |
| 2CH | ID11102 | Y11302 |
| 3CH | ID11103 | Y11303 |
| 4CH | ID11104 | Y11304 |
| 5CH | ID11105 | Y11305 |
| 6CH | ID11106 | Y11306 |
| 7CH | ID11107 | Y11307 |

Module 13 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID11200 | Y11400 |
| 1CH | ID11201 | Y11401 |
| 2CH | ID11202 | Y11402 |
| 3CH | ID11203 | Y11403 |
| 4CH | ID11204 | Y11404 |
| 5CH | ID11205 | Y11405 |
| 6CH | ID11206 | Y11406 |
| 7CH | ID11207 | Y11407 |

Module 14 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID11300 | Y11500 |
| 1CH | ID11301 | Y11501 |
| 2CH | ID11302 | Y11502 |
| 3CH | ID11303 | Y11503 |
| 4CH | ID11304 | Y11504 |
| 5CH | ID11305 | Y11505 |

| | | |
|-----|---------|--------|
| 6CH | ID11306 | Y11506 |
| 7CH | ID11307 | Y11507 |

Module 15 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID11400 | Y11600 |
| 1CH | ID11401 | Y11601 |
| 2CH | ID11402 | Y11602 |
| 3CH | ID11403 | Y11603 |
| 4CH | ID11404 | Y11604 |
| 5CH | ID11405 | Y11605 |
| 6CH | ID11406 | Y11606 |
| 7CH | ID11407 | Y11607 |

Module 16 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | ID11500 | Y11700 |
| 1CH | ID11501 | Y11701 |
| 2CH | ID11502 | Y11702 |
| 3CH | ID11503 | Y11703 |
| 4CH | ID11504 | Y11704 |
| 5CH | ID11505 | Y11705 |
| 6CH | ID11506 | Y11706 |
| 7CH | ID11507 | Y11707 |

Note:

- (1) Banning unused channels can improve the scanning speed of input/output.
- (2) When the input enabling switch is turned off during operation, the corresponding input channel will not collect data. (Data display is 0)

5-4. Working mode settings

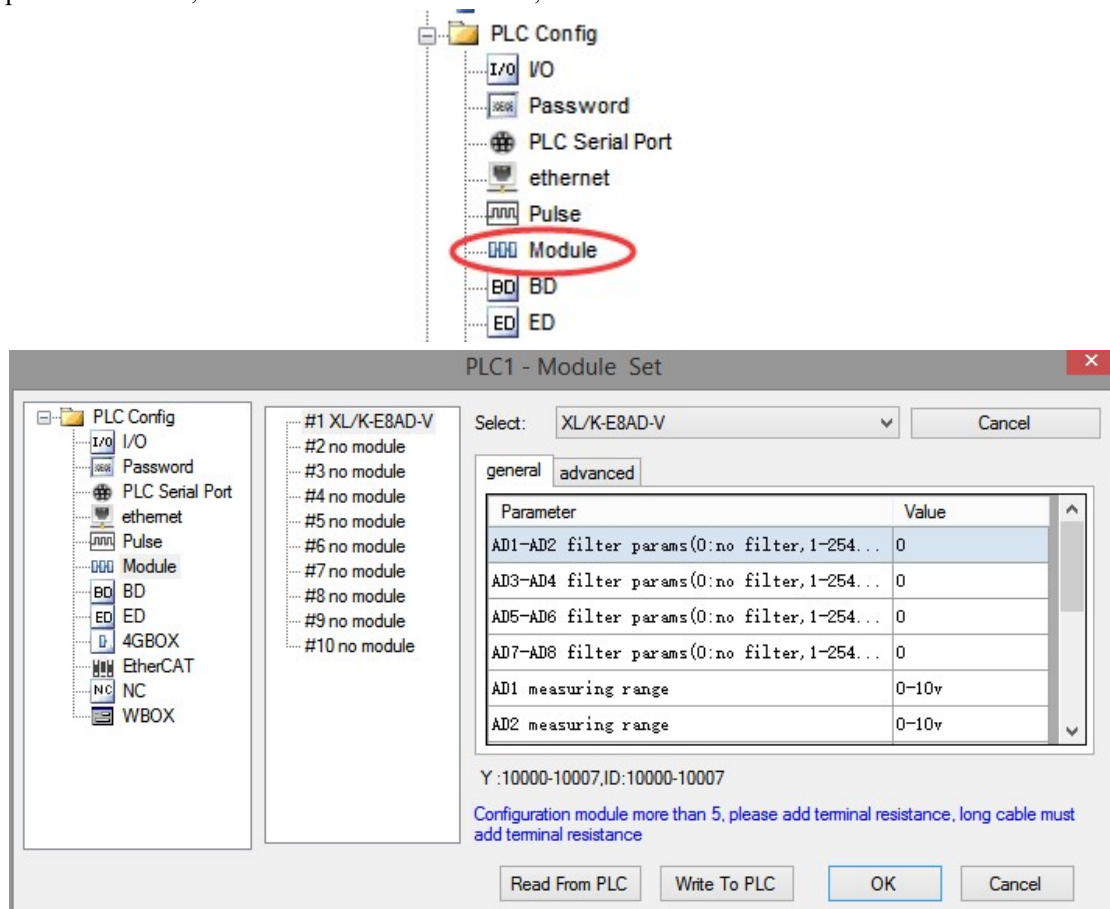
There are two ways to set the working mode (the effect of these two ways is equivalent):

- (1) Configuration through the software
- (2) Setting up by Flash Register

Set through the software

Please use XDPpro v3.5.1 or higher version software to configure the module.

Open the software, click module in the left menu,



Choose the module type, and set each channel's parameters in the above window. Then click write to PLC, cut the power supply and power on again to make the settings effective.

Note: The first-order low-pass filtering method weighs this time sampling value and the output value of the last filtering to get the effective filtering value; the filter coefficient is set by the user to 0-254, the smaller the value, the more stable the data, but may lead to data lag; therefore, when set to 1, the filtering effect is strongest and the data is the most stable; when set to 254, the filtering effect is the weakest; default is 0 (no filtering).

Set by Flash register

The input channel of the extended module is voltage mode, with 0~5V, 0~10V, -5~5V, -10~10V optional. It is set by special FLASH data register SFD in PLC. As follows:

| Module no. | SFD register | Module no. | SFD register |
|------------|---------------|------------|---------------|
| #1 | SFD350~SFD359 | #9 | SFD430~SFD439 |
| #2 | SFD360~SFD369 | #10 | SFD440~SFD449 |
| #3 | SFD370~SFD379 | #11 | SFD450~SFD459 |
| #4 | SFD380~SFD389 | #12 | SFD460~SFD469 |
| #5 | SFD390~SFD399 | #13 | SFD470~SFD479 |
| #6 | SFD400~SFD409 | #14 | SFD480~SFD489 |

| | | | |
|----|---------------|-----|---------------|
| #7 | SFD410~SFD419 | #15 | SFD490~SFD499 |
| #8 | SFD420~SFD429 | #16 | SFD500~SFD509 |

Note: As shown above, each register sets four-channel modes. Each register has 16 bits. From low to high, each four bit will set four-channel modes in turn.

| |
|---------------------------|
| SFD bit definition |
|---------------------------|

| | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | NOTE |
|------------------|---|------|------|-------------|---------------|------|------|------|--|
| Byte0 | AD channel 2, channel 1 filtering parameter | | | | | | | | AD filtering parameter |
| Byte1 | AD channel 4, channel 3 filtering parameter | | | | | | | | |
| Byte2 | AD channel 6, channel 5 filtering parameter | | | | | | | | |
| Byte3 | AD channel 8, channel 7 filtering parameter | | | | | | | | |
| Byte4 | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | Set the AD module input range, Byte4 low 4-bit set AD channel1, high 4-bit set AD channel2. Byte5 low 4-bit set AD channel3, high 4-bit set AD channel4, Byte6 low 4-bit set AD channel5, high 4-bit set AD channel6, Byte7 low 4-bit set AD channel7, high 4-bit set AD channel8. |
| | AD2 | | | | AD1 | | | | |
| | 0000: 0~10V | | | | 0000: 0~10V | | | | |
| | 0001: 0~5V | | | | 0001: 0~5V | | | | |
| | 0010: -10~10V | | | | 0010: -10~10V | | | | |
| 0011: -5~5V | | | | 0011: -5~5V | | | | | |
| Byte5 | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | |
| | AD4 | | | | AD3 | | | | |
| | 0000: 0~10V | | | | 0000: 0~10V | | | | |
| | 0001: 0~5V | | | | 0001: 0~5V | | | | |
| | 0010: -10~10V | | | | 0010: -10~10V | | | | |
| 0011: -5~5V | | | | 0011: -5~5V | | | | | |
| Byte6 | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | |
| | AD6 | | | | AD5 | | | | |
| | 0000: 0~10V | | | | 0000: 0~10V | | | | |
| | 0001: 0~5V | | | | 0001: 0~5V | | | | |
| | 0010: -10~10V | | | | 0010: -10~10V | | | | |
| 0011: -5~5V | | | | 0011: -5~5V | | | | | |
| Byte7 | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | |
| | AD8 | | | | AD7 | | | | |
| | 0000: 0~10V | | | | 0000: 0~10V | | | | |
| | 0001: 0~5V | | | | 0001: 0~5V | | | | |
| | 0010: -10~10V | | | | 0010: -10~10V | | | | |
| 0011: -5~5V | | | | 0011: -5~5V | | | | | |
| Byte8~ Byte19 | - | | | | | | | | |

Take the first module as an example to illustrate how to set it up.

Example: To set the first module's input channels 1 and 0 to 0~10V, input channels 3 and 2 to 0~5V, input channels 5 and 4 to 0~10V, input channels 7 and 6 to 0~5V, filter coefficients of channels 0, 1, 2 and 3 to 254, filter coefficients of channels 4, 5, 6 and 7 to 100.

Method 1:

You can configure it directly in the PLC software, as shown above.

Method 2:

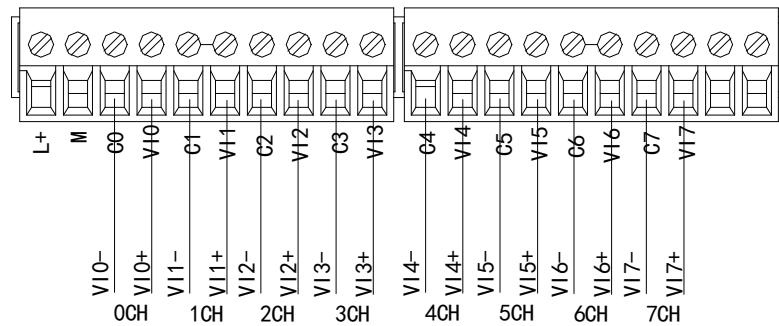
Set the SFD as follows:

SFD350=FEFEH SFD351=6464H SFD352=1100H SFD353=1100H

5-5. External wiring

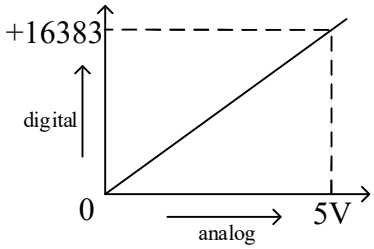
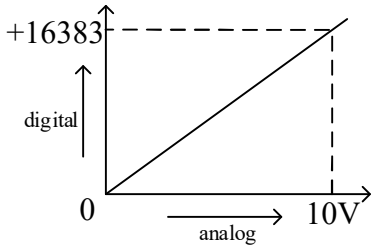
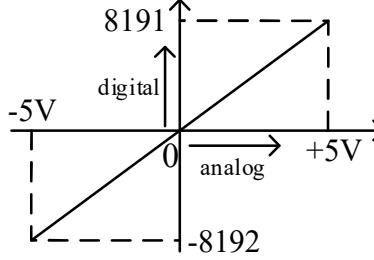
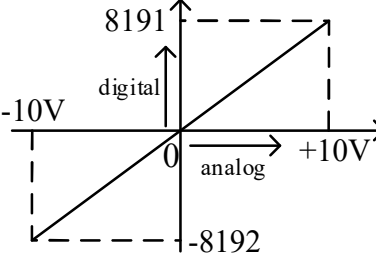
For external connection, to avoid interference, use shielding wire and connect the ground to the single point of shielding layer.

Voltage input



5-6. Analog digital conversion diagram

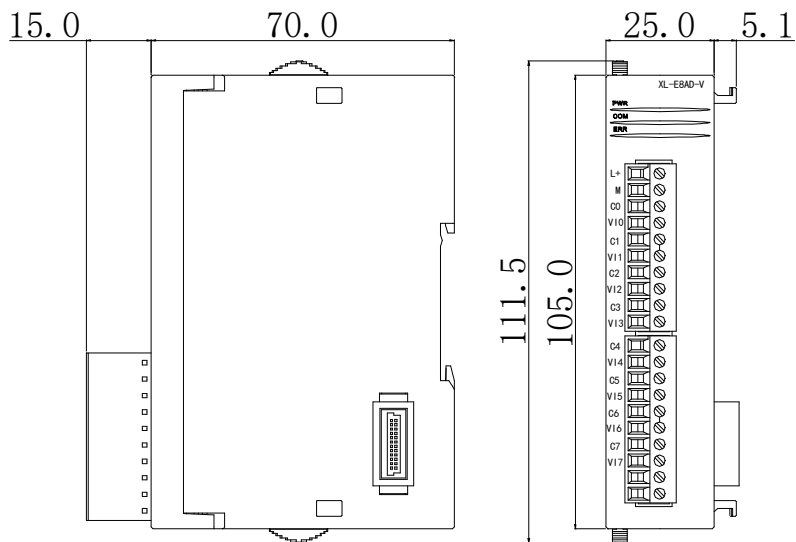
The relationship between input analog quantities and converted digital quantities is shown in the following table:

| 0~5V analog input | 0~10V analog input |
|--|---|
|  |  |
| -5~5V analog input | -10~10V analog input |
|  |  |

Note: When the channel enable switch is turned on and the AD voltage input is suspended, the corresponding ID register is displayed as 16383; When the channel enable switch is turned off, the ID register corresponding to the AD voltage input is displayed as 0.

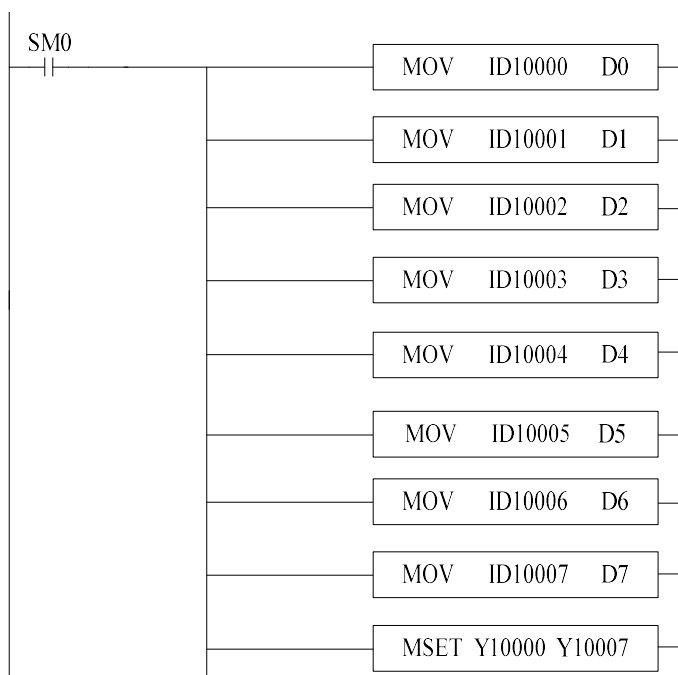
5-7. Dimension

(Unit: mm)



5-8. Application

Examples of real-time reading 8 channels of data (take Module 1 as an example)



Explain:

SM0 is a constant ON coil and has been in ON state during the operation of PLC.

The PLC starts to run, and continuously writes the data of channel 0 of the module 1 into the data register D0.

Data in channel 1 is written to data register D1;

Data in channel 2 is written to data register D2.

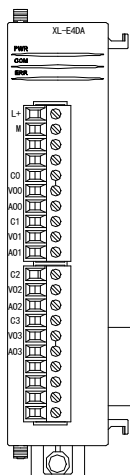
Data in channel 3 is written to data register D3.
Data in channel 4 is written to data register D4.
The data of channel 5 is written to the data register D5.
The data of channel 6 is written to the data register D6.
The data of channel 7 is written to the data register D7.
Since all channels are used, all the channel enablers are opened.

6. Analog output module XL-E4DA

This chapter mainly introduces XL-E4DA module specifications, terminal, input definition number allocation, working mode settings, external connections, analog-to-digital conversion diagrams, appearance size diagrams and related programming examples.

6-1. Module features and specifications

XL-E4DA analog output module converts four digital quantities into analog quantities, and transmits them to the main unit of PLC, and interacts with the main unit of PLC in real time.



Module features

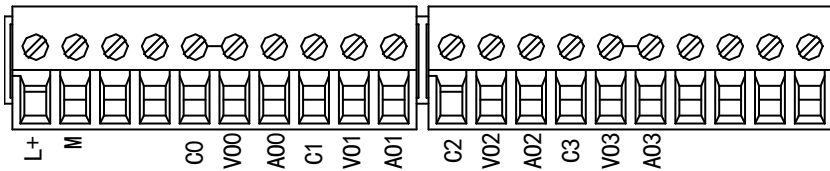
- Four-channel analog output: Voltage and current mode can be selected.
- 12-bit high-precision analog output.
- As a special functional module of the XL series, XL3 can connect up to 10 modules, XL5/XL5E/XL5N/XL5H/XLME/XLH/XSLH can expand 16 modules, and XL1 does not support expansion modules.

Module specification

| Item | Voltage output | Current output |
|---------------------|---|--|
| Analog output range | 0~5V, 0~10V, -5~5V, -10~10V (Exterior load resistance 2KΩ~1MΩ) | 0~20mA, 4~20mA (Exterior load resistance is less than 500Ω) |
| Digital input range | 12 bits binary data (0~4095 or -2048~2047) | |
| Resolution | 1/4095 (12Bit) | |
| Integrate precision | 1% | |
| Conversion speed | 2ms/1 channel | 2ms/1 channel |
| Module power supply | DC24V±10%, 150mA | |
| Installation | Fixed with M3 screws or directly installed on orbit of DIN46277 (Width: 35mm) | |

6-2. Terminal description

Terminal arrangement



Terminal signal

| Name | Function |
|-----------------|--|
| Indicator light | PWR The indicator lights up when the module has a power supply. |
| | COM When the module port communicates normally, the indicator lights on. |
| | ERR When there is an error in the module, the indicator is always on or flickering (red). When the ERR LED is always on, it indicates that the module has serious application errors and can not be used. It is necessary to adjust the mode of use and switch the PLC to STOP state. When the ERR LED flickers, there are application errors, abnormal work and abnormal data in the module, but the PLC is still RUN. |
| Terminal | L+ Module 24V power supply input + |

| | |
|-----|---------------------------------|
| M | Module 24V power supply input - |
| C0 | VO0, AO0 output ground |
| VO0 | Channel 1 DA voltage output |
| AO0 | Channel 1 DA current output |
| C1 | VO1, AO1 output ground |
| VO1 | Channel 2 DA voltage output |
| AO1 | Channel 2 DA current output |
| C2 | VO2, AO2 output ground |
| VO2 | Channel 3 DA voltage output |
| AO2 | Channel 3 DA current output |
| C3 | VO3, AO3 output ground |
| VO3 | Channel 4 DA voltage output |
| AO3 | Channel 4 DA current output |

Wiring head specification

When wiring the module, its wiring head should meet the following requirements:

- (1) The stripping length is 9 mm;
- (2) Flexible wires with bare tubular ends are 0.25-1.5 square.
- (3) Flexible wires with tubular pre-insulated end is 0.25-0.5 square.

6-3. I/O address

XL series analog module does not occupy I/O unit, the converted value is directly sent to the PLC register, the corresponding channel definition number of the PLC register is as follows:

Module 1 register address:

| Channel | DA signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | QD10000 | Y10000 |
| 1CH | QD10001 | Y10001 |
| 2CH | QD10002 | Y10002 |
| 3CH | QD10003 | Y10003 |

Module 2 register address:

| Channel | DA signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | QD10100 | Y10100 |
| 1CH | QD10101 | Y10101 |
| 2CH | QD10102 | Y10102 |
| 3CH | QD10103 | Y10103 |

Module 3 register address:

| Channel | DA signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | QD10200 | Y10200 |
| 1CH | QD10201 | Y10201 |
| 2CH | QD10202 | Y10202 |
| 3CH | QD10203 | Y10203 |

Module 4 register address:

| Channel | DA signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | QD10300 | Y10300 |
| 1CH | QD10301 | Y10301 |
| 2CH | QD10302 | Y10302 |
| 3CH | QD10303 | Y10303 |

Module 5 register address:

| Channel | DA signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | QD10400 | Y10400 |
| 1CH | QD10401 | Y10401 |
| 2CH | QD10402 | Y10402 |
| 3CH | QD10403 | Y10403 |

Module 6 register address:

| Channel | DA signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | QD10500 | Y10500 |
| 1CH | QD10501 | Y10501 |
| 2CH | QD10502 | Y10502 |

| | | |
|-----|---------|--------|
| 3CH | QD10503 | Y10503 |
|-----|---------|--------|

Module 7 register address:

| Channel | DA signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | QD10600 | Y10600 |
| 1CH | QD10601 | Y10601 |
| 2CH | QD10602 | Y10602 |
| 3CH | QD10603 | Y10603 |

Module 8 register address:

| Channel | DA signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | QD10700 | Y10700 |
| 1CH | QD10701 | Y10701 |
| 2CH | QD10702 | Y10702 |
| 3CH | QD10703 | Y10703 |

Module 9 register address:

| Channel | DA signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | QD10800 | Y11000 |
| 1CH | QD10801 | Y11001 |
| 2CH | QD10802 | Y11002 |
| 3CH | QD10803 | Y11003 |

Module 10 register address:

| Channel | DA signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | QD10900 | Y11100 |
| 1CH | QD10901 | Y11101 |
| 2CH | QD10902 | Y11102 |
| 3CH | QD10903 | Y11103 |

Module 11 register address:

| Channel | DA signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | QD11000 | Y11200 |

| | | |
|-----|---------|--------|
| 1CH | QD11001 | Y11201 |
| 2CH | QD11002 | Y11202 |
| 3CH | QD11003 | Y11203 |

Module 12 register address:

| Channel | DA signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | QD11100 | Y11300 |
| 1CH | QD11101 | Y11301 |
| 2CH | QD11102 | Y11302 |
| 3CH | QD11103 | Y11303 |

Module 13 register address:

| Channel | DA signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | QD11200 | Y11400 |
| 1CH | QD11201 | Y11401 |
| 2CH | QD11202 | Y11402 |
| 3CH | QD11203 | Y11403 |

Module 14 register address:

| Channel | DA signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | QD11300 | Y11500 |
| 1CH | QD11301 | Y11501 |
| 2CH | QD11302 | Y11502 |
| 3CH | QD11303 | Y11503 |

Module 15 register address:

| Channel | DA signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | QD11400 | Y11600 |
| 1CH | QD11401 | Y11601 |
| 2CH | QD11402 | Y11602 |
| 3CH | QD11403 | Y11603 |

Module 16 register address:

| Channel | DA signal | Channel enable switch (please turn on the switch to use this channel) |
|---------|-----------|--|
| 0CH | QD11500 | Y11700 |
| 1CH | QD11501 | Y11701 |
| 2CH | QD11502 | Y11702 |
| 3CH | QD11503 | Y11703 |

Note:

- 1) Banning unused channels can improve the scanning speed of input/output.
- 2) When the enabling switch of output is turned off during operation, the corresponding output channel keeps the original data unchanged.

6-4. Working mode settings

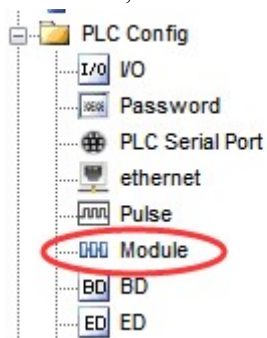
There are two ways to set the working mode (the effect of these two ways is equivalent):

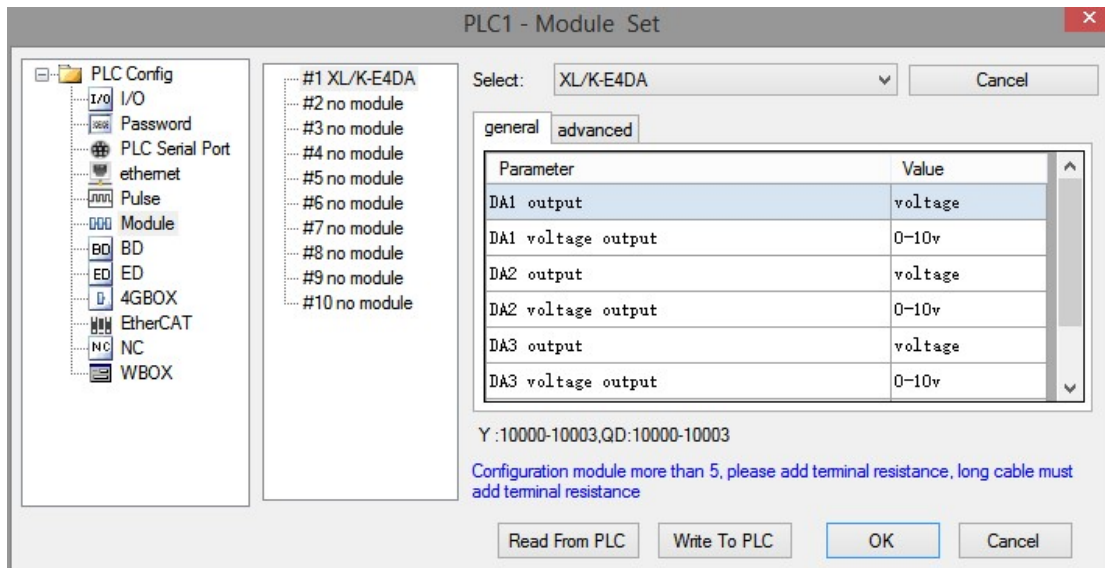
- (1) Configuration through the software
- (2) Setting up by Flash Register

Set through the software

Please use XDPpro v3.5.1 or higher version software to configure the module.

Open the software, click module in the left menu,





Choose the module type, and set each channel's parameters in the above window. Then click write to PLC, cut the power supply and power on again to make the settings effective.

Set by Flash register

The output channels of the expansion module can be selected in two modes: voltage and current. Current is 0-20mA, 4-20mA. Voltage is 0-5V, 0-10V, -5-5V and -10-10V. It is set by special FLASH data register SFD in PLC. As follows:

| Module no. | SFD register | Module no. | SFD register |
|------------|---------------|------------|---------------|
| #1 | SFD350~SFD359 | #9 | SFD430~SFD439 |
| #2 | SFD360~SFD369 | #10 | SFD440~SFD449 |
| #3 | SFD370~SFD379 | #11 | SFD450~SFD459 |
| #4 | SFD380~SFD389 | #12 | SFD460~SFD469 |
| #5 | SFD390~SFD399 | #13 | SFD470~SFD479 |
| #6 | SFD400~SFD409 | #14 | SFD480~SFD489 |
| #7 | SFD410~SFD419 | #15 | SFD490~SFD499 |
| #8 | SFD420~SFD429 | #16 | SFD500~SFD509 |

SFD bit definition

Take the first module as an example to illustrate how to set it up.

| | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 |
|------------------|------|--------------|-------------|------|------|--------------|-------------|------|
| | DA2 | | | | DA1 | | | |
| Byte0 | - | voltage | current | | - | voltage | current | |
| | | 000: 0~10V | 010: 0~20mA | | | 000: 0~10V | 010: 0~20mA | |
| | | 001: 0~5V | 011: 4~20mA | | | 001: 0~5V | 011: 4~20mA | |
| | | 100: -10~10V | | | | 100: -10~10V | | |
| | | 101: -5~5V | | | | 101: -5~5V | | |
| | DA4 | | | | DA3 | | | |
| Byte1 | - | voltage | current | | - | voltage | current | |
| | | 000: 0~10V | 010: 0~20mA | | | 000: 0~10V | 010: 0~20mA | |
| | | 001: 0~5V | 011: 4~20mA | | | 001: 0~5V | 011: 4~20mA | |
| | | 100: -10~10V | | | | 100: -10~10V | | |
| | | 101: -5~5V | | | | 101: -5~5V | | |
| Byte2~ Byte19 | - | | | | | | | |

Example: The working modes of output channel 3, channel 2, channel 1 and channel 0 are 0-10V, 0-10V, 0-20mA and 0-20mA, respectively.

Method 1:

You can configure it directly in the PLC software, the configuration method please refer to chapter 6-4.

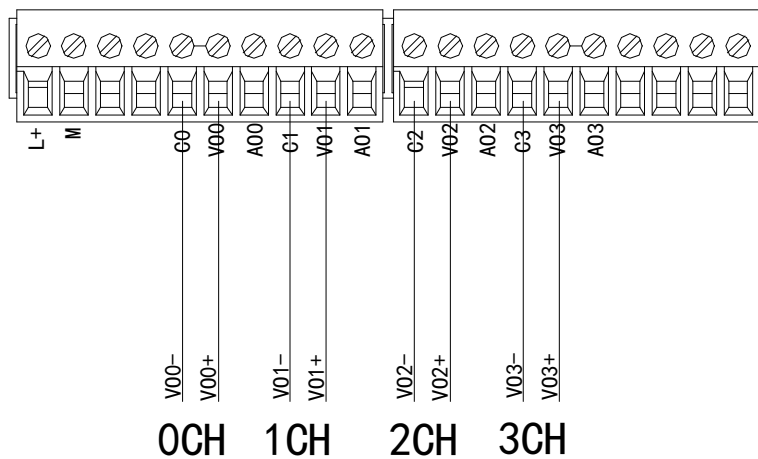
Method 2:

Set the SFD as follows: SFD350=0022H

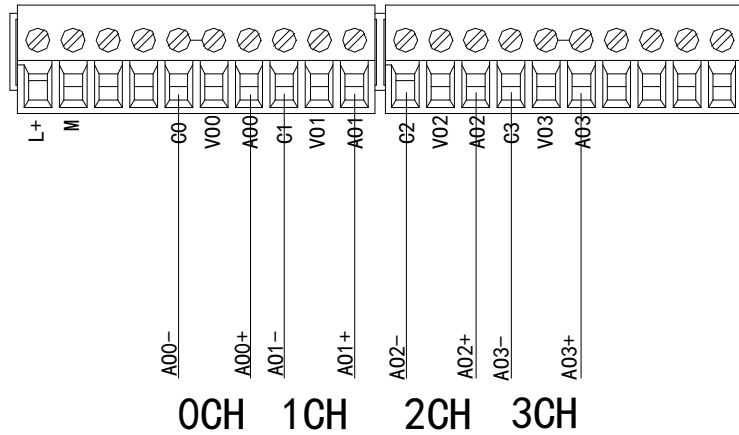
6-5. External wiring

For external connection, to avoid interference, use shielding wire and connect the ground to the single point of shielding layer.

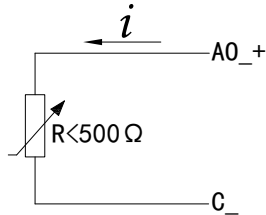
Voltage output



Current output



XL-E4DA current output wiring:

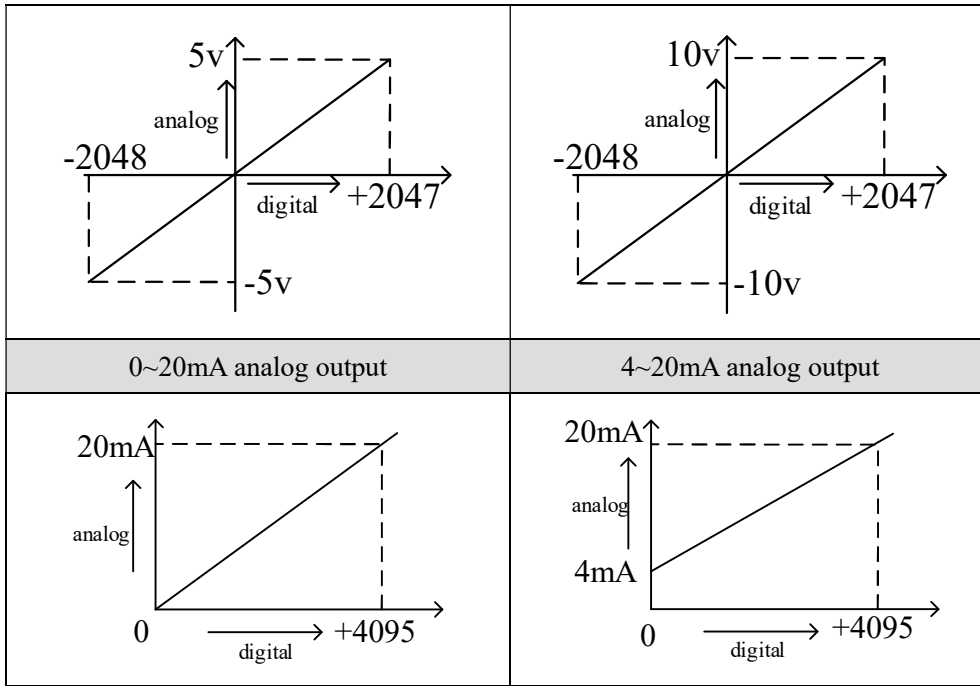


Note: current output no needs to connect DC24V power supply.

6-6. Analog digital conversion diagram

The relationship between the output digital quantity and its corresponding analog data is shown in the following table:

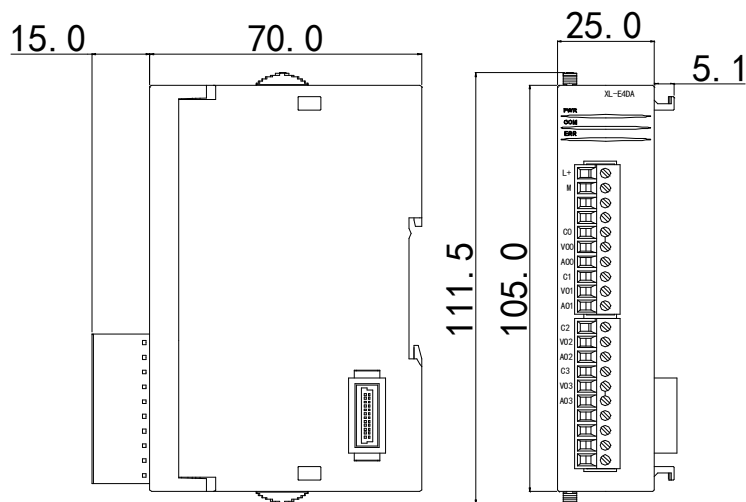
| 0~5V analog output | 0~10V analog output |
|---------------------|-----------------------|
| | |
| -5~5V analog output | -10~10V analog output |



Note: When the input data exceeds K4095, the analog data of DA conversion remains unchanged at 5V, 10V or 20mA.

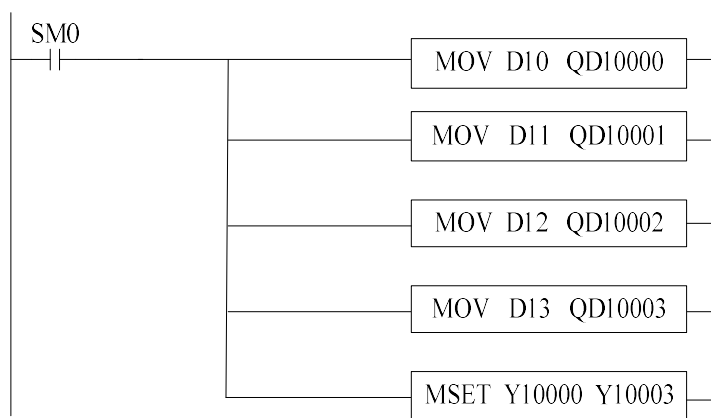
6-7. Dimension

(Unit: mm)



6-8. Application

Example: real-time write 4 channels data(take module 1 as an example)



Explain:

SM0 is a constant ON coil and has been in ON state during the operation of PLC.

Write the data register D10 to output channel 0.

Write the data register D11 to output channel 1.

Write the data register D12 to output channel 2.

Write the data register D13 to output channel 3.

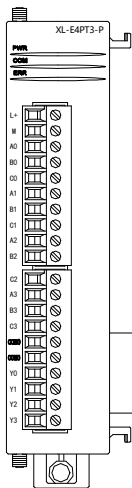
Since all channels are used, all the enabled bits of all channels are opened.

7. PT100 temperature module XL-E4PT3-P

This chapter mainly introduces XL-E4PT3-P module specifications, terminal instructions, input definition number allocation, working mode settings, external connections, analog-to-digital conversion diagrams, appearance size diagrams and related programming examples.

7-1. Module features and specifications

XL-E4PT3-P temperature PID control module processes 4-channel thermal resistance temperature signals and transmits them to the main unit of PLC.



Features

- Platinum thermal resistance input, indexing number Pt100, Pt1000
- 4 channels input, 4 channels output
- 4 groups PID parameters, auto-tune function
- The constant current output of 1mA is not affected by the change of external environment.
- Resolution is 0.1°C
- As a special functional module of the XL series, the XL3 series PLC can connect up to 10 modules, XL5/XL5E/XL5N/XL5H/XLME/XLH/XSLH can expand 16 modules, and XL1 does not support expansion modules.

Module specifications

| Item | Contents |
|-------------------------------|--|
| Analog input signal | Pt100, Pt1000 platinum thermistors |
| Temperature measurement range | -100°C~500°C |
| Digital output range | -1000~5000 |
| Resolution | 0.1°C |
| Integrate precision | ±0.5% (relative max value) |
| Conversion speed | 450ms/4 channels |
| Module power supply | DC24V±10%, 50mA |
| Install format | Fixed with M3 screws or directly installed on orbit of |

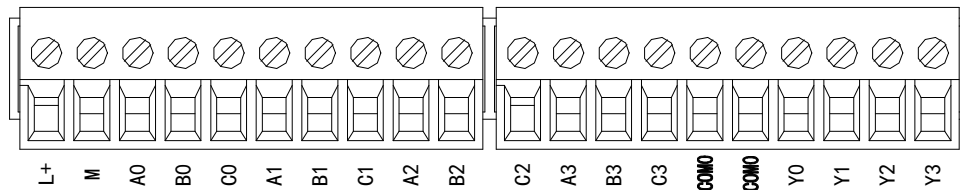
DIN46277 (Width: 35mm)

Note:

- (1) When there is no signal input, the channel data is the maximum value of the digital output range (5000).
- (2) Connect Pt100 or Pt1000 thermal resistor according to actual needs.
- (3) Only firmware version V3 and above modules support Pt1000, and can be used in conjunction with version V3.7.16 and above XDPPro software for configuration.

7-2. Terminals

Terminal arrangement



Module signal

| Name | | Function |
|-----------|-----|---|
| LED light | PWR | The indicator lights up when the module has a power supply |
| | COM | When the module communication port communicates normally, the indicator lights on |
| | ERR | When there is an error in the module, the indicator is always on or flickering (red) When the ERR lamp is always on, there are serious application errors in the module that can not be used, so the mode of use must be adjusted, and the PLC body is switched to STOP state. When the ERR lamp flickers, there are application errors, abnormal work and abnormal data in the module, but the PLC body is still RUN. |
| terminal | L+ | External power supply 24V + |
| | M | External power supply 24V - |
| | A0 | CH0 temperature input |
| | B0 | CH0 input common terminal |
| | C0 | CH0 input common terminal |
| | A1 | CH1 temperature input |
| | B1 | CH1 input common terminal |

| | | |
|--|-------|---|
| | C1 | CH1 input common terminal |
| | A2 | CH2 temperature input |
| | B2 | CH2 input common terminal |
| | C2 | CH2 input common terminal |
| | A3 | CH3 temperature input |
| | B3 | CH3 input common terminal |
| | C3 | CH3 input common terminal |
| | COM0 | PID output common terminal |
| | Y0~Y3 | PID output terminals corresponding to CH0~CH3 |

Wiring head specifications

When wiring the module, its wiring head should meet the following requirements:

- (1) The stripping length is 9 mm;
- (2) Flexible conductors with bare tubular ends are 0.25-1.5 square.
- (3) Flexible conductor with tubular pre-insulated end is 0.25-0.5 square.

7-3. I/O address

XL series analog module will not occupy I/O unit, the conversion value will be sent to PLC register. Each channel related PLC register address are shown as below:

| Parameter | Address | | | | |
|---|-----------|---------|---------|---------|---------|
| | Channel | CH0 | CH1 | CH2 | CH3 |
| Display temperature (unit: 0.1°C) | Module 1 | ID10000 | ID10001 | ID10002 | ID10003 |
| | Module 2 | ID10100 | ID10101 | ID10102 | ID10103 |
| | | ID10x00 | ID10x01 | ID10x02 | ID10x03 |
| | Module 16 | ID11500 | ID11501 | ID11502 | ID11503 |
| PID enable bit (0: OFF, 1: ON) | Module 1 | Y10000 | Y10001 | Y10002 | Y10003 |
| | Module 2 | Y10100 | Y10101 | Y10102 | Y10103 |
| | | Y10x00 | Y10x01 | Y10x02 | Y10x03 |
| | Module 16 | Y11700 | Y11701 | Y11702 | Y11703 |
| PID contact output (X input returning to the main body) | Module 1 | X10000 | X10001 | X10002 | X10003 |
| | Module 2 | X10100 | X10101 | X10102 | X10103 |
| | | X10x00 | X10x01 | X10x02 | X10x03 |
| | Module 16 | X11700 | X11701 | X11702 | X11703 |
| Open circuit detection (0: | Module 1 | X10010 | X10011 | X10012 | X10013 |
| | Module 2 | X10110 | X10111 | X10112 | X10113 |

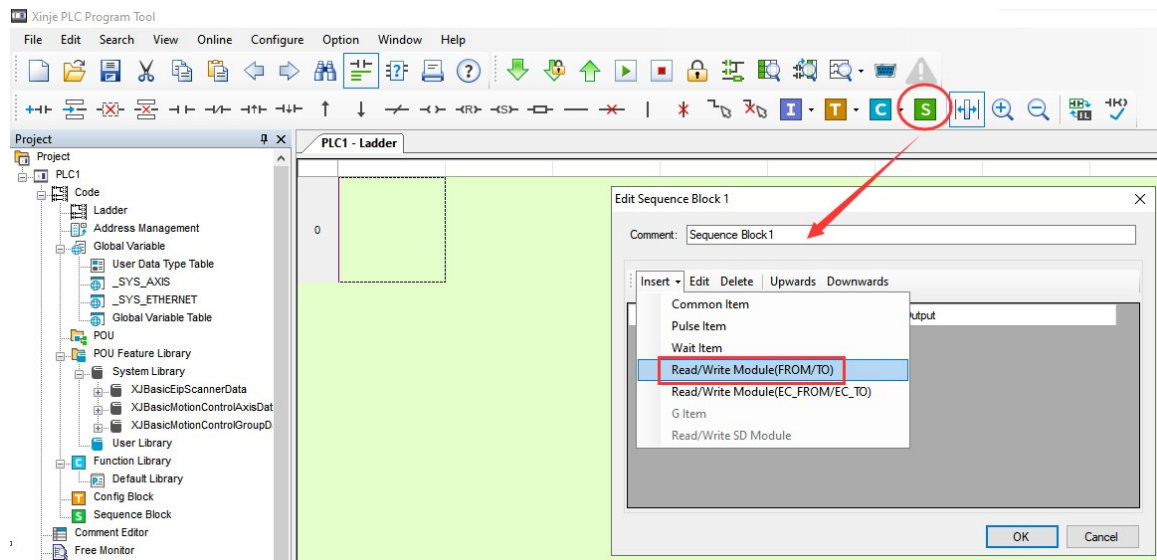
| | | | | | |
|----------------------|-----------|--------|--------|--------|--------|
| normal, 1: | | X10x10 | X10x11 | X10x12 | X10x13 |
| disconnected) | Module 16 | X11710 | X11711 | X11712 | X11713 |
| Auto-tuning error | Module 1 | X10020 | X10021 | X10022 | X10023 |
| | Module 2 | X10120 | X10121 | X10122 | X10123 |
| | | X10x20 | X10x21 | X10x22 | X10x23 |
| | Module 16 | X11720 | X11721 | X11722 | X11723 |

Note:

- (1) When the "Y function selection" is set to "channel enable", Y10000-Y10003 (taking # 1 module as an example) is the PID enable bit, and the PID duty cycle output needs to be monitored from X10000 to X10003 (taking # 1 module as an example).
- (2) When the "Y function selection" is set to "immediate output", Y0~Y3 are ordinary switch output terminals, and Y10000~Y10003 (taking # 1 module as an example) can be used to directly control the Y0~Y3 output of the module.
- (3) When the "Y function selection" is set to "channel enable", Y0~Y3 are the PID output terminals, and Y10000~Y10003 (taking # 1 module as an example) can be used to enable the corresponding channel's PID control. The Y0~Y3 output of the module is automatically calculated and controlled by the PID.

From/To instruction

The reading and writing of the temperature control module for the thermal resistor needs to be completed in the sequence block through the FROM/TO command, as shown in the following figure:



Parameter write instruction TO



Function: write the PLC register data to module address, the operate unit is word.

Operand:

S1: target module number, range: 10000~10015. Operand: K, TD, CD, D, HD, FD

S2: first address of module. Operand: K, TD, CD, D, HD, FD

S3: write in register numbers. Operand: K, TD, CD, D, HD, FD

D1: first address of PLC. Operand: TD, CD, D, HD, FD

Parameter read instruction FROM



Function: read the module data to the PLC register, the operate unit is word.

S1: target module number, range: 10000~10015. Operand: K, TD, CD, D, HD, FD

S2: first address of module. Operand: K, TD, CD, D, HD, FD

S3: read register numbers. Operand: K, TD, CD, D, HD, FD

D1: first address of PLC. Operand: TD, CD, D, HD, FD

Note:

- (1) The FROM/TO instruction can only be written in the sequence function block. For XL series PLCs with firmware version V3.4.5 and above, a maximum of 100 BLOCKs can be written in the program, but a maximum of 8 can be run simultaneously.
- (2) The starting number of the module starts from K10000, with module # 1 being K10000, module # 2 being K10001... and so on, module # 16 being K10015.

Related address definition:

The address of the read/write parameters:

| From_To data | Address | | | | Read/write | Default value |
|----------------------------------|---------|-----|-----|-----|------------|---------------|
| | CH0 | CH1 | CH2 | CH3 | | |
| Channel | CH0 | CH1 | CH2 | CH3 | | |
| Auto-tune bit | K0 | K0 | K0 | K0 | R/W | 0 |
| PID output (0~4095) | K1 | K2 | K3 | K4 | R | - |
| Target temperature (unit: 0.1°C) | K5 | K6 | K7 | K8 | R/W | 0 |
| Kp | K9 | K13 | K17 | K21 | R/W | 40 |
| Ki | K10 | K14 | K18 | K22 | R/W | 240 |
| Kd | K11 | K15 | K19 | K23 | R/W | 60 |
| Diff (unit: 0.1°C) | K12 | K16 | K20 | K24 | R/W | 1000 |
| Control period (unit: 0.1s) | K25 | K26 | K27 | K28 | R/W | 20 |
| Output range (range: | K29 | K30 | K31 | K32 | R/W | 100 |

| | | | | | | |
|--|-----|-----|-----|-----|-----|---|
| 0~100) | | | | | | |
| Temperature difference δ (unit: 0.1°C) | K33 | K34 | K35 | K36 | R/W | 0 |
| Calibrate ambient temperature values (unit: 0.1°C) | K37 | K38 | K39 | K40 | W | - |
| From/To data initialization | K41 | K41 | K41 | K41 | W | - |

| | |
|--|---|
| Auto-tune PID control bit | Auto-tune triggered signal, start to auto-tune mode when set to 1 After auto-tune, PID parameters and temperature control period value are refreshed, the bit value is cleared to be 0. The user can read the bit to know the state. 1 means auto-tune is ongoing. 0 means auto-tune has finished. |
| PID output value (0~4095) | When the PID output is for analog control (such as steam valve opening or thyristor conduction angle), this value can be transmitted to the analog output module to achieve control requirements. |
| PID parameters (P, I, D) | The best PID parameters got from the PID auto-tune. If the current PID parameters cannot meet the control requirements, users can set the experience PID parameters to make the module work according to the user setting value. |
| PID calculation range (Diff) Unit: 0.1°C | This function can set the temperature range of the PID operation, such as setting the relevant parameter Tdiff, the target temperature is Target, then the operation range of the PID is Target-Tdiff < T < Target + Tdiff, when T < Target-Tdiff, the output is the max value, when T > Target + Tdiff, the output is 0. |
| Temperature difference value δ Unit: 0.1°C | The actual temperature display = (sampling temperature value + temperature deviation value δ)/10. When the user thinks the measured temperature is different from the actual temperature, this value can be modified to correct the temperature. |
| Set temperature Unit: 0.1°C | The target temperature of the control system. Range from -1000~5000, which is -100~500°C, precision degree is 0.1°C. |
| Temperature control period Unit: 0.1s | The adjusting range of temperature control period is 0.1s~200s, and the minimum precision range is 0.1s. For example, when writing 5, the actual temperature control period is 0.5s. |
| Adjusting Environment temperature Unit: 0.1°C | When the user believes that the ambient temperature value is inconsistent with the temperature value displayed on the module channel, the known ambient temperature value can be written into this parameter. At the moment the module is written, the temperature deviation value is set to δ and save. Calculate temperature deviation value δ = adjusting ambient temperature value - sampling temperature value. Unit: 0.1 °C. |

| | |
|-----------------------------|--|
| | <p>For example, in the thermal equilibrium state, the user measured the ambient temperature as 60.0 °C using a mercury thermometer, and the displayed temperature was 55.0 °C (corresponding to the sampling temperature of 550), with a temperature deviation value $\delta = 0$. At this point, the user writes 600 and the temperature deviation value δ Recalculated to 50 (5 °C), the displayed temperature is (sampling temperature value+temperature deviation value δ) / 10=60 °C.</p> <p>Attention: When the user inputs the adjusting temperature value, confirm that it is consistent with the ambient temperature. This data is very important, and once entered incorrectly, it can lead to calculating temperature deviation values δ Serious error, which in turn affects the display temperature.</p> |
| Auto-tune output range | <p>The output amplitude calculated by PID is in %, where 100 represents the duty cycle as 100% of the full scale output and 80 represents 80% of the full scale output.</p> <p>Note: When set to 0, PID control will have no output.</p> |
| From/To data initialization | <p>This function can restore the parameters in the above table to their factory settings.</p> <p>When using it, K41 needs to be set to 1, setting to other values are invalid.</p> |

Note:

- (1) The "From/To data initialization" function requires the module firmware version to be V3 or higher.
- (2) When the "Y function selection" is set to "immediate output", only the "temperature deviation value" and "adjusting ambient temperature value" is valid, and other parameters are not effective.
- (3) The module can automatically save the set temperature value, PID parameters, temperature control cycle, output amplitude, temperature deviation, and temperature calibration parameters. When writing the above parameters, it is necessary to use the rising edge to trigger the writing. Do not keep writing. It is recommended to only write the parameters used. It is not recommended to write the entire piece of data for programming convenience, as writing 0 to some addresses may cause the system to malfunction.
- (4) The self-tuning enable address K0: K0 will occupy a continuous 8-bit address space. The 4-channel module enable bits correspond to the first 4 bits address space, while the last 4 bits addresses are idle (but cannot be used for other purposes). When the read/write enable bit is enabled, K0 can be a coil or register. When it is a coil, it occupies 8 consecutive bits starting from the coil address; When it is a register, it occupies that register. For example, to set the first and third channels of the module to self-tuning mode, and the other two channels to manual PID mode, with the command To K10000 K0 K1 M10, M10 and M12 should be set to ON, and M11, M13, M14, and M15 should be set to OFF; When the instruction is To K10000 K0 K1 D100, D100 should be assigned a value of 5.

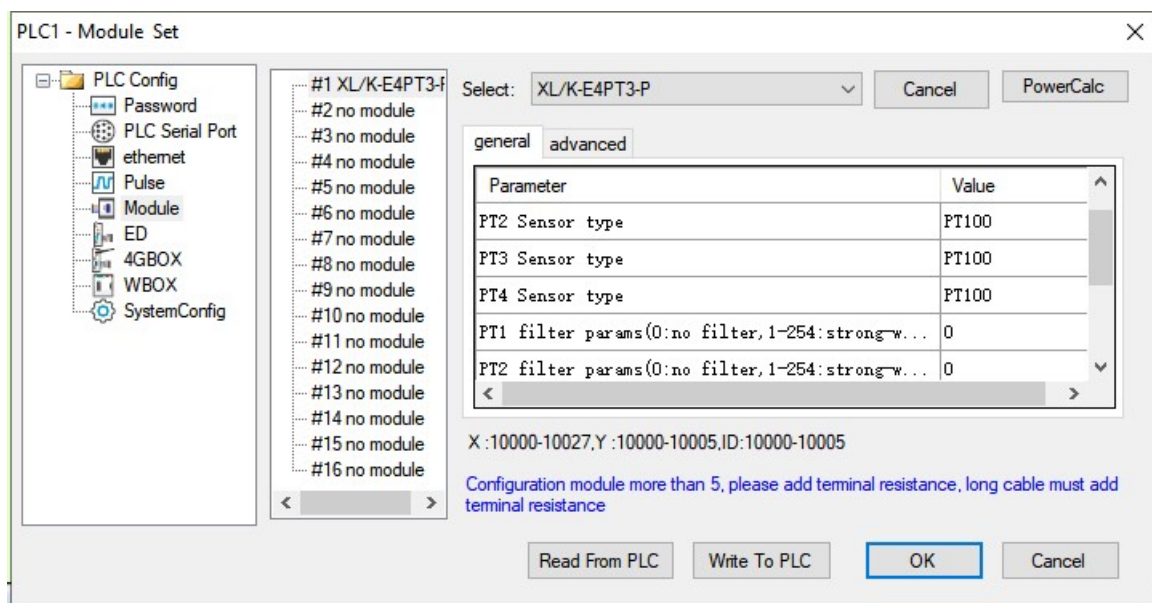
7-4. Working mode

There are two ways to set the working mode (the effect of these two ways is equivalent):

- 1: Through the XDPpro software
- 2: Through Flash Register (FD) Settings

Set through the software

Open the software, click configure/expansion module setting, then select the module type in the following window:



Choose the module model, set the parameters of each channel, click write to PLC. Then download user program and run, the settings will be effective.

Note:

- (1) The first-order low-pass filtering method weighted this sampling value and the output value of the last filtering to get the effective filtering value; the filter coefficient is set by the user to 0-254, the smaller the value, the more stable the data, but it may lead to data lag; therefore, when set to 1, the filtering effect is strongest and the data is the most stable; when set to 254, the filtering effect is the weakest; default is 0 (no filtering).
- (2) The "Y function selection" function needs to be supported by module firmware versions of V3 or above.
- (3) "Y Function Selection" is used to specify the functions of Y10000~Y10003 (# 1 module as an example). The default factory setting is "Channel Enable", which supports the module's own self-tuning and PID control functions. The output points Y0~Y3 on the module are affected by the PID output value, resulting in on/off effects; When set to "immediate output", the output points Y0~Y3 on the module are ordinary switch output points. Setting On Y10000~Y10003

can conduct Y0~Y3, while the module only retains the temperature acquisition function. If temperature control is required, please use the PID command of the PLC body to achieve it.
 (4) The "PT channel disconnection detection" function requires firmware version V3 or above.

Set through flash register

Extension module CH0~CH3 channel can set filter coefficients through special FLASH data register FD inside PLC. As follows:

| Module ID | SFD address | Module ID | SFD address |
|-----------|---------------|-----------|---------------|
| #1 | SFD350~SFD359 | #9 | SFD430~SFD439 |
| #2 | SFD360~SFD369 | #10 | SFD440~SFD449 |
| #3 | SFD370~SFD379 | #11 | SFD450~SFD459 |
| #4 | SFD380~SFD389 | #12 | SFD460~SFD469 |
| #5 | SFD390~SFD399 | #13 | SFD470~SFD479 |
| #6 | SFD400~SFD409 | #14 | SFD480~SFD489 |
| #7 | SFD410~SFD419 | #15 | SFD490~SFD499 |
| #8 | SFD420~SFD429 | #16 | SFD500~SFD509 |

SFD bit definition

Take module 1 as an example to explain the setting method:

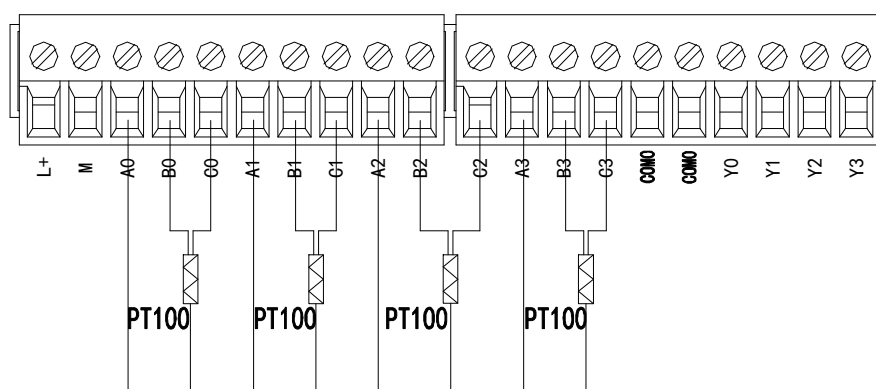
| Register | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 |
|----------|-------|---|------|------|---|--|------|------|
| SFD350 | Byte0 | PT channel 1 filtering coefficient (0 not filtered, 1-254 filtering intensity decreases sequentially) | | | | | | |
| | Byte1 | PT channel 2 filtering coefficient (0 not filtered, 1-254 filtering intensity decreases sequentially) | | | | | | |
| SFD351 | Byte2 | PT channel 3 filtering coefficient (0 not filtered, 1-254 filtering intensity decreases sequentially) | | | | | | |
| | Byte3 | PT channel 4 filtering coefficient (0 not filtered, 1-254 filtering intensity decreases sequentially) | | | | | | |
| SFD352 | Byte4 | - | | | | | | |
| | Byte5 | - | | | | | | |
| SFD353 | Byte6 | - | | | | | | |
| | Byte7 | - | | | | | | |
| SFD354 | Byte8 | - | | | PT channel disconnection detection 00: On 01: Off | Y function selection 00: Channel Enable 01: Immediate output | | |

| | | | |
|---------------|--------|-----------------------------|-----------------------------|
| | Byte9 | - | - |
| SFD355 | Byte10 | PT2 sensor type | PT1 sensor type |
| | | 0000: PT100 0001: PT1000 | 0000: PT100 0001: PT1000 |
| | Byte11 | PT4 sensor type | PT3 sensor type |
| | | 0000: PT100 0001: PT1000 | 0000: PT100 0001: PT1000 |
| SFD356 | Byte12 | - | - |
| | Byte13 | - | - |
| SFD357~SFD359 | | - | |

7-5. External wiring

When connecting the thermal resistance, when connecting the external + 24V power supply, please use the 24V power supply on the PLC body to avoid interference.

Input wiring

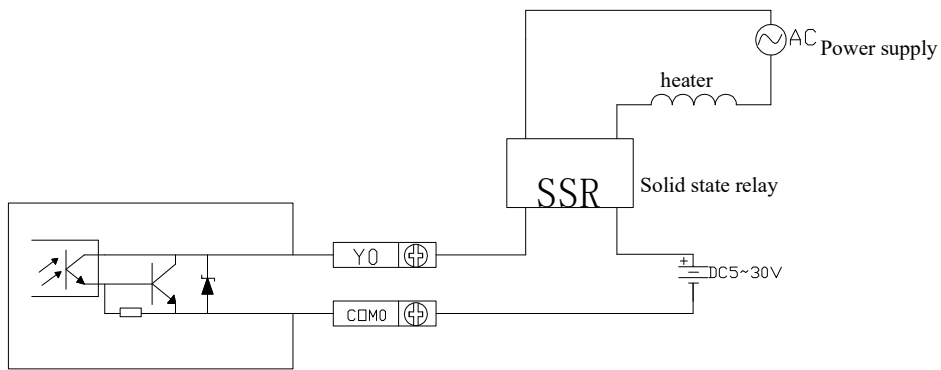


For a three-wire platinum thermistor, please connect two wires of the same color to the C0 end and the other wire to the A0 or A1 end.

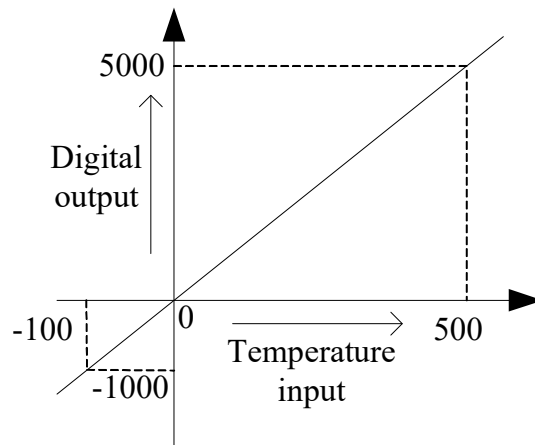
Output circuit

- Output terminal: transistor output terminal, please choose DC5V ~ 30V smooth power supply.
- Circuit Insulation: Optical couplers are used for optical insulation between the internal circuit of programmable controller and the output transistor, and the common modules are also separated from each other.
- Response time: The time from the programmable controller-driven (or circuit-breaking) optical coupler to the transistor ON/OFF is no more than 0.2 ms.
- Output Current: In order to limit the temperature rising, please make 50mA at each point.

- Open circuit leakage current: below 0.1mA.

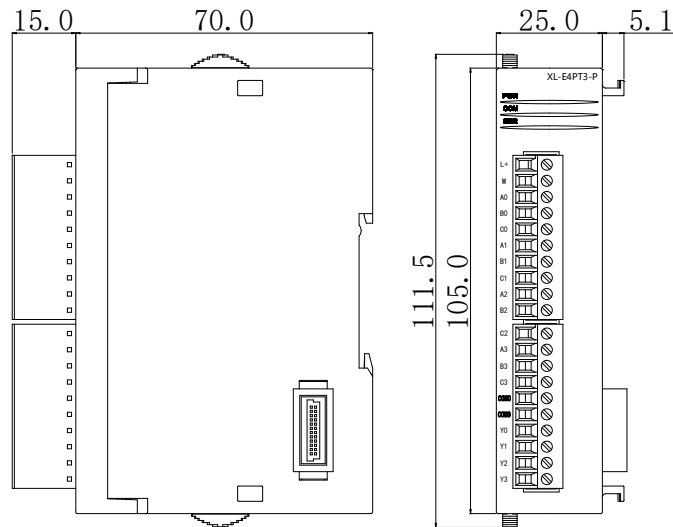


PT100 Input characteristic curve



7-6. Dimension

Unit: mm

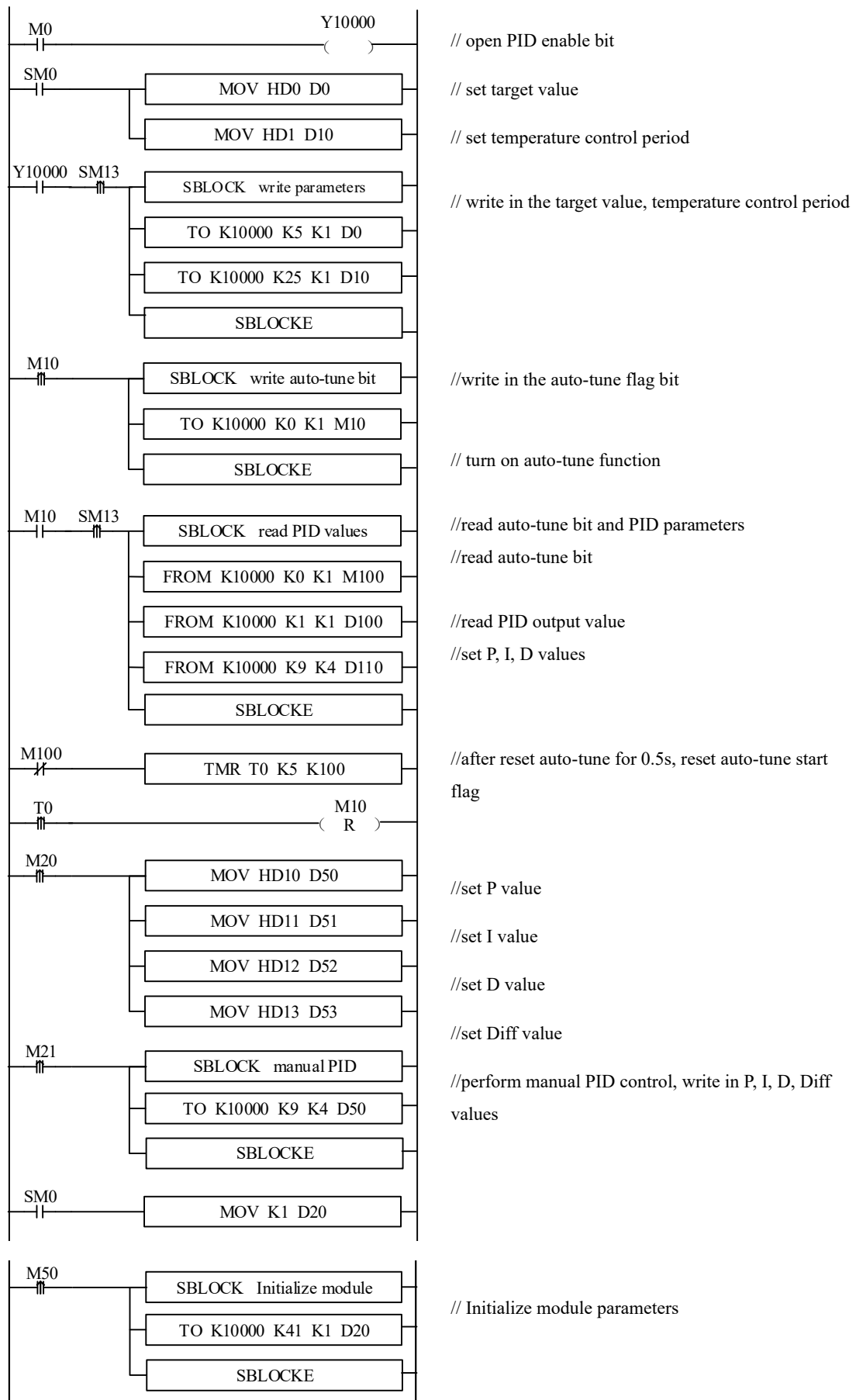


7-7. Application

When temperature control is required, there are two programming options:

1. use the PID of the PLC body for temperature control, at this time, you need to switch the Y function selection to 'immediate output', the programming case details please refer to "XDXL PLC instruction manual" chapter 7 PID control functions.
2. use the built-in PID of the module for temperature control, at this time, you need to switch the Y function selection to "channel enable", programming cases such as shown in following example 1.

Example 1: take module 1 as an example, do PID control for channel 0.



Explanation:

After enabling the self-tuning, this command will immediately occupy a total of 8 bits in M10-M17. M10-M13 corresponds to the self-tuning enable of each channel. To set which channel needs to be tuned, set the corresponding coil to ON. M14~M17 have no meaning at the moment and need to be left blank.

If the output is a solid-state relay, it is recommended to set the temperature control cycle to 1-3 seconds; If the output is a relay, it is recommended to set the temperature control cycle to 3-15s.

Due to inconsistent units, the PID parameters of the main body and module cannot be used interchangeably. The main body PID parameters are in uppercase, and the module PID parameters are in lowercase. The specific conversion relationship is as follows: $p=P/100$; $i=I/10$; $d=D/100$.

M0 turn on PID enable
SM0 set the target value, temperature control period
M1 write in target value, temperature control period
M3 set the manual P, I, D parameters
M4 write in manual P, I, D parameters
M10 read the auto-tuning bit, PID parameters and PID output value
M50 initialize the module
Y10000 PID enable bit of channel 0

D0 target value
D10 temperature control period
D80 P
D81 I
D82 D
D83 DIFF

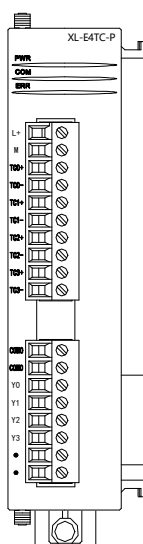
8. Thermocouple temperature module

XL-E4TC-P

This chapter mainly introduces XL-E4TC-P module specifications, terminal instructions, input definition number allocation, working mode settings, external connections, analog-to-digital conversion diagrams, appearance size diagrams and related programming examples.

8-1. Specifications

XL-E4TC-P can process 4-channel of thermocouple signal and send the data to the PLC.



Features

- thermocouple sensor signal input
- 4 channels input, 4 channels output
- 4 groups PID parameters, auto-tune function
- Built-in cold-terminal compensation circuit
- Resolution is 0.1°C
- As a special functional module of the XL series, the XL3 series PLC can connect up to 10 modules, XL5/XL5E/XL5N/XL5H/XLME/XLH/XSLH can expand 16 modules, and XL1 does not support expansion modules.

Specification

| Item | Contents | |
|-------------------------------|--|--|
| Analog input signal | K, S, E, N, B, T, J, R type thermocouple | |
| Temperature measurement range | K | 0.0°C~1300.0°C |
| | S | 0.0°C~1700.0°C |
| | E | 0.0°C~600.0°C |
| | N | 0.0°C~1200.0°C |
| | B | 250.0°C~1800.0°C (display 0 below 250.0°C) |

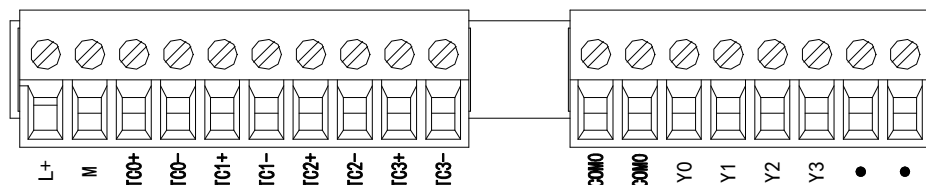
| | | |
|----------------------|---|----------------|
| | T | 0.0°C~400.0°C |
| | J | 0.0°C~800.0°C |
| | R | 0.0°C~1700.0°C |
| Digital output range | 0~max measuring temperature×10 (Taking K-type as an example, the digital output range is 0~13000) | |
| Resolution | 0.1°C | |
| Integrate precision | ±1% (relative max value) | |
| Conversion speed | 420ms 4 channels | |
| Module power supply | DC24V±10%, 50mA | |
| Installation | Fixed with M3 screws or directly installed on orbit of DIN46277 (Width: 35mm) | |

Note:

1. If no signal input, the channel data is -1.
2. According to the actual requirement to connect the thermocouple
3. The cover of device which installs thermocouple should be connected to the ground.

8-2. Terminals

Arrangement



Signal

| Name | Function | |
|-----------------|----------|---|
| Indicator light | PWR | The indicator lights up when the module has a power supply |
| | COM | When the module communication port communicates normally, the indicator lights on |
| | ERR | When there is an error in the module, the indicator is always on or flickering (red) When the ERR lamp is always on, there are serious application errors in the module that can not be used, so the mode of use must be adjusted, and the PLC body is switched to STOP state. When the ERR lamp flickers, there are application errors, abnormal work and |

| | | |
|-----------------|-------|---|
| | | abnormal data in the module, but the PLC body is still RUN. |
| Wiring terminal | L+ | External power supply 24V + |
| | M | External power supply 24V - |
| | TC0+ | CH0 thermocouple input + |
| | TC0- | CH0 thermocouple input - |
| | TC1+ | CH1 thermocouple input + |
| | TC1- | CH1 thermocouple input - |
| | TC2+ | CH2 thermocouple input + |
| | TC2- | CH2 thermocouple input - |
| | TC3+ | CH3 thermocouple input + |
| | TC3- | CH3 thermocouple input - |
| | COM0 | PID output common terminal |
| | Y0~Y3 | PID output terminals corresponding to CH0~CH3 |

Wiring specification

When wiring the module, its wiring head should meet the following requirements:

- (1) The stripping length is 9 mm;
- (2) Flexible conductors with bare tubular ends are 0.25-1.5 square.
- (3) Flexible conductor with tubular pre-insulated end is 0.25-0.5 square.

8-3. I/O address assignment

XL series analog module will not occupy I/O unit, the conversion value will be sent to PLC register. Each channel related PLC register address are shown as below:

| Parameters | Notes | | | | |
|--|--|---------|---------|---------|---------|
| | Channel | Ch0 | Ch1 | Ch2 | Ch3 |
| Display temperature Unit: 0.1 °C | Module 1 | ID10000 | ID10001 | ID10002 | ID10003 |
| | Module 2 | ID10100 | ID10101 | ID10102 | ID10103 |
| | | ID10×00 | ID10×01 | ID10×02 | ID10×03 |
| | Module 16 | ID11500 | ID11501 | ID11502 | ID11503 |
| PID output (return to the X input of PLC) | Module 1 | X10000 | X10001 | X10002 | X10003 |
| | Module 2 | X10100 | X10101 | X10102 | X10103 |
| | | X10×00 | X10×01 | X10×02 | X10×03 |
| | Module 16 | X11700 | X11701 | X11702 | X11703 |
| | When module duty cycle output, X point should be monitored, but Y point should not be monitored, because Y point is the PID enabler. | | | | |

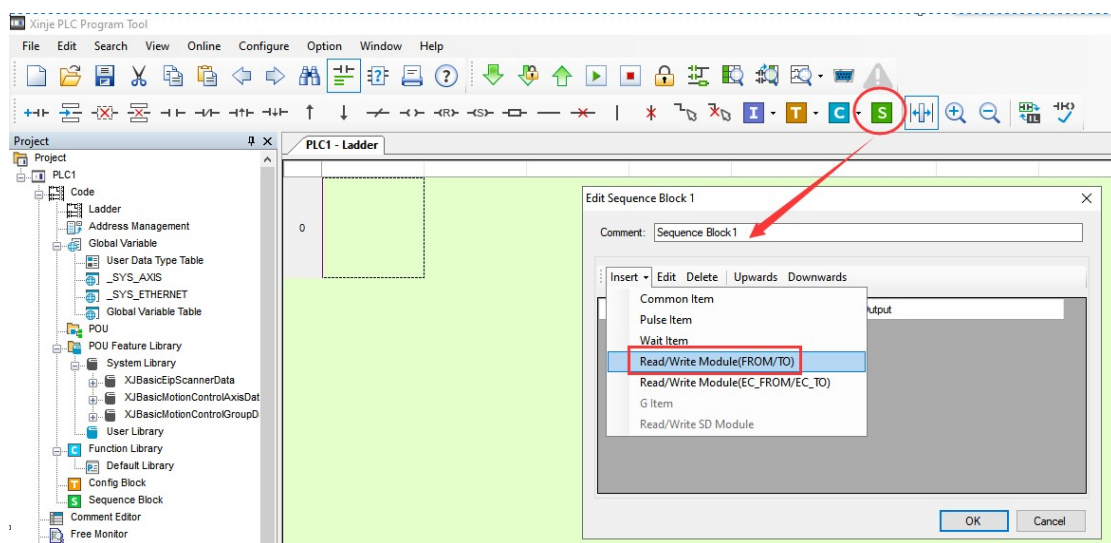
| | | | | | |
|---|-----------|--------|--------|--------|--------|
| Connection state of thermocouple(0 is connection, 1 is disconnection) | Module 1 | X10010 | X10011 | X10012 | X10013 |
| | Module 2 | X10110 | X10111 | X10112 | X10113 |
| | | X10×10 | X10×11 | X10×12 | X10×13 |
| | Module 16 | X11710 | X11711 | X11712 | X11713 |
| PID auto-tune error signal bit(0 is normal, 1 is error) | Module 1 | X10020 | X10021 | X10022 | X10023 |
| | Module 2 | X10120 | X10121 | X10122 | X10123 |
| | | X10×20 | X10×21 | X10×22 | X10×23 |
| | Module 16 | X11720 | X11721 | X11722 | X11723 |
| Channel PID enable signal (0: Off, 1: On) | Module 1 | Y10000 | Y10001 | Y10002 | Y10003 |
| | Module 2 | Y10100 | Y10101 | Y10102 | Y10103 |
| | | Y10×00 | Y10×01 | Y10×02 | Y10×03 |
| | Module 16 | Y11700 | Y11701 | Y11702 | Y11703 |

Note:

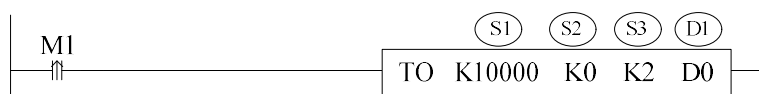
- (1) When the "Y function selection" is set to "channel enable", Y10000-Y10003 (taking # 1 module as an example) is the PID enable bit, and the PID duty cycle output needs to be monitored from X10000 to X10003 (taking # 1 module as an example).
- (2) When the "Y function selection" is set to "immediate output", Y0~Y3 are ordinary switch output terminals, and Y10000~Y10003 (taking # 1 module as an example) can be used to directly control the Y0~Y3 output of the module.
- (3) When the "Y function selection" is set to "channel enable", Y0~Y3 are the PID output terminals, and Y10000~Y10003 (taking # 1 module as an example) can be used to enable the corresponding channel's PID control. The Y0~Y3 output of the module is automatically calculated and controlled by the PID.

From/To instruction

The reading and writing of the thermocouple temperature control module needs to be completed in the sequence block through the FROM/TO command, as shown in the following figure:



Parameter write instruction TO



Function: write the PLC register data to module address, the operate unit is word.

Operand:

S1: target module number, range: 10000~10015. Operand: K, TD, CD, D, HD, FD

S2: first address of module. Operand: K, TD, CD, D, HD, FD

S3: write in register numbers. Operand: K, TD, CD, D, HD, FD

D1: first address of PLC. Operand: TD, CD, D, HD, FD

Parameter read instruction FROM



Function: read the module data to the PLC register, the operate unit is word.

S1: target module number, range: 10000~10015. Operand: K, TD, CD, D, HD, FD

S2: first address of module. Operand: K, TD, CD, D, HD, FD

S3: read register numbers. Operand: K, TD, CD, D, HD, FD

D1: first address of PLC. Operand: TD, CD, D, HD, FD

Note:

- (1) The FROM/TO instruction can only be written in the sequence block. For XL series PLCs with firmware version V3.4.5 and above, a maximum of 100 BLOCKs can be written in the program, but a maximum of 8 can be run simultaneously.
- (2) The starting number of the module starts from K10000, with module # 1 being K10000, module # 2 being K10001... and so on, module # 16 being K10015.

Related address definition:

The address of the read/write parameters:

| From_To data | Note | | | | Read /write | Default value |
|----------------------------------|------|-----|-----|-----|-------------|---------------|
| | CH0 | CH1 | CH2 | CH3 | | |
| PID auto-tune enable bit | K0 | K0 | K0 | K0 | R/W | 0 |
| PID output (0~4095) | K1 | K2 | K3 | K4 | R | - |
| Target temperature (unit: 0.1°C) | K5 | K6 | K7 | K8 | R/W | 0 |
| Kp | K9 | K13 | K17 | K21 | R/W | 40 |
| Ki | K10 | K14 | K18 | K22 | R/W | 240 |
| Kd | K11 | K15 | K19 | K23 | R/W | 60 |
| Diff (unit: 0.1°C) | K12 | K16 | K20 | K24 | R/W | 1000 |

| | | | | | | |
|---|-----|-----|-----|-----|-----|-----|
| Control period (unit: 0.1s) | K25 | K26 | K27 | K28 | R/W | 20 |
| Output range (range: 0~100) | K29 | K30 | K31 | K32 | R/W | 100 |
| Temperature difference δ (unit: 0.1°C) | K33 | K34 | K35 | K36 | R/W | 0 |
| Calibrate ambient temperature values | K37 | K38 | K39 | K40 | W | - |
| From/To data initialization | K41 | K41 | K41 | K41 | W | - |

| | |
|--|---|
| Auto-tune PID control bit | Auto-tune triggered signal, start to auto-tune mode when set to 1 After auto-tune, PID parameters and temperature control period value are refreshed, the bit value is cleared to be 0. The user can read the bit to know the state. 1 means auto-tune is ongoing. 0 means auto-tune has finished. |
| PID output value (0~4095) | When the PID output is for analog control (such as steam valve opening or thyristor conduction angle), this value can be transmitted to the analog output module to achieve control requirements. |
| PID parameters (P, I, D) | The best PID parameters got from the PID auto-tune. If the current PID parameters cannot meet the control requirements, users can set the experience PID parameters to make the module work according to the user setting value. |
| PID calculation range (Diff) Unit: 0.1°C | This function can set the temperature range of the PID operation, such as setting the relevant parameter Tdiff, the target temperature is Target, then the operation range of the PID is Target-Tdiff < T < Target + Tdiff, when T < Target-Tdiff, the output is the max value, when T > Target + Tdiff, the output is 0. |
| Temperature difference value δ Unit: 0.1°C | The actual temperature display = (sampling temperature value + temperature deviation value δ)/10. When the user thinks the measured temperature is different from the actual temperature, this value can be modified to correct the temperature. |
| Set temperature Unit: 0.1°C | The target temperature of the control system. Range from -1000~5000, which is -100~500°C, precision degree is 0.1°C. |
| Temperature control period Unit: 0.1s | The adjusting range of temperature control period is 0.1s~200s, and the minimum precision range is 0.1s. For example, when writing 5, the actual temperature control period is 0.5s. |
| Adjusting Environment temperature Unit: 0.1°C | When the user believes that the ambient temperature value is inconsistent with the temperature value displayed on the module channel, the known ambient temperature value can be written into this parameter. At the moment the module is written, the temperature deviation value is set to δ and save. Calculate temperature deviation value δ = adjusting ambient temperature value - sampling temperature value. Unit: 0.1 °C. |

| | |
|-----------------------------|--|
| | <p>For example, in the thermal equilibrium state, the user measured the ambient temperature as 60.0 °C using a mercury thermometer, and the displayed temperature was 55.0 °C (corresponding to the sampling temperature of 550), with a temperature deviation value $\delta = 0$. At this point, the user writes 600 and the temperature deviation value δ Recalculated to 50 (5 °C), the displayed temperature is (sampling temperature value+temperature deviation value δ) / 10=60 °C.</p> <p>Attention: When the user inputs the adjusting temperature value, confirm that it is consistent with the ambient temperature. This data is very important, and once entered incorrectly, it can lead to calculating temperature deviation values δ Serious error, which in turn affects the display temperature.</p> |
| Auto-tune output range | <p>The output amplitude calculated by PID is in %, where 100 represents the duty cycle as 100% of the full scale output and 80 represents 80% of the full scale output.</p> <p>Note: When set to 0, PID control will have no output.</p> |
| From/To data initialization | <p>This function can restore the parameters in the above table to their factory settings.</p> <p>When using it, K41 needs to be set to 1, setting to other values are invalid.</p> |

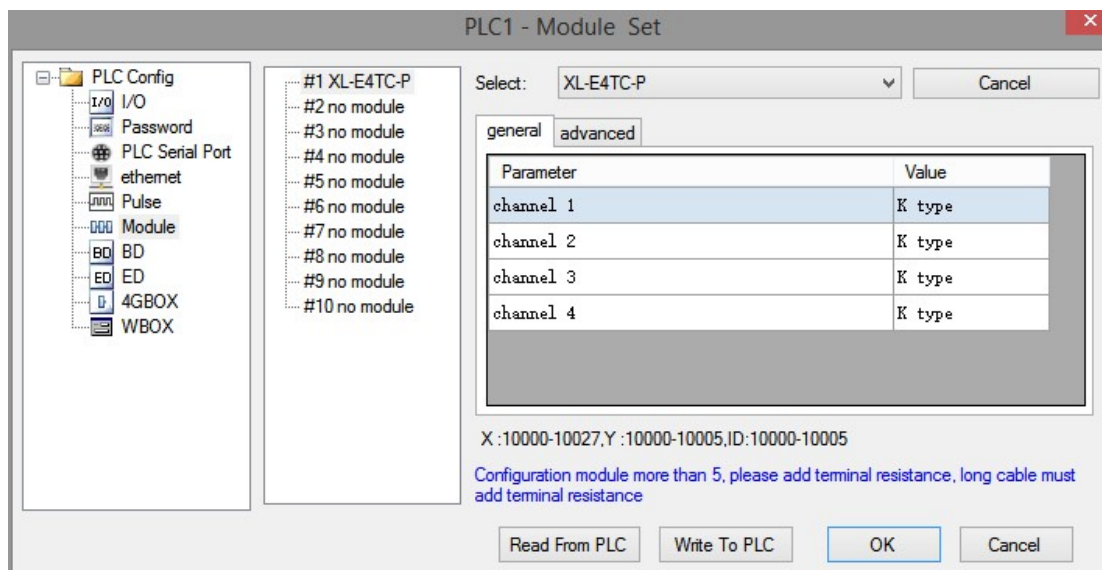
Note:

- (1) The "From/To data initialization" function requires the module firmware version to be V3 or higher.
- (2) When the "Y function selection" is set to "immediate output", only the "temperature deviation value" and "adjusting ambient temperature value" is valid, and other parameters are not effective.
- (3) The module can automatically save the set temperature value, PID parameters, temperature control cycle, output amplitude, temperature deviation, and temperature calibration parameters. When writing the above parameters, it is necessary to use the rising edge to trigger the writing. Do not keep writing. It is recommended to only write the parameters used. It is not recommended to write the entire piece of data for programming convenience, as writing 0 to some addresses may cause the system to malfunction.
- (4) The self-tuning enable address K0: K0 will occupy a continuous 8-bit address space. The 4-channel module enable bits correspond to the first 4 bits address space, while the last 4 bits addresses are idle (but cannot be used for other purposes). When the read/write enable bit is enabled, K0 can be a coil or register. When it is a coil, it occupies 8 consecutive bits starting from the coil address; When it is a register, it occupies that register. For example, to set the first and third channels of the module to self-tuning mode, and the other two channels to manual PID mode, with the command To K10000 K0 K1 M10, M10 and M12 should be set to ON, and M11, M13, M14, and M15 should be set to OFF; When the instruction is To K10000 K0 K1 D100, D100 should be assigned a value of 5.

8-4. Working mode

Set via software

Open the software, click configure/expansion module setting, then select the module type in the following window:



Set the thermocoupler of each channel, click write to PLC and ok. Then download user program and run, the settings will be effective.

Set via Flash register

The expansion module 0CH~3CH channel can set the type of thermocouple, and it can be set through the special FLASH data register FD inside the PLC. As follows:

| Module ID | SFD address | Module ID | SFD address |
|-----------|---------------|-----------|---------------|
| #1 | SFD350~SFD359 | #9 | SFD430~SFD439 |
| #2 | SFD360~SFD369 | #10 | SFD440~SFD449 |
| #3 | SFD370~SFD379 | #11 | SFD450~SFD459 |
| #4 | SFD380~SFD389 | #12 | SFD460~SFD469 |
| #5 | SFD390~SFD399 | #13 | SFD470~SFD479 |
| #6 | SFD400~SFD409 | #14 | SFD480~SFD489 |
| #7 | SFD410~SFD419 | #15 | SFD490~SFD499 |
| #8 | SFD420~SFD429 | #16 | SFD500~SFD509 |

SFD bit definition

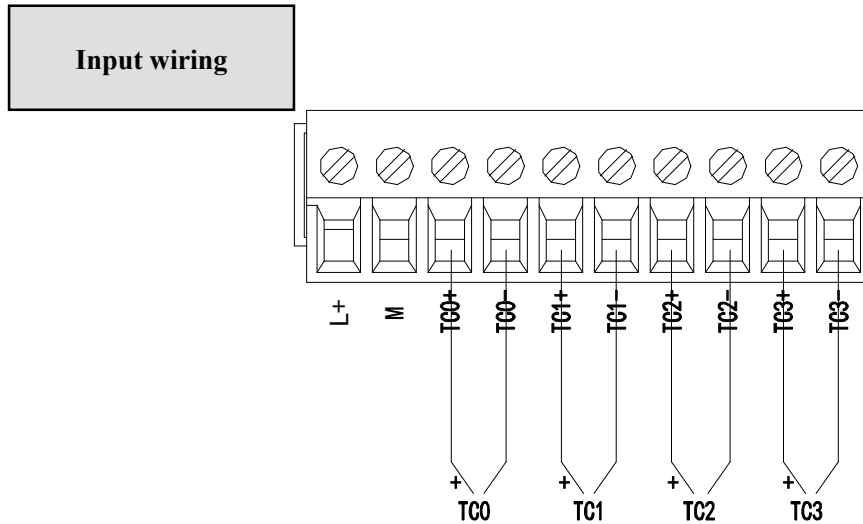
Take module 1 as an example to explain the setting method:

| Register | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | |
|---------------|-------------|---------|------|---------|---|--|------|------|--|
| SFD350 | TC1 channel | | | | TC0 channel | | | | |
| | Byte0 | K: 0000 | | | | K: 0000 | | | |
| | | S: 0001 | | | | S: 0001 | | | |
| | | E: 0010 | | | | E: 0010 | | | |
| | | N: 0011 | | | | N: 0011 | | | |
| | | J: 0100 | | | | J: 0100 | | | |
| | | T: 0101 | | | | T: 0101 | | | |
| | | R: 0110 | | | | R: 0110 | | | |
| | | B: 0111 | | | | B: 0111 | | | |
| | TC3 channel | | | | TC2 channel | | | | |
| | Byte1 | K: 0000 | | | | K: 0000 | | | |
| | | S: 0001 | | | | S: 0001 | | | |
| | | E: 0010 | | | | E: 0010 | | | |
| | | N: 0011 | | | | N: 0011 | | | |
| J: 0100 | | | | J: 0100 | | | | | |
| T: 0101 | | | | T: 0101 | | | | | |
| R: 0110 | | | | R: 0110 | | | | | |
| B: 0111 | | | | B: 0111 | | | | | |
| SFD351 | Byte2 | - | | | | | | | |
| | Byte3 | - | | | | | | | |
| SFD352 | Byte4 | - | | | TC channel disconnection detection 00: On 01: Off | Y function selection 00: Channel Enable 01: Immediate output | | | |
| | Byte5 | - | | | | | | | |
| SFD353~SFD359 | | - | | | | | | | |

Note: The "Y function selection" and "TC channel disconnection detection" functions require module firmware version V3 or above.

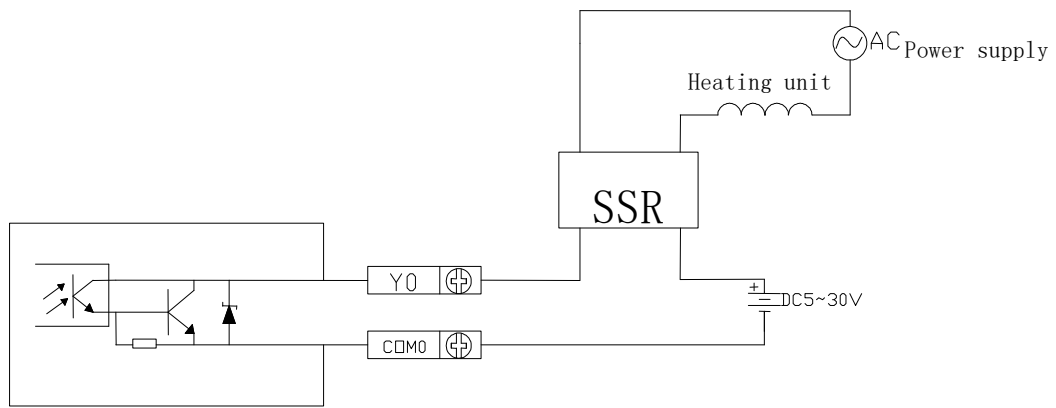
8-5. External connection

For thermocouple connection, When connect to +24V power, please use the 24V power supply of PLC to avoid interference.

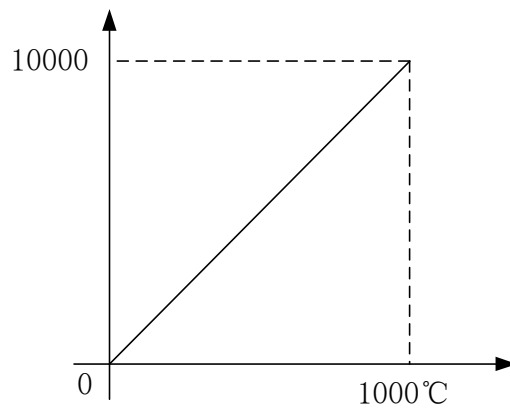


Output circuit

- Output terminal
For transistor output terminals, please use DC5V~30V power supply.
- Circuit insulation
PLC internal circuit and output transistor is optical insulation with optical coupling device.
Each public module is separate.
- Response time
The time is less than 0.2ms from PLC driving (or cut) optical coupling circuit to transistor ON/OFF.
- Output circuit
Each point current is 50mA to avoid over-heating.
- Open circuit leak current
Below 0.1mA.



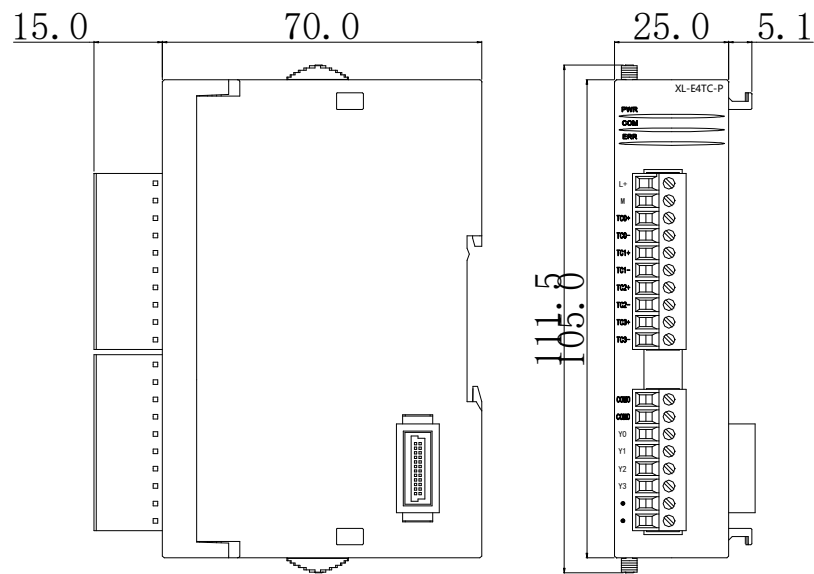
Thermocouple input characteristic curve



8-6. Dimension

The outline and dimension:

(unit: mm)

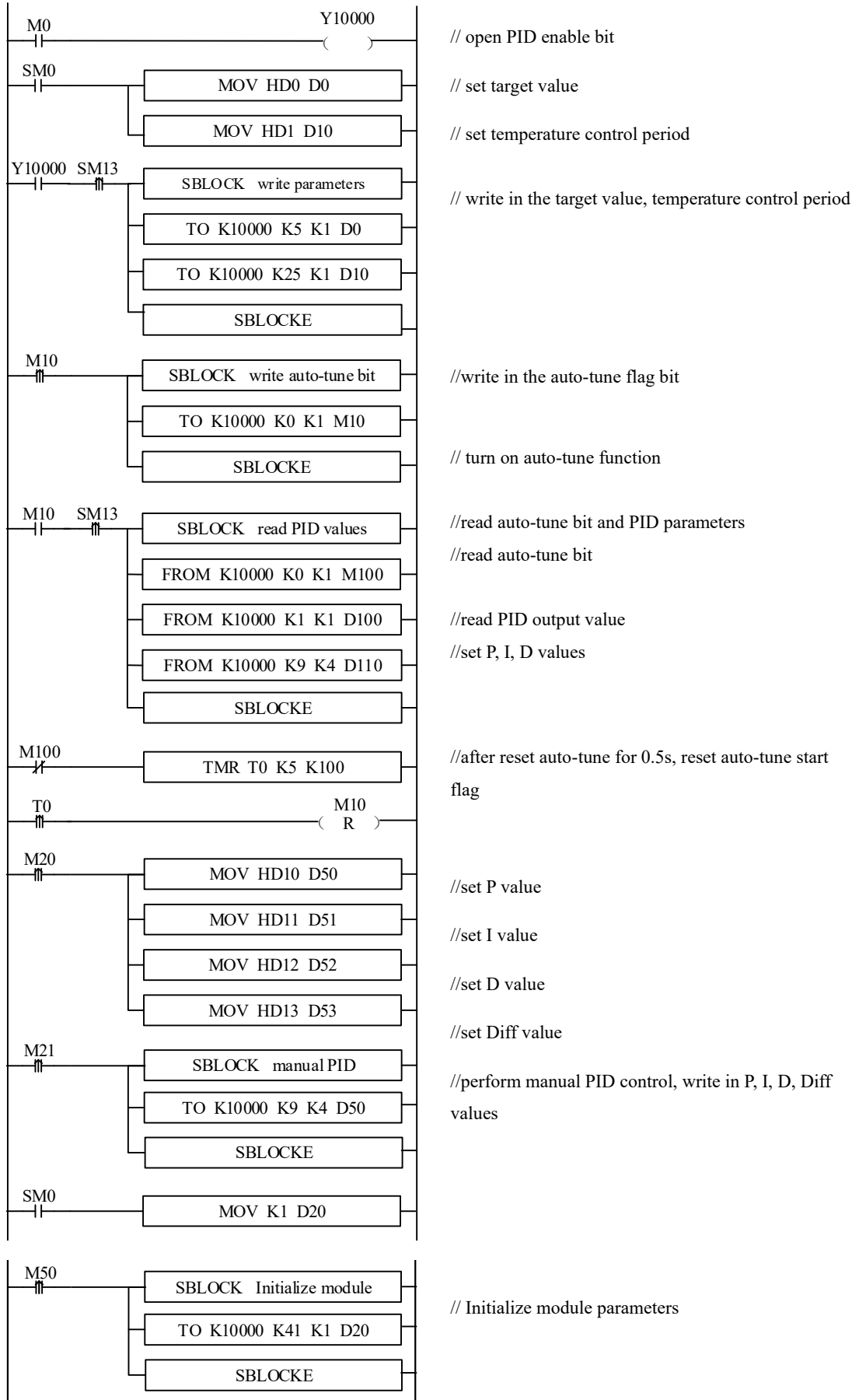


8-7. Programming example

When temperature control is required, there are two programming options:

1. use the PID of the PLC body for temperature control, at this time, you need to switch the Y function selection to 'immediate output', the programming case details please refer to "XDXL PLC instruction manual" chapter 7 PID control functions.
2. use the built-in PID of the module for temperature control, at this time, you need to switch the Y function selection to "channel enable", programming cases such as shown in following example 1.

Example 1: Do PID control for CH0 of module 1.



Explanation:

After enabling the self-tuning, this command will immediately occupy a total of 8 bits in M10-M17. M10-M13 corresponds to the self-tuning enable of each channel. To set which channel needs to be tuned, set the corresponding coil to ON. M14~M17 have no meaning at the moment and need to be left blank.

If the output is a solid-state relay, it is recommended to set the temperature control cycle to 1-3 seconds; If the output is a relay, it is recommended to set the temperature control cycle to 3-15s.

Due to inconsistent units, the PID parameters of the main body and module cannot be used interchangeably. The main body PID parameters are in uppercase, and the module PID parameters are in lowercase. The specific conversion relationship is as follows: $p=P/100$; $i=I/10$; $d=D/100$.

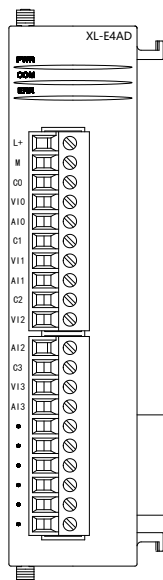
M0 turn on PID enable
SM0 set the target value, temperature control period
M1 write in target value, temperature control period
M3 set the manual P, I, D parameters
M4 write in manual P, I, D parameters
M10 read the auto-tuning bit, PID parameters and PID output value
M50 initialize the module
Y10000 PID enable bit of channel 0

D0 target value
D10 temperature control period
D80 P
D81 I
D82 D
D83 DIFF

9. Analog input module XL-E4AD

9-1. Specifications

XL-E4AD transform the analog input (current or voltage) to digital value and send to PLC register.



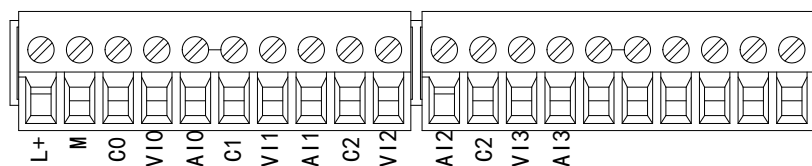
Features:

- 4-channel analog input: two modes of voltage input and current input can be selected.
- 14-bit high precision analog input.
- As a special functional module of the XL series, the XL3 series PLC can connect up to 10 modules, XL5/XL5E/XL5N/XL5H/XLME/XLH/XSLH can expand 16 modules, and XL1 does not support expansion modules.

Specifications:

| ITEMS | Analog Input (AD) | |
|----------------------|---|-----------------------------|
| | Voltage Input | Current Input |
| Analog Input Range | 0~5V, 0~10V, -5~5V, -10~10V | 0~20mA, 4~20mA, -20~20mA |
| Max input range | DC±15V | -40~40mA |
| Digital Output Range | 14 bits binary (0~16383 or -8192~8191) | |
| Resolution | 1/16383(14Bit) | |
| Synthesis Precision | ±1% | |
| Conversion Speed | 2ms per channel | |
| Power Supply | DC24V±10%, 150mA | |
| Installation | Fix with M3 screw or install on DIN46277 guilder (Width: 35mm) directly | |

9-2. Terminals



| Name | Function | |
|------------------|----------|---|
| Wiring terminals | L+ | External power supply for the module DC24V+ |
| | M | External power supply for the module DC24V- |
| | C0 | VI0, AI0 input ground |
| | VI0 | Channel 1 AD voltage input terminal |
| | AI0 | Channel 1 AD current input terminal |
| | C1 | VI1, AI1 input ground |
| | VI1 | Channel 2 AD voltage input terminal |
| | AI1 | Channel 2 AD current input terminal |
| | C2 | VI2, AI2 input ground |
| | VI2 | Channel 3 AD voltage input terminal |
| | AI2 | Channel 3 AD current input terminal |
| | C3 | VI3, AI3 input ground |
| | VI3 | Channel 4 AD voltage input terminal |
| | AI3 | Channel 4 AD current input terminal |

Note:

When wiring the module, its connector shall meet the following requirements:

- (1) Stripping length: 9mm.
- (2) Flexible cable with tubular bare end 0.25-1.5mm².
- (3) Flexible cable with tubular pre-insulated end is 0.25-0.5mm².

9-3. I/O address assignment

XL series expansions do not occupy I/O units; the converted value is sent to PLC register directly.

Note: each channel can work after turning on the channel enable bit.

Expansion module 1 address

| Channel | AD signal | Channel enable bit (set ON the enable bit to use this channel) | Channel alarm bit |
|---------|-----------|--|-------------------|
| 0CH | ID10000 | Y10000 | X10000 |
| 1CH | ID10001 | Y10001 | X10001 |

| | | | |
|-----|---------|--------|--------|
| 2CH | ID10002 | Y10002 | X10002 |
| 3CH | ID10003 | Y10003 | X10003 |

Expansion module 2 address

| Channel | AD signal | Channel enable bit (set ON the enable bit to use this channel) | Channel alarm bit |
|---------|-----------|--|-------------------|
| 0CH | ID10100 | Y10100 | X10100 |
| 1CH | ID10101 | Y10101 | X10101 |
| 2CH | ID10102 | Y10102 | X10102 |
| 3CH | ID10103 | Y10103 | X10103 |

Expansion module 3 address

| Channel | AD signal | Channel enable bit (set ON the enable bit to use this channel) | Channel alarm bit |
|---------|-----------|--|-------------------|
| 0CH | ID10200 | Y10200 | X10200 |
| 1CH | ID10201 | Y10201 | X10201 |
| 2CH | ID10202 | Y10202 | X10202 |
| 3CH | ID10203 | Y10203 | X10203 |

Expansion module 4 address

| Channel | AD signal | Channel enable bit (set ON the enable bit to use this channel) | Channel alarm bit |
|---------|-----------|--|-------------------|
| 0CH | ID10300 | Y10300 | X10300 |
| 1CH | ID10301 | Y10301 | X10301 |
| 2CH | ID10302 | Y10302 | X10302 |
| 3CH | ID10303 | Y10303 | X10303 |

Expansion module 5 address

| Channel | AD signal | Channel enable bit (set ON the enable bit to use this channel) | Channel alarm bit |
|---------|-----------|--|-------------------|
| 0CH | ID10400 | Y10400 | X10400 |
| 1CH | ID10401 | Y10401 | X10401 |
| 2CH | ID10402 | Y10402 | X10402 |
| 3CH | ID10403 | Y10403 | X10403 |

Expansion module 6 address

| Channel | AD signal | Channel enable bit (set ON the enable bit to use this channel) | Channel alarm bit |
|---------|-----------|--|-------------------|
| 0CH | ID10500 | Y10500 | X10500 |
| 1CH | ID10501 | Y10501 | X10501 |
| 2CH | ID10502 | Y10502 | X10502 |
| 3CH | ID10503 | Y10503 | X10503 |

Expansion module 7 address

| Channel | AD signal | Channel enable bit (set ON the enable bit to use this channel) | Channel alarm bit |
|---------|-----------|--|-------------------|
| 0CH | ID10600 | Y10600 | X10600 |
| 1CH | ID10601 | Y10601 | X10601 |
| 2CH | ID10602 | Y10602 | X10602 |
| 3CH | ID10603 | Y10603 | X10603 |

Expansion module 8 address

| Channel | AD signal | Channel enable bit (set ON the enable bit to use this channel) | Channel alarm bit |
|---------|-----------|--|-------------------|
| 0CH | ID10700 | Y10700 | X10700 |
| 1CH | ID10701 | Y10701 | X10701 |
| 2CH | ID10702 | Y10702 | X10702 |
| 3CH | ID10703 | Y10703 | X10703 |

Expansion module 9 address

| Channel | AD signal | Channel enable bit (set ON the enable bit to use this channel) | Channel alarm bit |
|---------|-----------|--|-------------------|
| 0CH | ID10800 | Y11000 | X11000 |
| 1CH | ID10801 | Y11001 | X11001 |
| 2CH | ID10802 | Y11002 | X11002 |
| 3CH | ID10803 | Y11003 | X11003 |

Expansion module 10 address

| Channel | AD signal | Channel enable bit (set ON the enable bit to use this channel) | Channel alarm bit |
|---------|-----------|--|-------------------|
| 0CH | ID10900 | Y11100 | X11100 |
| 1CH | ID10901 | Y11101 | X11101 |
| 2CH | ID10902 | Y11102 | X11102 |
| 3CH | ID10903 | Y11103 | X11103 |

Expansion module 11 address

| Channel | AD signal | Channel enable bit (set ON the enable bit to use this channel) | Channel alarm bit |
|---------|-----------|--|-------------------|
| 0CH | ID11000 | Y11200 | X11200 |
| 1CH | ID11001 | Y11201 | X11201 |
| 2CH | ID11002 | Y11202 | X11202 |
| 3CH | ID11003 | Y11203 | X11203 |

Expansion module 12 address

| Channel | AD signal | Channel enable bit (set ON the enable bit to use this channel) | Channel alarm bit |
|---------|-----------|--|-------------------|
| 0CH | ID11100 | Y11300 | X11300 |
| 1CH | ID11101 | Y11301 | X11301 |
| 2CH | ID11102 | Y11302 | X11302 |
| 3CH | ID11103 | Y11303 | X11303 |

Expansion module 13 address

| Channel | AD signal | Channel enable bit (set ON the enable bit to use this channel) | Channel alarm bit |
|---------|-----------|--|-------------------|
| 0CH | ID11200 | Y11400 | X11400 |
| 1CH | ID11201 | Y11401 | X11401 |
| 2CH | ID11202 | Y11402 | X11402 |
| 3CH | ID11203 | Y11403 | X11403 |

Expansion module 14 address

| Channel | AD signal | Channel enable bit (set ON the enable bit to use this channel) | Channel alarm bit |
|---------|-----------|--|-------------------|
| 0CH | ID11300 | Y11500 | X11500 |
| 1CH | ID11301 | Y11501 | X11501 |
| 2CH | ID11302 | Y11502 | X11502 |
| 3CH | ID11303 | Y11503 | X11503 |

Expansion module 15 address

| Channel | AD signal | Channel enable bit (set ON the enable bit to use this channel) | Channel alarm bit |
|---------|-----------|--|-------------------|
| 0CH | ID11400 | Y11600 | X11600 |
| 1CH | ID11401 | Y11601 | X11601 |
| 2CH | ID11402 | Y11602 | X11602 |
| 3CH | ID11403 | Y11603 | X11603 |

Expansion module 16 address

| Channel | AD signal | Channel enable bit (set ON the enable bit to use this channel) | Channel alarm bit |
|---------|-----------|--|-------------------|
| 0CH | ID11500 | Y11700 | X11700 |
| 1CH | ID11501 | Y11701 | X11701 |
| 2CH | ID11502 | Y11702 | X11702 |
| 3CH | ID11503 | Y11703 | X11703 |

Note:

1. Forbid the unused channel to improve the I/O scanning speed.
2. If set off the enable bit of the input channel, this channel will not accept the data. (the data display is 0).

9-4. Working mode

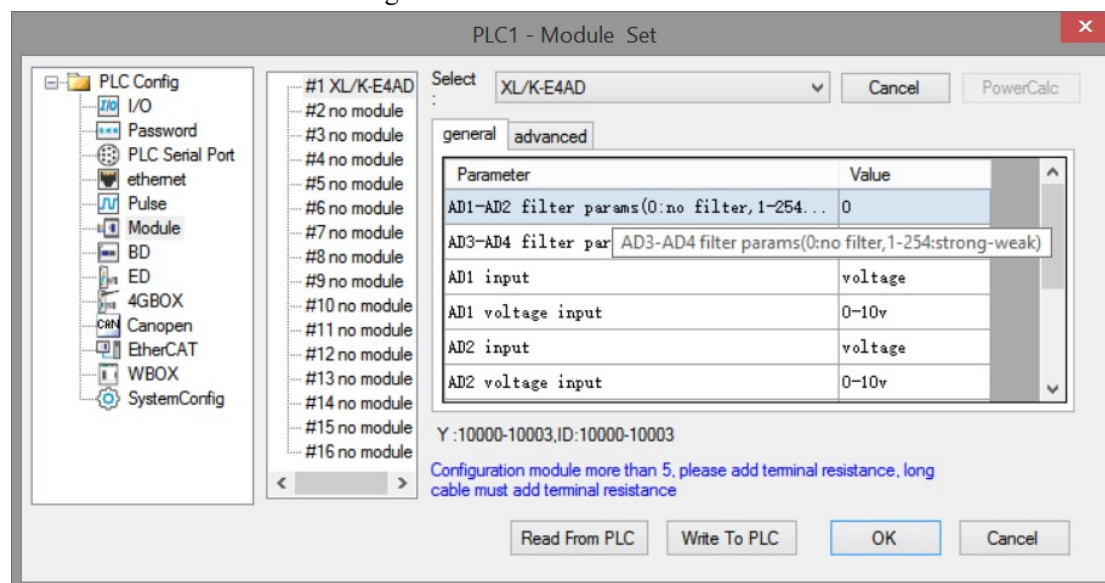
There are two ways to set the working mode:

1. XDPpro software
2. Flash registers of PLC

XDPpro software:

Open the XDPpro software, click configure/expansion module settings:

Set the model and channel parameters in the following window. Then click write to PLC.
Please restart the PLC after setting.



Note:

1. The first-order low-pass filtering method uses this sampling value and the last filtering output value for weighting to get the effective filtering value.
2. The filter coefficient is set to 0 ~ 254 by the user, the smaller the value is, the more stable the data is, but it may cause data lag; when it is set to 1, the filtering effect is the strongest, and when it is set to 254, the filtering effect is the weakest, and the default value is 0 (no filtering).

Flash registers:

The working mode can be voltage 0~5V, 0~10V, -5~5V, -10~10V or current 0~20mA, 4~20mA, -20~20mA, set through SFD registers of PLC:

| Module no. | SFD address | Module no. | SFD address |
|------------|---------------|------------|---------------|
| #1 | SFD350~SFD359 | #9 | SFD430~SFD439 |
| #2 | SFD360~SFD369 | #10 | SFD440~SFD449 |
| #3 | SFD370~SFD379 | #11 | SFD450~SFD459 |
| #4 | SFD380~SFD389 | #12 | SFD460~SFD469 |
| #5 | SFD390~SFD399 | #13 | SFD470~SFD479 |
| #6 | SFD400~SFD409 | #14 | SFD480~SFD489 |
| #7 | SFD410~SFD419 | #15 | SFD490~SFD499 |
| #8 | SFD420~SFD429 | #16 | SFD500~SFD509 |

Note: As shown in the preceding table, every register set 4 channels mode, each register has 16 bits, from low to high, and every 4 bits set 1 channel mode.

We take module 1 as an example to show how to set:

| Register | | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | Note | |
|---------------|-------|--|------|------|------|------|--|------|------|--|--|
| SFD350 | Byte0 | AD channel 1, 2 filtering coefficient | | | | | | | | AD filtering coefficient | |
| | Byte1 | AD channel 3, 4 filtering coefficient | | | | | | | | | |
| SFD351 | Byte2 | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | To set the input range of AD module. Byte2 low 4-bit is to set AD channel 1, high 4-bit is to set AD channel 2. Byte3 Low 4-bit is to set AD channel 3, high 4-bit is to set AD channel 4. | |
| | | AD2 | | | | AD1 | | | | | |
| | - | 000: 0~10V 001: 0~5V 100: -10~10V 101: -5~5V 010: 0~20mA 011: 4~20mA 110: -20~20mA | | | | - | 000: 0~10V 001: 0~5V 100: -10~10V 101: -5~5V 010: 0~20mA 011: 4~20mA 110: -20~20mA | | | | |
| | AD4 | | AD3 | | | | | | | | |
| SFD351 | Byte3 | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | | |
| | | AD4 | | AD3 | | | | | | | |
| SFD352 | Byte4 | AD channel short circuit/open circuit/over range detection switch | | | | | | | | | |
| | Byte5 | - | | | | | | | | | |
| SFD353~SFD359 | | - | | | | | | | | | |

For example:

Set module no. 1 channel 3, 2, 1, 0 working mode to 0~20mA, 4~20mA, 0~10V, 0~5V. Set channel 1 and channel 2 filter factor to 254, set channel 3 and channel 4 filter factor to 100.

So the SFD values are:

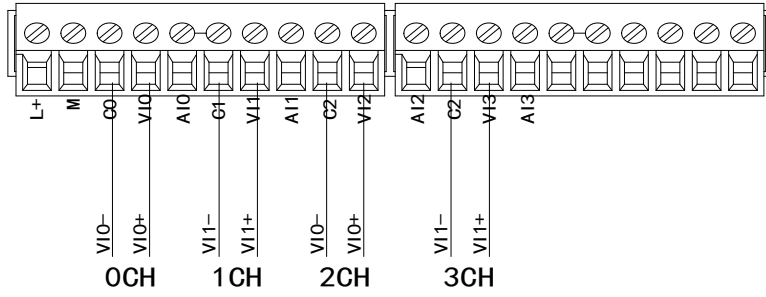
SFD350=64FEH SFD351=2301H SFD352=0000H SFD353=0000H

9-5. Exterior connection

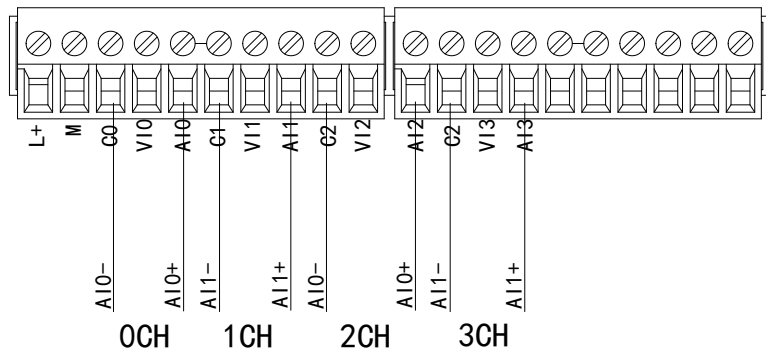
When make external connection, please note the following items:

- To avoid interference, please use shield cable and single-point ground with the shield layer.

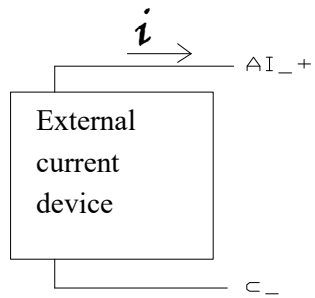
Voltage input



Current input



XL-E4AD current input wiring:



Note: it no needs to connect DC24V power supply for current output.

9-6. AD conversion diagram

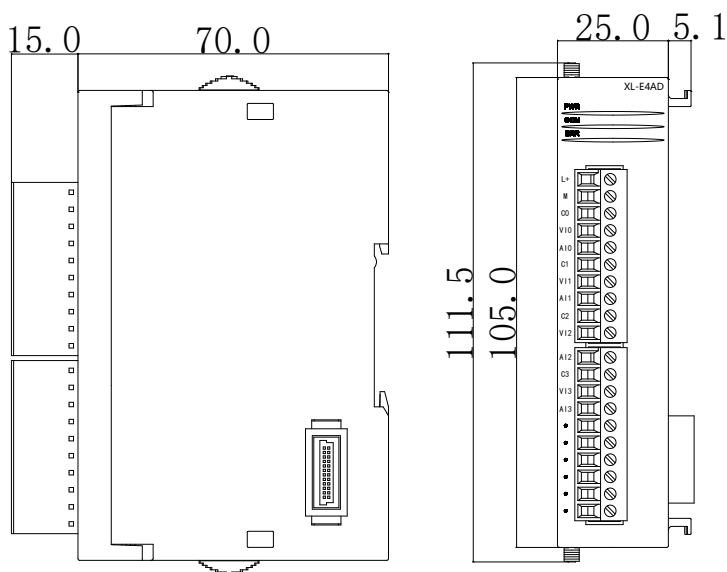
The relationship between analog input and converted digital value is shown in the following chart:

| 0~5V analog input | 0~10V analog input |
|-----------------------|----------------------|
| | |
| -5~5V analog input | -10~10V analog input |
| | |
| 0~20mA analog input | 4~20mA analog input |
| | |
| -20~20mA analog input | |
| | |

Note: When the channel enable switch is turned on and the AD voltage input is suspended, the corresponding ID register is displayed as 16383; When the AD current input is suspended, the corresponding ID register is displayed as 0. When the channel enable switch is turned off, the ID register corresponding to the AD voltage/current input is displayed as 0.

9-7. Dimension

(Unit: mm)



9-8. Programming

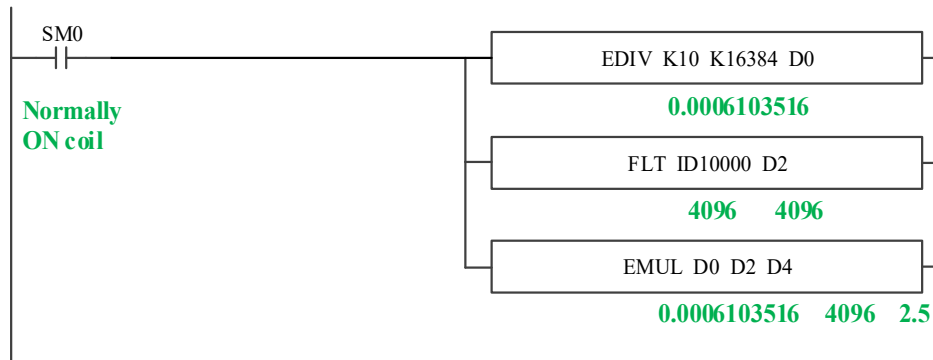
For example, the output signal of the existing pressure sensor needs to be collected (performance parameters of the pressure sensor: the detection pressure range is 0Mp~10Mpa, and the output analog signal is 4~20mA).

Analysis: because the pressure detection range of the pressure sensor is 0Mp~10Mpa, the corresponding output analog quantity is 4~20mA, and the digital quantity range of the expansion module converted by analog-to-digital conversion is 0~16383. So we can skip the analog quantity 4~20mA of the intermediate conversion link, which is directly the digital quantity range 0~16383 corresponding to the pressure detection range of 0Mp~10mp. $10\text{Mp}/16384=0.0006103515$ is the pressure value corresponding to each digit 1 of the digital quantity collected by the expansion module, so the real-time pressure of the current pressure sensor can be calculated by multiplying the real-time value collected in the expansion module ID register by 0.0006103515. For example, if the digital quantity collected in the ID register is 4096, the corresponding pressure is 2.5Mp.

Note:

- (1) First, set the enable bit corresponding to the first channel, namely Y10000, to ON.
- (2) Please use floating-point operation for calculation, otherwise the calculation accuracy will be affected or even cannot be calculated!

The program is as follows:



Explanation:

SM0 is normally ON coil, which is always ON during PLC operation.

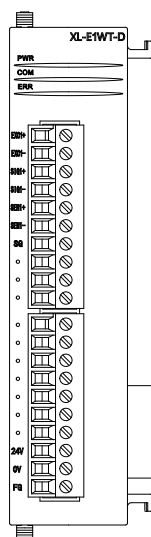
The PLC starts to run, and the analog quantity acquisition first calculates the pressure value corresponding to each digit 1 of the digital quantity collected by the expansion module, and then converts the digital quantity (integer) collected in the ID10000 register into a floating point number. Therefore, the current real-time pressure value can be calculated by multiplying the real-time value collected in the ID10000 register of the expansion module by the pressure value corresponding to each digit 1 of the digital quantity collected by the expansion module.

10. N channel pressure measurement module XL-EnWT-D

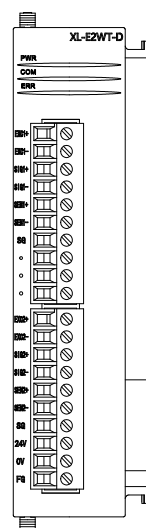
10-1. Features

XL-EnWT pressure measurement module can be used to detect 1/2/4 channels -20~20mV voltage signal or collect voltage signal of pressure sensor, and convert analog voltage value into digital value through A/D and perform operation.

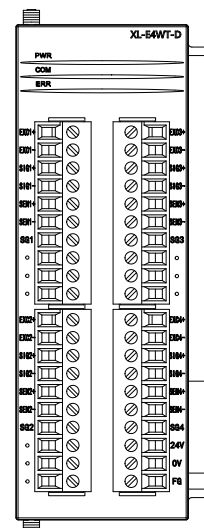
XL-E1WT-D



XL-E2WT-D



XL-E4WT-D



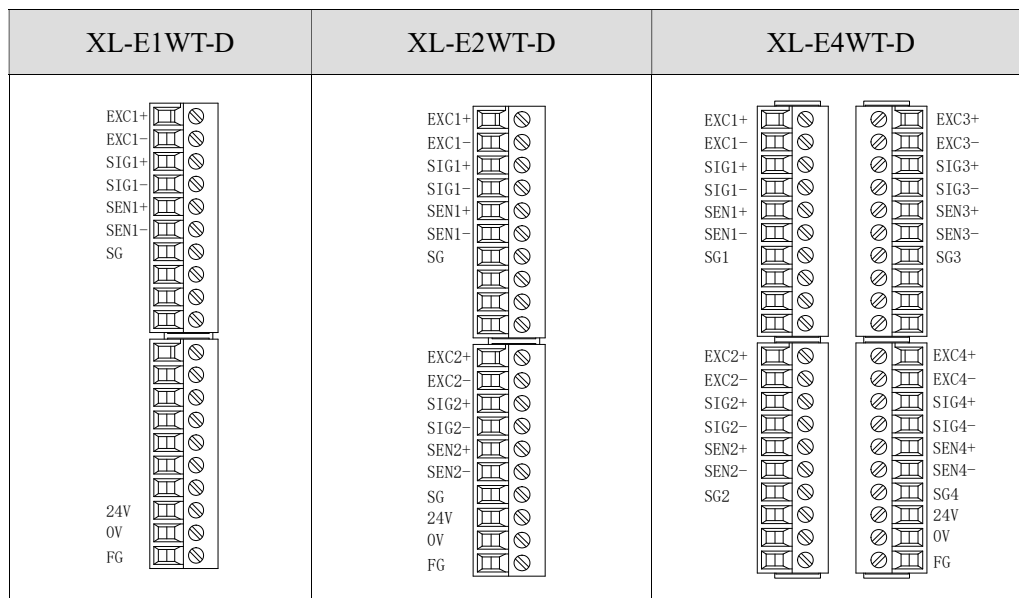
Features:

- The analog voltage signal of 1 / 2 / 4 channel pressure sensor can be collected.
- It can detect the voltage signal of -20~20mV.
- 23-bit high precision A / D conversion.
- As a special functional module of the XL series, XL3 can connect up to 10 modules, XL5/XL5E/XL5N/XL5H/XLME/XLH/XSLH can expand 16 modules, and XL1 does not support expansion modules.

Specifications:

| | |
|------------------------|---|
| Input range | DC -20~20mV |
| AD real resolution | 1/8388607 (23Bit) |
| Max display resolution | 1/500000 |
| Non-linear | 0.01%F.S |
| Transformation speed | 150/300/450 times/second (optional) |
| Power supply | DC24V±10% |
| Sensor power supply | 5VDC/120mA, can parallel 4 pieces of 350Ω pressure sensor |
| Installation | Mount on DIN46277 rail (width 35mm) or fix with screw M3 |
| Software version | V3.7.4b and higher version |
| Working environment | No corrosive gas |
| Ambient temperature | -10°C~50°C |
| Humidity | 5~95%RH (no condensation) |

10-2. Terminals



XL-E1WT-D, XL-E2WT-D, XL-E4WT-D:

| | Name | Function | | | |
|-----------------|------|--|---------------|--|--|
| LED | PWR | This indicator is on when the module has power supply | | | |
| | COM | This indicator is on when the module communication port communicates normally | | | |
| | ERR | <p>When there is an error in the module, the indicator is always on or flashing.</p> <p>When the ERR light is always on, it means that the module cannot be used due to serious application errors, and the use mode must be adjusted, and the PLC body is switched to the STOP state.</p> <p>When the ERR light flashes, it indicates that the module has application error, abnormal operation and abnormal data, but the PLC body is still running.</p> | | | |
| Wiring terminal | CH1 | EXC1+ | Excitation + | Connected to the power input terminal of the sensor | |
| | | EXC1- | Excitation - | | |
| | | SIG1+ | Signal + | Connected to sensor signal output terminal | |
| | | SIG1- | Signal - | | |
| | | SEN1+ | Feedback + | Connected to sensor feedback voltage output terminal | |
| | | SEN1- | Feedback - | | |
| | | SG | Signal ground | Connected to sensor signal cable ground wire | |
| | CH2 | EXC2+ | Excitation + | Connected to the power input terminal of the sensor | |
| | | EXC2- | Excitation - | | |
| | | SIG2+ | Signal + | Connected to sensor signal output terminal | |
| | | SIG2- | Signal - | | |
| | | SEN2+ | Feedback + | Connected to sensor feedback voltage output terminal | |
| | | SEN2- | Feedback - | | |
| | | SG | Signal ground | Connected to sensor signal cable ground wire | |
| Wiring terminal | CH3 | EXC3+ | Excitation + | Connected to the power input terminal of the sensor | |
| | | EXC3- | Excitation - | | |
| | | SIG3+ | Signal + | Connected to sensor signal output terminal | |
| | | SIG3- | Signal - | | |
| | | SEN3+ | Feedback + | Connected to sensor feedback voltage output terminal | |
| | | SEN3- | Feedback - | | |
| | | SG | Signal ground | Connected to sensor signal cable ground wire | |
| | CH4 | EXC4+ | Excitation + | Connected to the power input terminal of the sensor | |
| | | EXC4- | Excitation - | | |
| | | SIG4+ | Signal + | Connected to sensor signal output terminal | |
| | | SIG4- | Signal - | | |
| | | SEN4+ | Feedback + | Connected to sensor feedback voltage output terminal | |
| | | SEN4- | Feedback - | | |
| | | SG | Signal ground | Connected to sensor signal cable ground wire | |
| | - | L+, M | Power supply | Give the power supply for the module, DC24V±10% | |

| | | | | |
|--|--|----|---------------------|---------------------------------|
| | | FG | Power supply ground | Power supply grounding terminal |
|--|--|----|---------------------|---------------------------------|

Note: XL-E1WT-D has no CH2~CH4 channel, and XL-E2WT-D has no CH3~CH4 channel.

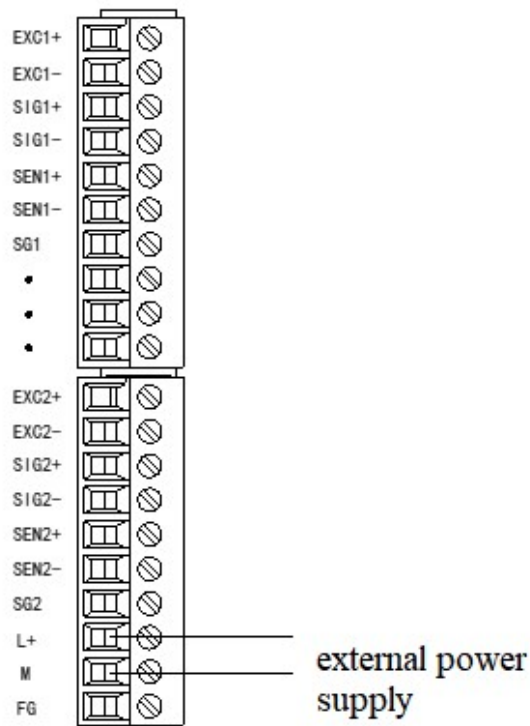
When wiring the module, its connector shall meet the following requirements:

- (1) Stripping length: 9mm.
- (2) Flexible cable with tubular bare end 0.25-1.5mm².
- (3) Flexible cable with tubular pre-insulated end is 0.25-0.5mm².

10-3. External connection

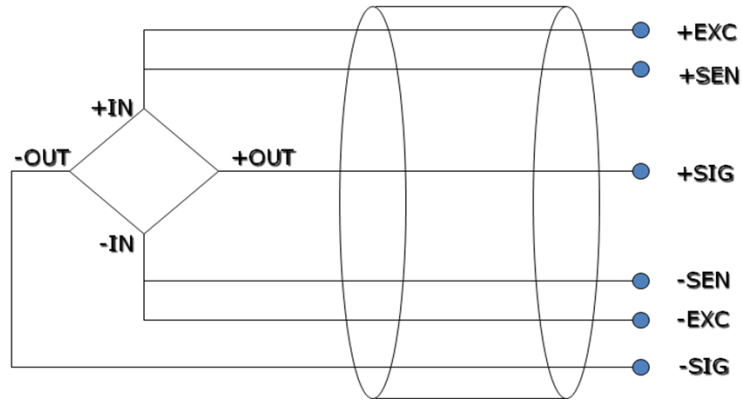
Please use shield cable and single-point connect to the ground for shield layer.

Power supply wiring

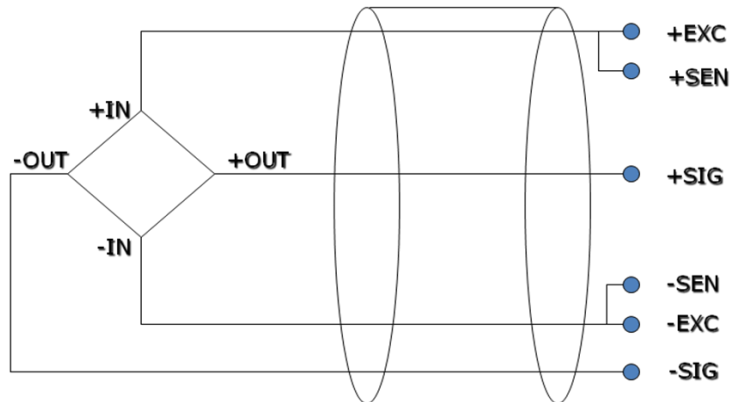


Connect to sensor

6 wires mode:



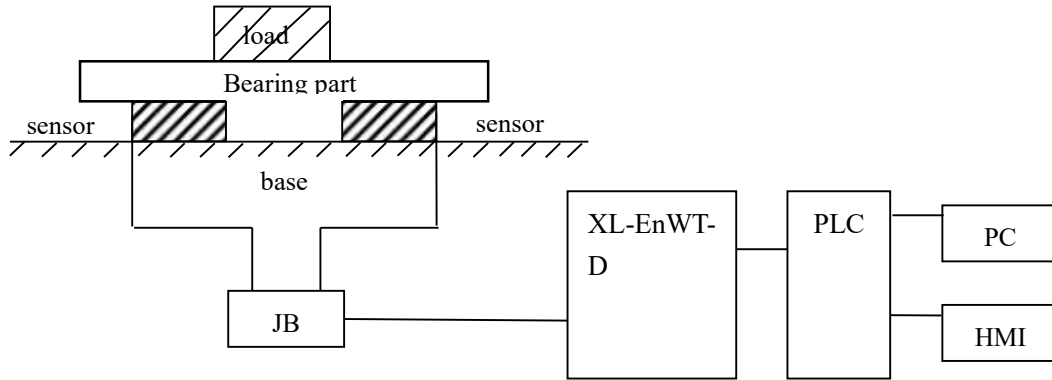
4 wires mode:



Note: short connect EXC1- and SEN1-, short connect EXC1+ and SEN1+ for 4 wires mode sensor.

10-4. Weighing system

A typical weighing system:



Loading bearing part: to support the load. Such as flat, hopper, container, air transport car...

Pressure sensor: transform the weight to voltage signal.

Assembly part: make sure the pressure sensor can work correctly, assembly part and direct part can avoid overload. Overload will cause measurement error and sensor damage.

Connection box (JB): to collect several sensor signals.

XL-EnWT-D: can be used as an electronic assessment device, it gets the pressure sensor signal and makes further assessment.

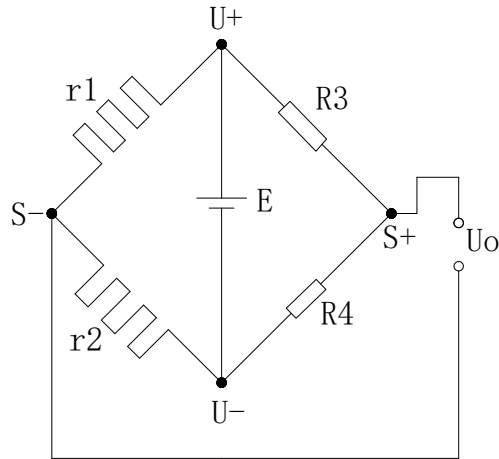
10-5. Module functions

XL-EnWT-D has the follow functions:

- Adjust the pressure sensor
- Collect the pressure sensor signal
- Calculate the weight value
- -20~20mV voltage signal test

10-5-1. Pressure sensor

The pressure sensor is based on resistance strain effect, see the following diagram:



R1 and R2 is strain resistor which make bridge circuit with R3 and R4. With the change of R1 and R2, the bridge circuit will lose the balance, unbalance voltage U_o will be produced as the output of sensor.

U_+ and U_- are positive and negative point of the sensor power supply. Please select the 5V power of the module or from outside.

S_+ and S_- are positive and negative point of the sensor output. Connect the output to the module to test the weight.

10-6. I/O address

The I/O address of module 1:

| Soft component | | Address | Explanation | Note |
|----------------|-----|---------|------------------------|------|
| Output coil | CH1 | Y10000 | Filter level | |
| | | Y10001 | Reset | |
| | | Y10002 | Zero point calibration | |
| | | Y10003 | Gain calibration | |
| | CH2 | Y10004 | Filter level | |
| | | Y10005 | Reset | |
| | | Y10006 | Zero point calibration | |
| | | Y10007 | Gain calibration | |
| | CH3 | Y10010 | Filter level | |
| | | Y10011 | Reset | |
| | | Y10012 | Zero point calibration | |
| | | Y10013 | Gain calibration | |
| | CH4 | Y10014 | Filter level | |
| | | Y10015 | Reset | |
| | | Y10016 | Zero point calibration | |
| | | Y10017 | Gain calibration | |

| | | | | |
|----------------|-----|---------|---|--------------|
| | ALL | Y10020 | Back to out of factory value | |
| Input coil | CH1 | X10000 | Stable flag | |
| | | X10001 | Overflow flag | |
| | | X10002 | Calibration success flag | |
| | | X10003 | Calibration failure flag | |
| | | X10020 | AD update flag | |
| | CH2 | X10004 | Stable flag | |
| | | X10005 | Overflow flag | |
| | | X10006 | Calibration success flag | |
| | | X10007 | Calibration failure flag | |
| | | X10021 | AD update flag | |
| | CH3 | X10010 | Stable flag | |
| | | X10011 | Overflow flag | |
| | | X10012 | Calibration success flag | |
| | | X10013 | Calibration failure flag | |
| | | X10022 | AD update flag | |
| | CH4 | X10014 | Stable flag | |
| | | X10015 | Overflow flag | |
| | | X10016 | Calibration success flag | |
| | | X10017 | Calibration failure flag | |
| | | X10023 | AD update flag | |
| Input register | CH1 | ID10000 | Present weight | Double words |
| | | ID10002 | Present digital value/present input voltage | Double words |
| | CH2 | ID10004 | Present weight | Double words |
| | | ID10006 | Present digital value/present input voltage | Double words |
| | CH3 | ID10008 | Present weight | Double words |
| | | ID10010 | Present digital value/present input voltage | Double words |
| | CH4 | ID10012 | Present weight | Double words |
| | | ID10014 | Present digital value/present input voltage | Double words |

The I/O address of module 2:

| Soft component | | Address | Explanation | Note |
|----------------|-----|---------|------------------------------|--------------|
| Output coil | CH1 | Y10100 | Filter level | |
| | | Y10101 | Reset | |
| | | Y10102 | Zero point calibration | |
| | | Y10103 | Gain calibration | |
| | CH2 | Y10104 | Filter level | |
| | | Y10105 | Reset | |
| | | Y10106 | Zero point calibration | |
| | | Y10107 | Gain calibration | |
| | CH3 | Y10110 | Filter level | |
| | | Y10111 | Reset | |
| | | Y10112 | Zero point calibration | |
| | | Y10113 | Gain calibration | |
| | CH4 | Y10114 | Filter level | |
| | | Y10115 | Reset | |
| | | Y10116 | Zero point calibration | |
| | | Y10117 | Gain calibration | |
| | ALL | Y10120 | Back to out of factory value | |
| Input coil | CH1 | X10100 | Stable flag | |
| | | X10101 | Overflow flag | |
| | | X10102 | Calibration success flag | |
| | | X10103 | Calibration failure flag | |
| | | X10120 | AD update flag | |
| | CH2 | X10104 | Stable flag | |
| | | X10105 | Overflow flag | |
| | | X10106 | Calibration success flag | |
| | | X10107 | Calibration failure flag | |
| | | X10121 | AD update flag | |
| | CH3 | X10110 | Stable flag | |
| | | X10111 | Overflow flag | |
| | | X10112 | Calibration success flag | |
| | | X10113 | Calibration failure flag | |
| | | X10122 | AD update flag | |
| | CH4 | X10114 | Stable flag | |
| | | X10115 | Overflow flag | |
| | | X10116 | Calibration success flag | |
| | | X10117 | Calibration failure flag | |
| | | X10123 | AD update flag | |
| | CH1 | ID10100 | Present weight | Double words |

| | | | | |
|----------------|-----|---|---|--------------|
| Input register | | ID10102 | Present digital value/present input voltage | Double words |
| | CH2 | ID10104 | Present weight | Double words |
| | | ID10106 | Present digital value/present input voltage | Double words |
| | CH3 | ID10108 | Present weight | Double words |
| | | ID10110 | Present digital value/present input voltage | Double words |
| | CH4 | ID10112 | Present weight | Double words |
| ID10114 | | Present digital value/present input voltage | Double words | |

.....

The I/O address of module 16:

| Soft component | | Address | Explanation | Note |
|----------------|--------|------------------------------|--------------------------|------|
| Output coil | CH1 | Y11500 | Filter level | |
| | | Y11501 | Reset | |
| | | Y11502 | Zero point calibration | |
| | | Y11503 | Gain calibration | |
| | CH2 | Y11504 | Filter level | |
| | | Y11505 | Reset | |
| | | Y11506 | Zero point calibration | |
| | | Y11507 | Gain calibration | |
| | CH3 | Y11510 | Filter level | |
| | | Y11511 | Reset | |
| | | Y11512 | Zero point calibration | |
| | | Y11513 | Gain calibration | |
| | CH4 | Y11514 | Filter level | |
| | | Y11515 | Reset | |
| | | Y11516 | Zero point calibration | |
| | | Y11517 | Gain calibration | |
| ALL | Y10020 | Back to out of factory value | | |
| Input coil | CH1 | X11500 | Stable flag | |
| | | X11501 | Overflow flag | |
| | | X11502 | Calibration success flag | |
| | | X11503 | Calibration failure flag | |
| | | X11520 | AD update flag | |
| | CH2 | X11504 | Stable flag | |

| | | | | |
|---------|----------------|---------|---|----------------|
| | | X11505 | Overflow flag | |
| | | X11506 | Calibration success flag | |
| | | X11507 | Calibration failure flag | |
| | | X11521 | AD update flag | |
| | CH3 | X11510 | Stable flag | |
| | | X11511 | Overflow flag | |
| | | X11512 | Calibration success flag | |
| | | X11513 | Calibration failure flag | |
| | | X11522 | AD update flag | |
| | CH4 | X11514 | Stable flag | |
| | | X11515 | Overflow flag | |
| | | X11516 | Calibration success flag | |
| | | X11517 | Calibration failure flag | |
| | | X11523 | AD update flag | |
| | Input register | CH1 | ID11500 | Present weight |
| ID11502 | | | Present digital value/present input voltage | Double words |
| CH2 | | ID11504 | Present weight | Double words |
| | | ID11506 | Present digital value/present input voltage | Double words |
| CH3 | | ID11508 | Present weight | Double words |
| | | ID11510 | Present digital value/present input voltage | Double words |
| CH4 | | ID11512 | Present weight | Double words |
| | | ID11514 | Present digital value/present input voltage | Double words |

Note: XL-E1WT-D has no CH2~CH4, XL-E2WT-D has no CH3~CH4.

Address explanation:

| | |
|--------------------------|--|
| filter level | ON: filter level A, OFF: filter level B |
| Reset | The reset is valid in the reset range, not save zero point |
| zero point calibration | To calibrate the system zero point |
| gain calibration | To calibrate system linear |
| Stable flag | The signal output is effective when meeting the stable range and time |
| Overflow flag | When the signal voltage larger than 10mv, this signal output is effective |
| Calibration success flag | This signal output is effective when zero point calibration and gain calibration succeeded |
| Calibration failure | This signal output is effective when zero point calibration and gain |

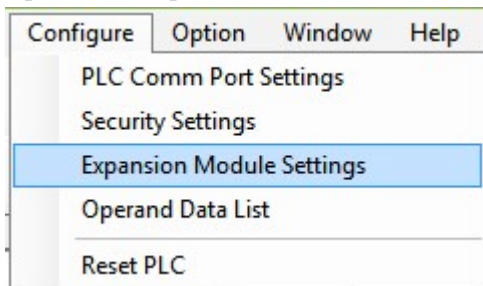
| | |
|---|--|
| flag | calibration failed (the detailed reasons please check module applicatoin error info) |
| AD update flag bit | AD value acquisition and setting ON once |
| Present digital value/present input voltage | Switch through upper device, when it is switched to present input voltage, the unit is mv, the decimal place is 4 bits |

10-7. Working mode

There are two methods to set the working mode:

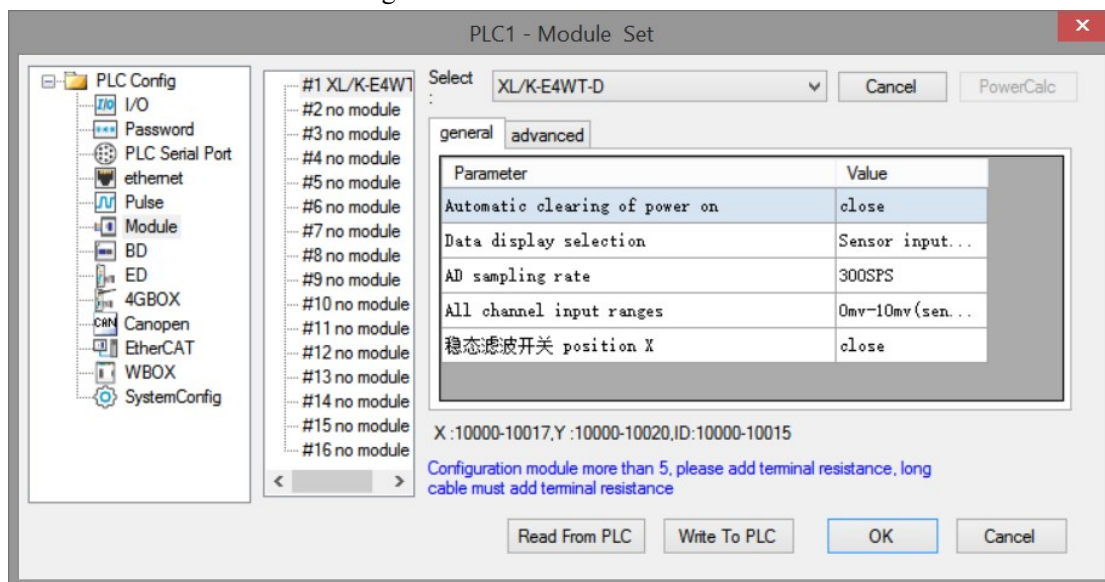
1. set through the control panel
2. set through Flash register

Open the XDPpro PLC software, click the menu configure/expansion module setting.



Set the model and channel parameters in the following window. Then click write to PLC.

Please restart the PLC after setting.



| Parameter | Function |
|--------------------------------|--|
| Automatic clearing of power on | After opening, the module will be reset automatically every time it is powered on. |
| Data display selection | Configuration switching can be performed. When switching to the current input voltage, the unit is mV and the decimal point is 4 digits; |

| | |
|----------------------------|--|
| AD sampling rate | Select AD sampling speed |
| All channel input ranges | Support -20~20mV voltage signal detection, can choose the range according to the demand |
| Steady state filter switch | Steady state filter switch, when set to off, the steady-state filter coefficient can be written, but it is invalid. When set to on, it is valid in steady state. |

Flash register setting:

The expansion module can set the gear and user-defined fast sampling frequency through PLC flash register SFD.

| Module no. | SFD address | Module no. | SFD address |
|------------|---------------|------------|---------------|
| #1 | SFD350~SFD359 | #9 | SFD430~SFD439 |
| #2 | SFD360~SFD369 | #10 | SFD440~SFD449 |
| #3 | SFD370~SFD379 | #11 | SFD450~SFD459 |
| #4 | SFD380~SFD389 | #12 | SFD460~SFD469 |
| #5 | SFD390~SFD399 | #13 | SFD470~SFD479 |
| #6 | SFD400~SFD409 | #14 | SFD480~SFD489 |
| #7 | SFD410~SFD419 | #15 | SFD490~SFD499 |
| #8 | SFD420~SFD429 | #16 | SFD500~SFD509 |

SFD350~SFD359 register explanation:

| SFD | | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | NOTE |
|--------|-------|--|------|------|---|------|--|--|------------------|------|
| SFD350 | Byte0 | AD sampling speed Range 0~2 Initial value: 1 0: 150 time/second 1: 300 time/second 2: 450 time/second | | | Steady state filtering 0: OFF 1: ON | | Sampling data mode Initial value: 0 0: sensor input voltage (mv) 1: AD sampling digital value | Automatic reset when power on Initial value: 0 0: OFF 1: ON | All the channels | |
| | Byte1 | - | | | | | | | | |

10-8. Module setting

Module parameter list:

| Address | Contents | Explanation | | Features |
|---------|---|--|------------------|-----------|
| K0 | Zero point tracking range | Range: 0~9 Initial value: 5 | All the channels | Word R/W |
| K1 | Zero point tracking time | Range: 10~5000 (ms) Initial value: 2000 | | Word R/W |
| K2 | Reset range | Range: 1~99 (%) Initial value: 50 | | Word R/W |
| K3 | Stable range | Range: 1~99 Initial value: 3 | | Word R/W |
| K4 | Stable time | Range: 10~5000 (ms) Initial value: 100 | | Word R/W |
| K5 | Filter level A | Range: 0~34 Initial value: 3 | | Word R/W |
| K6 | Filter level B | Range: 0~34 Initial value: 5 | | Word R/W |
| K8 | Steady state filter coefficient | Range: 0~34 Initial value: 0 | | Word R/W |
| K9 | - | | | |
| K10 | Return value of relative digital quantity in gain calibration | Gain calibration digital vlaue-zero-point Calibration digital value | CH1 | Dword R |
| K12 | Gain calibration weight value | Gain calibration weight value | | Dword R/W |
| K14 | CH1 min scale division | Range: 1,2,5,10,20,50 | | Word R/W |
| K15 | CH1 max range | Range: <= scale division×500000 | | Dword R/W |
| K20 | Return value of relative digital quantity in gain calibration | Gain calibration digital vlaue-zero-point Calibration digital value | CH2 | Dword R |
| K22 | Gain calibration weight value | Gain calibration weight value | | Dword R/W |
| K24 | CH2 min scale division | Range: 1,2,5,10,20,50 | | Word R/W |
| K25 | CH2 max range | Range: <= scale division×500000 | | Dword R/W |
| K27 | Reserved | | | |
| K30 | Return value of | Gain calibration digital vlaue- | | Dword R |

| | | | | |
|-----|---|---|-----|-----------|
| | relative digital quantity in gain calibration | zero-point Calibration digital value | | |
| K32 | Gain calibration weight value | Gain calibration weight value | CH3 | Dword R/W |
| K34 | CH3 min scale division | Range: 1,2,5,10,20,50 | | Word R/W |
| K35 | CH3 max range | Range: \leq scale division \times 500000 | | Dword R/W |
| K40 | Return value of relative digital quantity in gain calibration | Gain calibration digital vlaue-zero-point Calibration digital value | CH4 | Dword R |
| K42 | Gain calibration weight value | Gain calibration weight value | | Dword R/W |
| K44 | CH4 min scale division | Range: 1,2,5,10,20,50 | | Word R/W |
| K45 | CH4 max range | Range: \leq scale division \times 500000 | | Dword R/W |
| K47 | Reserved | | | |

Parameter notes:

1. Zero-point tracking range and time: If the weight value fluctuates in the range of K0 of zero point and the fluctuation lasts for K1 time, it is considered that the fluctuation value in this range is not recorded, and the weight value is displayed as 0.
2. Reset range: It is allowed to perform the reset action within the proportion range of the parameter maximum range.
3. Stable range and time: When the difference between the last weight value and the previous weight value is in K3 range and maintains K4 time, it is considered that the weight value at this time has been stable.

Take module no.1 as an example:

Weight unit setting:

Write in weight through instruction TO. For example, the object weight is 1kg, write in 1 means the unit is kg, write in 1000 means the unit is g, write in 10000 means the unit is 0.1g.
resolution=1kg/write in digital value.

Calibration:

Please calibrate the pressure sensor for the first time using.

Take module channel 1 as an example:

Step 1:

Confirm whether the module and sensor work properly.

Judgment method:

First, monitor whether the overflow flag X10001 is OFF state. If it is ON, the sensor is not connected or the sensor is damaged.

Second, using the software to monitor whether ID10002 value fluctuates following sensor (fluctuation range is related to sensor range), and pressure value increased when increasing the load, if there are value but increase the load stress value decreases, that means (1) sensor installed opposite, please adjust the sensor position or exchange +/- of sensor output signal; (2) The incoming voltage signal has been overflow, reducing the load appropriately.

Step 2:

Make the sensor no load, after the stable flag X10000 is ON, set ON zero-point calibration Y10002. X10002 ON means the zero-point calibration is successful. If after few seconds, X10003 is ON, that means zero-point calibration is failed.

Step 3:

Put the load whose weight is known on the scale, write the weight through TO instruction, after stable flag X10000 is ON, set ON gain calibration Y10003, X10002 ON means calibration is successful, shut off Y10003. If after few seconds, X10003 is ON, that means zero-point calibration is failed.

Step 4:

Hereto, the calibration finished. The module will automatic adjust the result according to the idle load value and calibration value when weighing, and finally get the correct weight.

10-9. Module error info

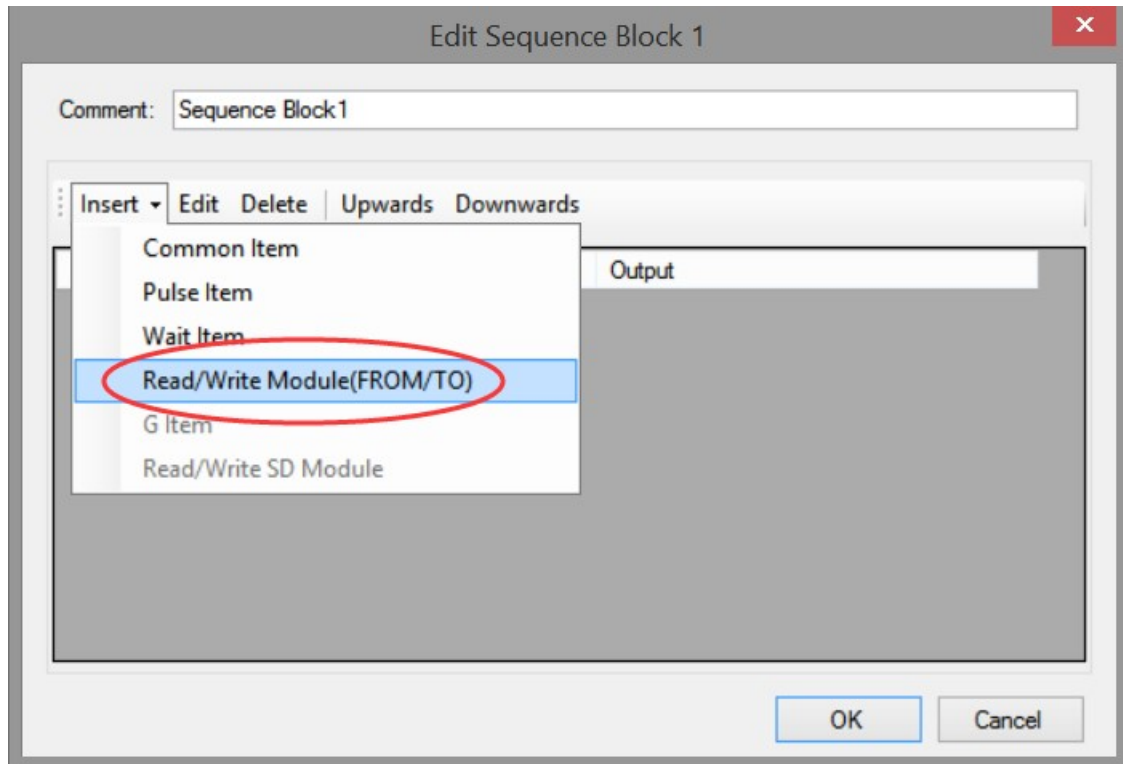
Serious application error (related to main unit register address SD503 high 8 bits)

| Error code | | | Meaning |
|------------|------|---------|------------------------------|
| Binary | Hex | Decimal | |
| 0000 0001 | 0x01 | 1 | Not connect 24V |
| 0000 0010 | 0x02 | 2 | Not finish the setting in 5s |
| 0000 0011 | 0x03 | 3 | Module model is different |
| 0000 0011 | 0x04 | 4 | Communicate with PLC error |

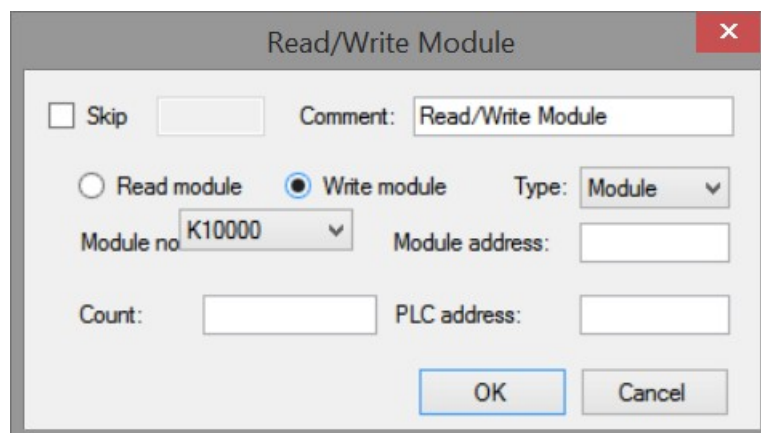
The error code using method: write in module no. in SD500, if it needs to check module no.1 error code, please write in 10000.

10-10. Instruction FROM and TO

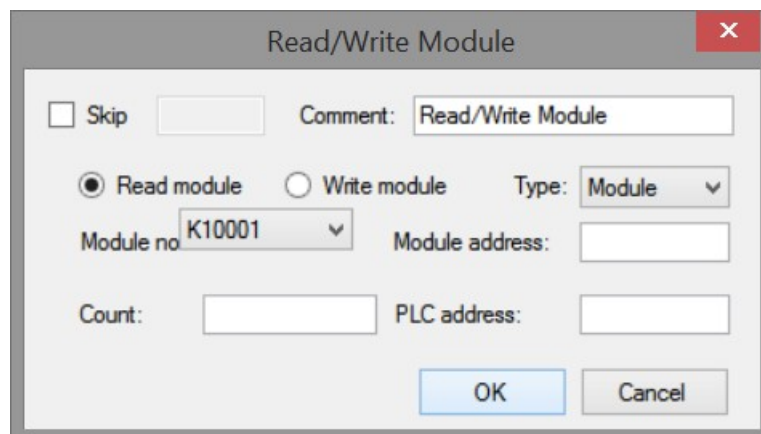
The reading and writing of XD-EnWT-D module needs to be completed through the FROM/TO instruction in the sequential function block, as shown in the figure below:



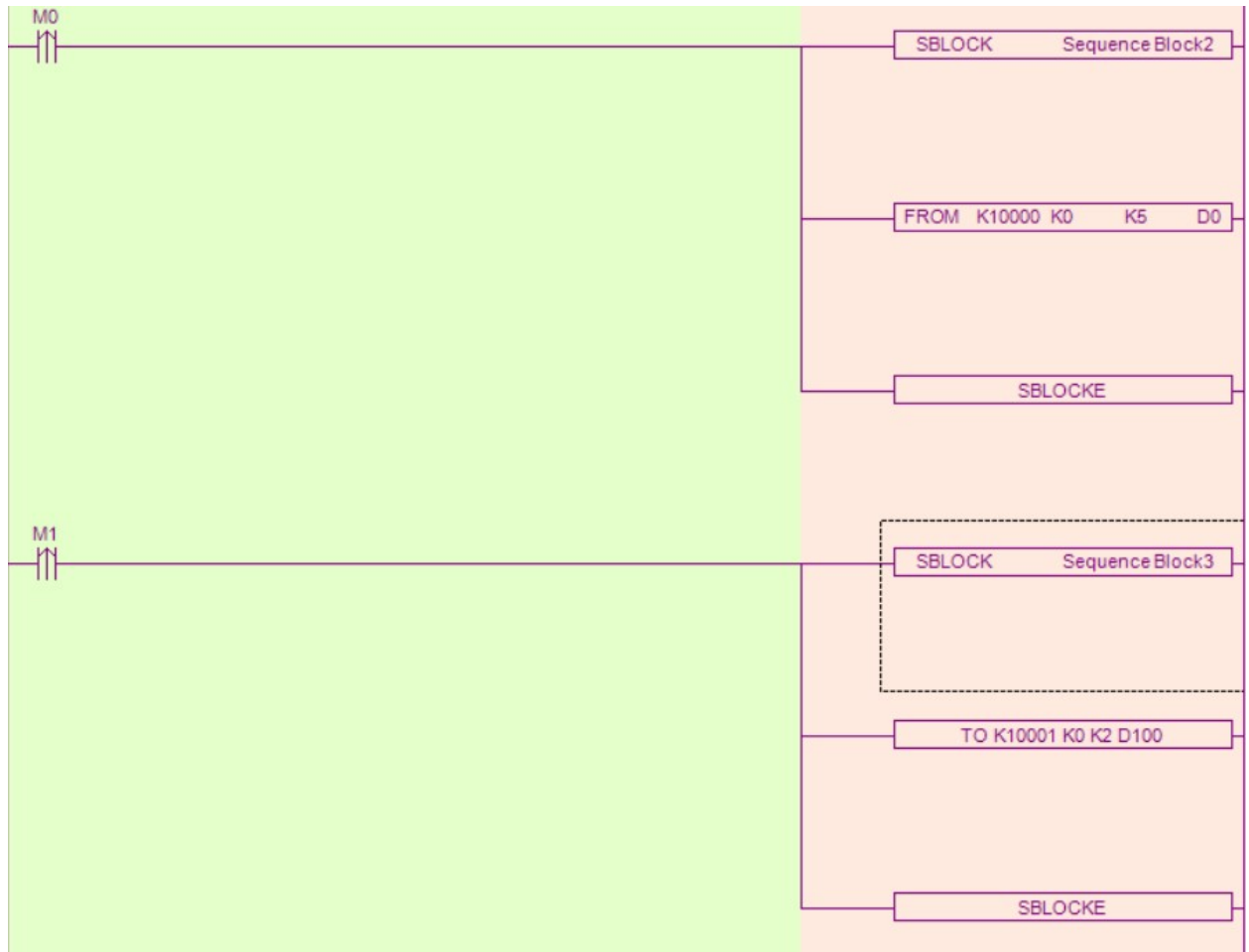
(a) Insert FROM/TO module



(b) Write instruction

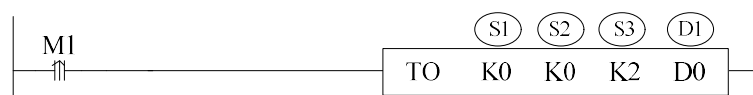


(c) Read instruction



(d) Ladder chart

Write instruction TO



Function: write the PLC register data to module specified address, the unit is word.

Operand:

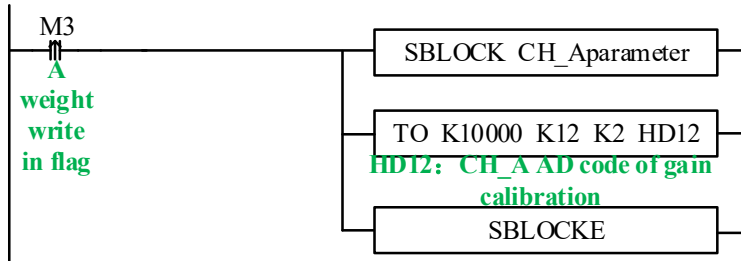
S1: target module number. Operand: K, TD, CD, D, HD, FD.

S2: module first address. Operand: K, TD, CD, D, HD, FD.

S3: write in register quantity. Operand: K, TD, CD, D, HD, FD.

D1: write in data register first address in PLC. Operand: TD, CD, D, HD, FD.

Example: write the weight value to module no.1 channel 1



Read instruction FROM



Function: read the module data to PLC register, the unit is word.

Operand:

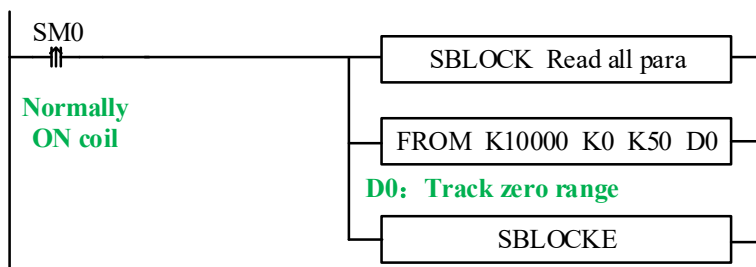
S1: target module number. Operand: K, TD, CD, D, HD, FD.

S2: module first address. Operand: K, TD, CD, D, HD, FD.

S3: read register quantity. Operand: K, TD, CD, D, HD, FD.

D1: PLC register first address. Operand: TD, CD, D, HD, FD.

For example: read all the parameters of module no.1



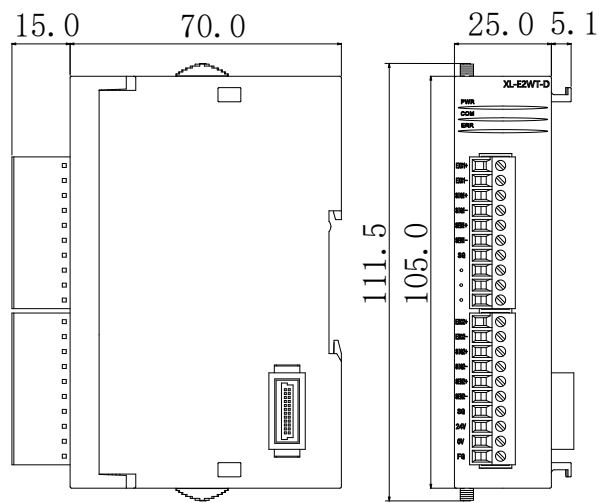
Note:

1. From/TO instruction can only be written in sequence function block, XL series PLC with firmware version v3.4.5 and above can write up to 100 blocks in the program, but can only run up to 8 blocks at the same time.
2. The starting number of module starts from k10000, k10000 is module 1 and k10001 is module 2. By analogy, module 16 is K10015.

10-11. Dimension

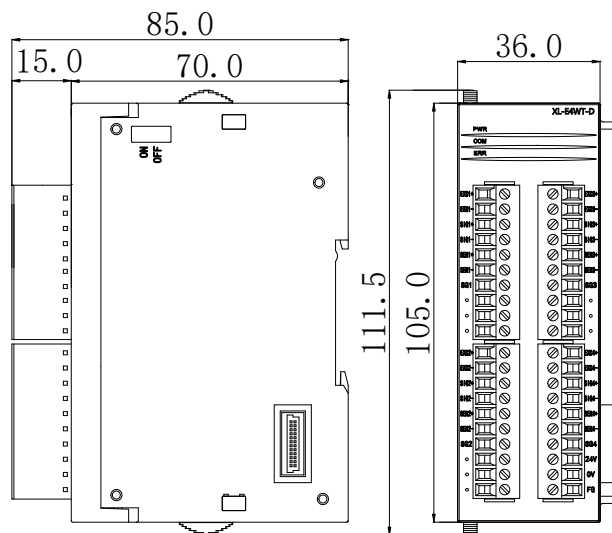
XL-E1WT-D, XL-E2WT-D

(Unit: mm)



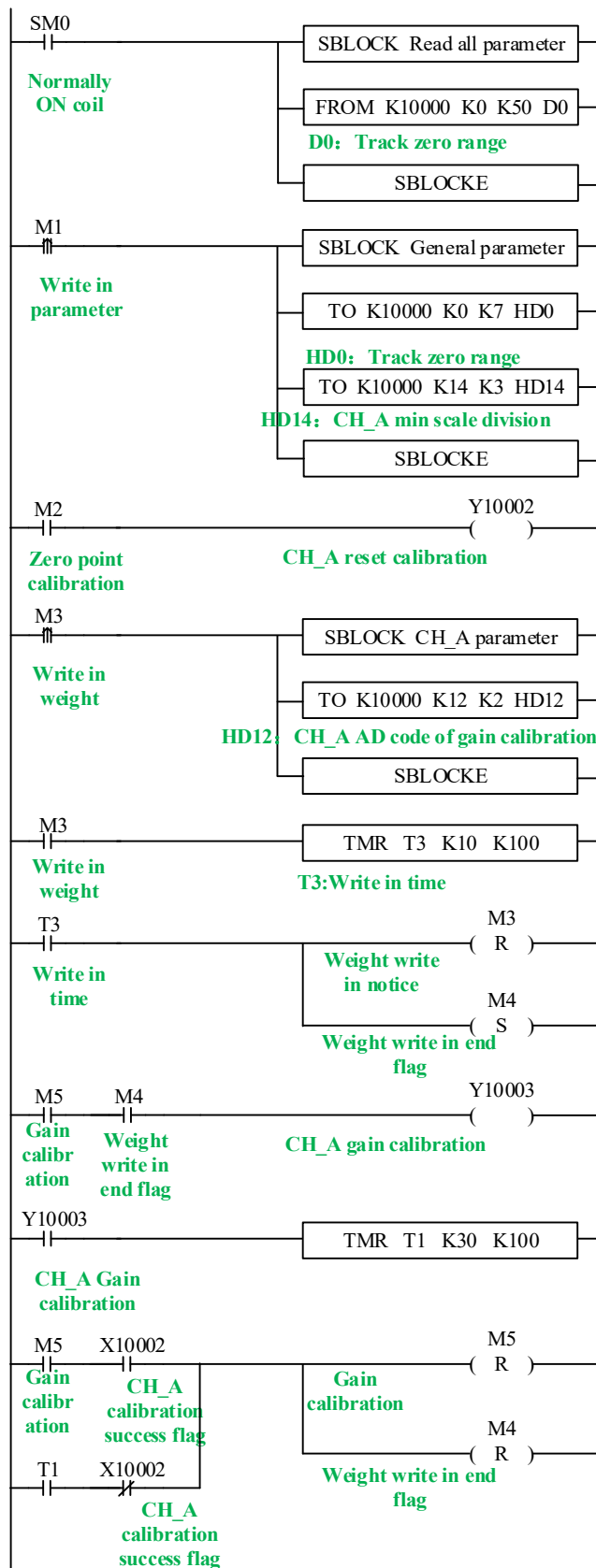
XL-E4WT-D

(Unit: mm)



10-12. Application program

Take module 1 as an example:



Explanation:

Read all the parameters and write in general parameters through FROM/TO instruction.

Set ON M1, write in all the parameters of channel 1.

Zero-point calibration: set ON M2, if zero-point calibration is successful, X10002 is set ON.

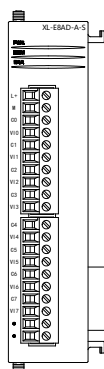
Gain calibration: first set ON M3, write the weight value HD12 to the module. After write in success flag M4 is ON, it starts to calibrate gain. Set ON M5 to start the calibration, the preset stable time is 3s. after the scale is stable, gain calibration success flag X10002 is ON or calibration time T1 reached, reset M4, M5, gain calibration is finished.

11. Analog input module XL-E8AD-A-S

This chapter mainly introduces XL-E8AD-A-S module specifications, terminal instructions, input definition number allocation, working mode settings, external connections, analog-to-digital conversion diagrams, appearance size diagrams and related programming examples.

11-1. Module features and specifications

XL-E8AD-A-S analog input module converts 8 analog current input values into digital values, and transmits them to the main unit of PLC, and interacts with the main unit of PLC in real time.



Module features

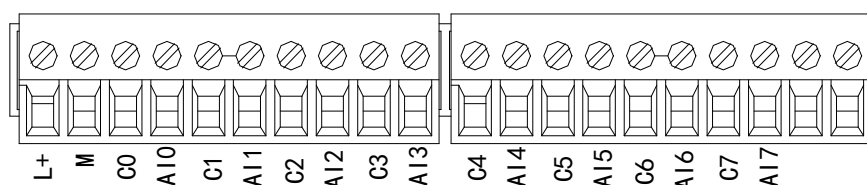
- 8-channel analog input: current input.
- 16-bit high-precision analog input.
- As a special functional module of the XL series, XL3 can connect up to 10 modules, XL5/XL5E/XL5N/XL5H/XLME/XLH/XSLH can expand 16 modules, and XL1 does not support expansion modules.

Module specification

| Item | Analog input |
|----------------------|---|
| | Current input |
| Analog input range | 0~20mA, 4~20mA, -20~20mA |
| Max input range | -40~40mA |
| Digital output range | 16 bits binary data (0~65535 or -32768~32767) |
| Resolution | 1/65535 (16Bit) |
| Integrated precision | ±1% |
| Conversion speed | 2ms/1 channel |
| Module power supply | DC24V±10%, 150mA |

11-2. Terminal descriptions

Terminal arrangement



Terminal signal

| Name | Function | |
|-----------------|----------|---|
| Indicator light | PWR | The indicator lights up when the module has a power supply. |
| | COM | When the module port communicates normally, the indicator lights on. |
| | ERR | When there is an error in the module, the indicator is always on or flickering (red). |

| | | |
|----------|----------------------------|---|
| | | <p>When the ERR LED is always on, it indicates that the module has serious application errors and can not be used. It is necessary to adjust the mode of use and switch the PLC to STOP state.</p> <p>When the ERR LED flickers, there are application errors, abnormal work and abnormal data in the module, but the PLC is still RUN.</p> |
| Terminal | L+ | Module 24V power supply input + |
| | M | Module 24V power supply input - |
| | C0 | AI0 output ground |
| | AI0 | Channel 1 AD current input |
| | C1 | AI1 output ground |
| | AI1 | Channel 2 AD current input |
| | C2 | AI2 output ground |
| | AI2 | Channel 3 AD current input |
| | C3 | AI3 output ground |
| | AI3 | Channel 4 AD current input |
| | C4 | AI4 output ground |
| | AI4 | Channel 5 AD current input |
| | C5 | AI5 output ground |
| | AI5 | Channel 6 AD current input |
| | C6 | AI6 output ground |
| | AI6 | Channel 7 AD current input |
| | C7 | AI7 output ground |
| AI7 | Channel 8 AD current input | |

Wiring head specification

When wiring the module, its wiring head should meet the following requirements:

- (1) The stripping length is 9 mm;
- (2) Flexible wires with bare tubular ends are 0.25-1.5 square.
- (3) Flexible wires with tubular pre-insulated end is 0.25-0.5 square.

11-3. I/O address

XL series analog module does not occupy I/O unit, the converted value is directly sent to the PLC register, the corresponding channel definition number of the PLC register is as follows:

Module 1 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID10000 | Y10000 | X10000 |
| 1CH | ID10002 | Y10001 | X10001 |
| 2CH | ID10004 | Y10002 | X10002 |
| 3CH | ID10006 | Y10003 | X10003 |
| 4CH | ID10008 | Y10004 | X10004 |
| 5CH | ID10010 | Y10005 | X10005 |
| 6CH | ID10012 | Y10006 | X10006 |
| 7CH | ID10014 | Y10007 | X10007 |

Module 2 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID10100 | Y10100 | X10100 |
| 1CH | ID10102 | Y10101 | X10101 |
| 2CH | ID10104 | Y10102 | X10102 |
| 3CH | ID10106 | Y10103 | X10103 |
| 4CH | ID10108 | Y10104 | X10104 |
| 5CH | ID10110 | Y10105 | X10105 |
| 6CH | ID10112 | Y10106 | X10106 |
| 7CH | ID101014 | Y10107 | X10107 |

Module 3 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID10200 | Y10200 | X10200 |
| 1CH | ID10202 | Y10201 | X10201 |
| 2CH | ID10204 | Y10202 | X10202 |
| 3CH | ID10206 | Y10203 | X10203 |
| 4CH | ID10208 | Y10204 | X10204 |
| 5CH | ID10210 | Y10205 | X10205 |
| 6CH | ID10212 | Y10206 | X10206 |
| 7CH | ID10214 | Y10207 | X10207 |

Module 4 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID10300 | Y10300 | X10300 |
| 1CH | ID10302 | Y10301 | X10301 |
| 2CH | ID10304 | Y10302 | X10302 |
| 3CH | ID10306 | Y10303 | X10303 |
| 4CH | ID10308 | Y10304 | X10304 |
| 5CH | ID10310 | Y10305 | X10305 |
| 6CH | ID10312 | Y10306 | X10306 |
| 7CH | ID10314 | Y10307 | X10307 |

Module 5 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID10400 | Y10400 | X10400 |
| 1CH | ID10402 | Y10401 | X10401 |
| 2CH | ID10404 | Y10402 | X10402 |
| 3CH | ID10406 | Y10403 | X10403 |
| 4CH | ID10408 | Y10404 | X10404 |
| 5CH | ID10410 | Y10405 | X10405 |
| 6CH | ID10412 | Y10406 | X10406 |
| 7CH | ID10414 | Y10407 | X10407 |

Module 6 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID10500 | Y10500 | X10500 |
| 1CH | ID10502 | Y10501 | X10501 |
| 2CH | ID10504 | Y10502 | X10502 |
| 3CH | ID10506 | Y10503 | X10503 |
| 4CH | ID10508 | Y10504 | X10504 |
| 5CH | ID10510 | Y10505 | X10505 |
| 6CH | ID10512 | Y10506 | X10506 |
| 7CH | ID10514 | Y10507 | X10507 |

Module 7 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID10600 | Y10600 | X10600 |
| 1CH | ID10602 | Y10601 | X10601 |
| 2CH | ID10604 | Y10602 | X10602 |
| 3CH | ID10606 | Y10603 | X10603 |
| 4CH | ID10608 | Y10604 | X10604 |
| 5CH | ID10610 | Y10605 | X10605 |
| 6CH | ID10612 | Y10606 | X10606 |
| 7CH | ID10614 | Y10607 | X10607 |

Module 8 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID10700 | Y10700 | X10700 |
| 1CH | ID10702 | Y10701 | X10701 |
| 2CH | ID10704 | Y10702 | X10702 |
| 3CH | ID10706 | Y10703 | X10703 |
| 4CH | ID10708 | Y10704 | X10704 |
| 5CH | ID10710 | Y10705 | X10705 |
| 6CH | ID10712 | Y10706 | X10706 |
| 7CH | ID10714 | Y10707 | X10707 |

Module 9 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID10800 | Y11000 | X11000 |
| 1CH | ID10802 | Y11001 | X11001 |
| 2CH | ID10804 | Y11002 | X11002 |
| 3CH | ID10806 | Y11003 | X11003 |
| 4CH | ID10808 | Y11004 | X11004 |
| 5CH | ID10810 | Y11005 | X11005 |
| 6CH | ID10812 | Y11006 | X11006 |
| 7CH | ID10814 | Y11007 | X11007 |

Module 10 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID10900 | Y11100 | X11100 |
| 1CH | ID10902 | Y11101 | X11101 |
| 2CH | ID10904 | Y11102 | X11102 |
| 3CH | ID10906 | Y11103 | X11103 |
| 4CH | ID10908 | Y11104 | X11104 |
| 5CH | ID10910 | Y11105 | X11105 |
| 6CH | ID10912 | Y11106 | X11106 |
| 7CH | ID10914 | Y11107 | X11107 |

Module 11 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID11000 | Y11200 | X11200 |
| 1CH | ID11002 | Y11201 | X11201 |
| 2CH | ID11004 | Y11202 | X11202 |
| 3CH | ID11006 | Y11203 | X11203 |
| 4CH | ID11008 | Y11204 | X11204 |
| 5CH | ID11010 | Y11205 | X11205 |
| 6CH | ID11012 | Y11206 | X11206 |
| 7CH | ID11014 | Y11207 | X11207 |

Module 12 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID11100 | Y11300 | X11300 |
| 1CH | ID11102 | Y11301 | X11301 |
| 2CH | ID11104 | Y11302 | X11302 |
| 3CH | ID11106 | Y11303 | X11303 |
| 4CH | ID11108 | Y11304 | X11304 |
| 5CH | ID11110 | Y11305 | X11305 |
| 6CH | ID11112 | Y11306 | X11306 |
| 7CH | ID11114 | Y11307 | X11307 |

Module 13 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID11200 | Y11400 | X11400 |
| 1CH | ID11202 | Y11401 | X11401 |
| 2CH | ID11204 | Y11402 | X11402 |
| 3CH | ID11206 | Y11403 | X11403 |
| 4CH | ID11208 | Y11404 | X11404 |
| 5CH | ID11210 | Y11405 | X11405 |
| 6CH | ID11212 | Y11406 | X11406 |
| 7CH | ID11214 | Y11407 | X11407 |

Module 14 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID11300 | Y11500 | X11500 |
| 1CH | ID11302 | Y11501 | X11501 |
| 2CH | ID11304 | Y11502 | X11502 |
| 3CH | ID11306 | Y11503 | X11503 |
| 4CH | ID11308 | Y11504 | X11504 |
| 5CH | ID11310 | Y11505 | X11505 |
| 6CH | ID11312 | Y11506 | X11506 |
| 7CH | ID11314 | Y11507 | X11507 |

Module 15 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID11400 | Y11600 | X11600 |
| 1CH | ID11402 | Y11601 | X11601 |
| 2CH | ID11404 | Y11602 | X11602 |
| 3CH | ID11406 | Y11603 | X11603 |
| 4CH | ID11408 | Y11604 | X11604 |
| 5CH | ID11410 | Y11605 | X11605 |
| 6CH | ID11412 | Y11606 | X11606 |
| 7CH | ID11414 | Y11607 | X11607 |

Module 16 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID11500 | Y11700 | X11700 |
| 1CH | ID11502 | Y11701 | X11701 |
| 2CH | ID11504 | Y11702 | X11702 |
| 3CH | ID11506 | Y11703 | X11703 |
| 4CH | ID11508 | Y11704 | X11704 |
| 5CH | ID11510 | Y11705 | X11705 |
| 6CH | ID11512 | Y11706 | X11706 |
| 7CH | ID11514 | Y11707 | X11707 |

Note:

- (1) Banning unused channels can improve the scanning speed of input/output.
- (2) When the input enabling switch is turned off during operation, the corresponding input channel will not collect data. (Data display is 0)

11-4. Working mode settings

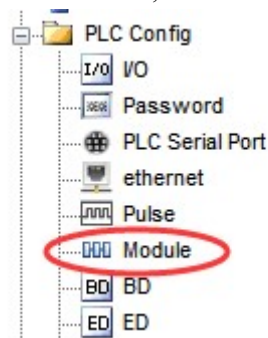
There are two ways to set the working mode (the effect of these two ways is equivalent):

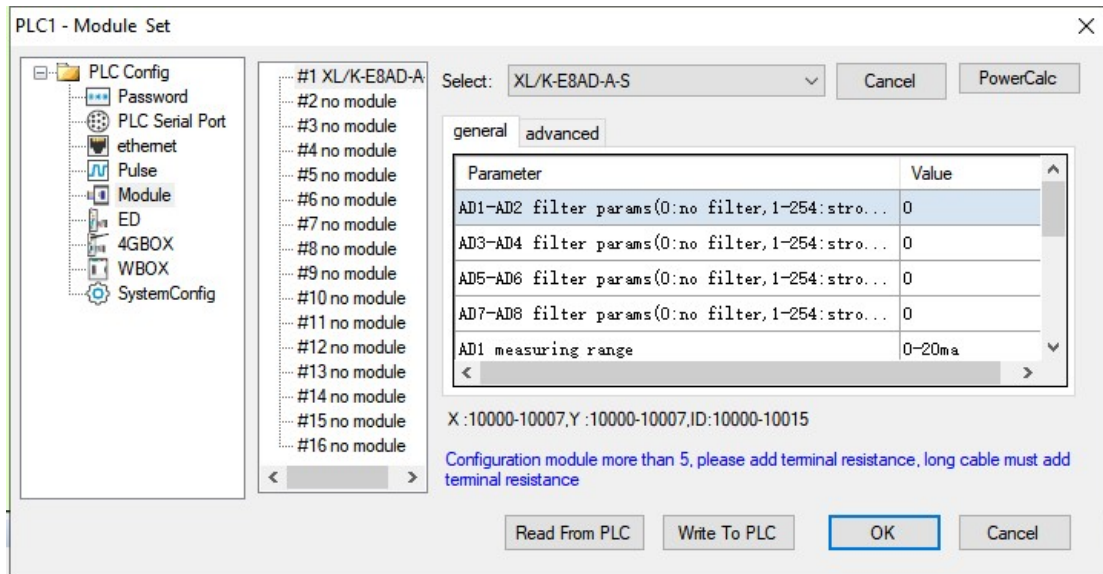
- (1) Configuration through the software
- (2) Setting up by Flash Register

Set through the software

Please use XDPpro v3.5.1 or higher version software to configure the module.

Open the software, click module in the left menu,





Choose the module type, and set each channel's parameters in the above window. Then click write to PLC, cut the power supply and power on again to make the settings effective.

Note: The first-order low-pass filtering method weighs this time sampling value and the output value of the last filtering to get the effective filtering value; the filter coefficient is set by the user to 0-254, the smaller the value, the more stable the data, but may lead to data lag; therefore, when set to 1, the filtering effect is strongest and the data is the most stable; when set to 254, the filtering effect is the weakest; default is 0 (no filtering).

Set by Flash register

The input channel of the extended module is current mode, with 0-20mA, 4-20mA and -20-20mA optional. It is set by special FLASH data register SFD in PLC. As follows:

| Module no. | SFD register | Module no. | SFD register |
|------------|---------------|------------|---------------|
| #1 | SFD350~SFD359 | #9 | SFD430~SFD439 |
| #2 | SFD360~SFD369 | #10 | SFD440~SFD449 |
| #3 | SFD370~SFD379 | #11 | SFD450~SFD459 |
| #4 | SFD380~SFD389 | #12 | SFD460~SFD469 |
| #5 | SFD390~SFD399 | #13 | SFD470~SFD479 |
| #6 | SFD400~SFD409 | #14 | SFD480~SFD489 |
| #7 | SFD410~SFD419 | #15 | SFD490~SFD499 |
| #8 | SFD420~SFD429 | #16 | SFD500~SFD509 |

Note: As shown above, each register sets four-channel modes. Each register has 16 bits. From low to high, each four bit will set four-channel modes in turn.

SFD bit definition

| | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | NOTE |
|------------------|---|------|------|----------------|--------------|------|------|------|---|
| Byte0 | AD channel 2, channel 1 filtering parameter | | | | | | | | AD filtering parameter |
| Byte1 | AD channel 4, channel 3 filtering parameter | | | | | | | | |
| Byte2 | AD channel 6, channel 5 filtering parameter | | | | | | | | |
| Byte3 | AD channel 8, channel 7 filtering parameter | | | | | | | | |
| Byte4 | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | Set the AD module input range, Byte4 low 4-bit set AD channel1, high 4-bit set AD channel2. Byte5 low 4-bit set AD channel3, high 4-bit set AD channel4, Byte6 low 4-bit set AD channel5, high 4-bit set AD channel6, Byte7 low 4-bit set AD channel7, high 4-bit set AD channel8. |
| | AD2 | | | | AD1 | | | | |
| | 1000: 0~20mA | | | | 1000: 0~20mA | | | | |
| | 1001: 4~20mA | | | | 1001: 4~20mA | | | | |
| 1010: -20~20mA | | | | 1010: -20~20mA | | | | | |
| Byte5 | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | |
| | AD4 | | | | AD3 | | | | |
| | 1000: 0~20mA | | | | 1000: 0~20mA | | | | |
| | 1001: 4~20mA | | | | 1001: 4~20mA | | | | |
| 1010: -20~20mA | | | | 1010: -20~20mA | | | | | |
| Byte6 | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | |
| | AD6 | | | | AD5 | | | | |
| | 1000: 0~20mA | | | | 1000: 0~20mA | | | | |
| | 1001: 4~20mA | | | | 1001: 4~20mA | | | | |
| 1010: -20~20mA | | | | 1010: -20~20mA | | | | | |
| Byte7 | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | |
| | AD8 | | | | AD7 | | | | |
| | 1000: 0~20mA | | | | 1000: 0~20mA | | | | |
| | 1001: 4~20mA | | | | 1001: 4~20mA | | | | |
| 1010: -20~20mA | | | | 1010: -20~20mA | | | | | |
| Byte8~ Byte19 | - | | | | | | | | |

Take the first module as an example to illustrate how to set it up.

Example: To set the working modes of input channels 1 and 0 of the first module to be 0-20 mA, input channels 3 and 2 to be 4-20 mA, input channels 5 and 4 to be 0-20 mA, input channels 7 and 6 to be -20-20 mA, filter coefficients of channels 0, 1, 2 and 3 to be 254, filter coefficients of channels 4, 5, 6 and 7 to be 100.

Method 1:

You can configure it directly in the PLC software, as shown above.

Method 2:

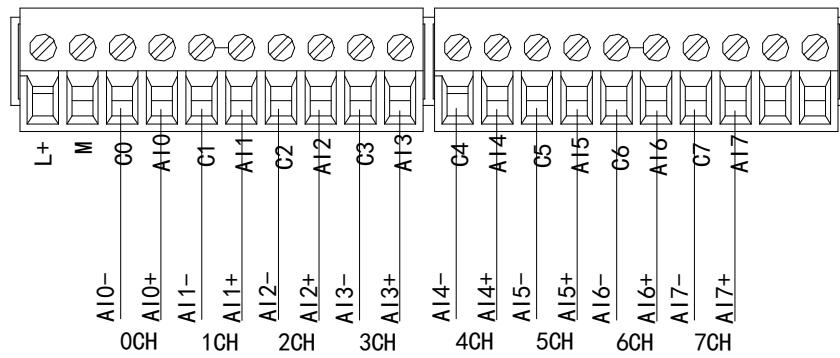
Set the SFD as follows:

SFD350=FEFEH SFD351=6464H SFD352=9988H SFD353=AA88H

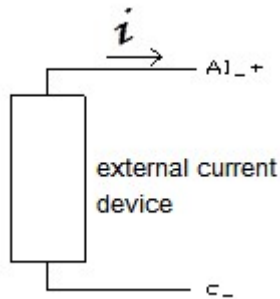
11-5. External wiring

For external connection, to avoid interference, use shielding wire and connect the ground to the single point of shielding layer.

Current input

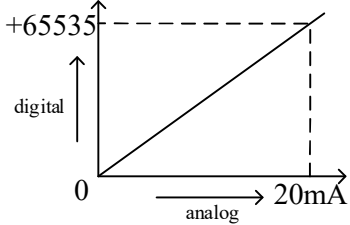
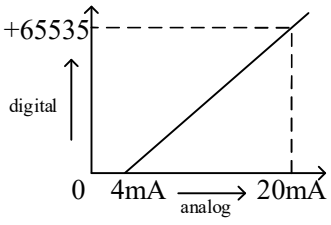
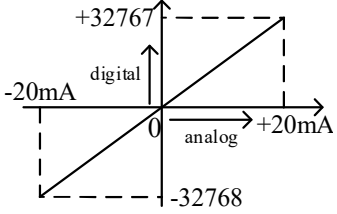


XL-E8AD-A-S current input wiring:



11-6. Analog digital conversion diagram

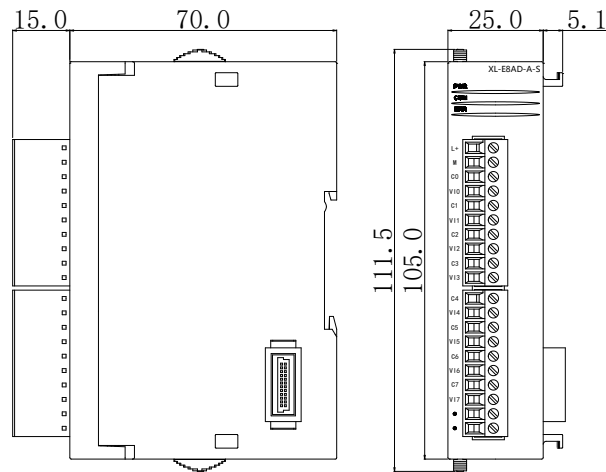
The relationship between input analog quantities and converted digital quantities is shown in the following table:

| 0~20mA analog input | 4~20mA analog input |
|--|--|
|  |  |
| -20~20mA analog input | |
|  | |

Note: When the channel enable switch is turned on and the AD current input is suspended, the ID register corresponding to the AD current input is displayed as 0. When the channel enable switch is turned off, the ID register corresponding to the AD current input is displayed as 0.

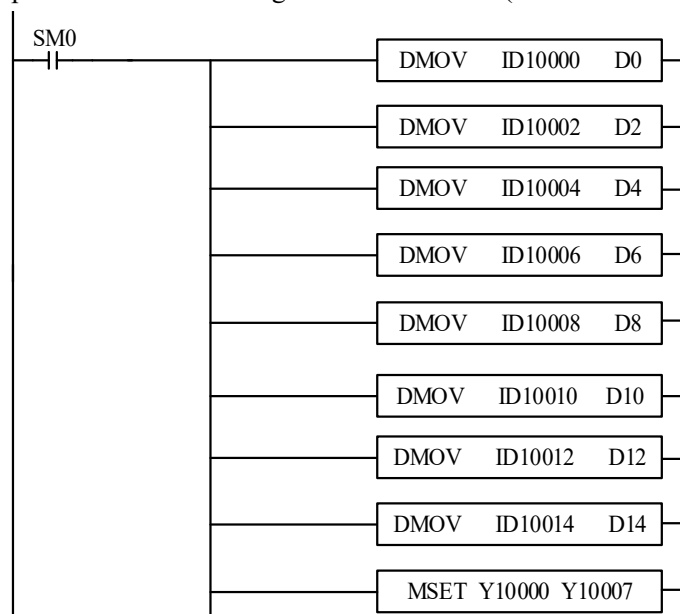
11-7. Dimension

(Unit: mm)



11-8. Application

Examples of real-time reading 8 channels of data (take Module 1 as an example)



Explain:

SM0 is a constant ON coil and has been in ON state during the operation of PLC.

The PLC starts to run, and continuously writes the data of channel 0 of the module 1 into the data register D0.

Data in channel 1 is written to data register D1, D0.

Data in channel 2 is written to data register D3, D2.

Data in channel 3 is written to data register D5, D4.

Data in channel 4 is written to data register D7, D6.
Data in channel 5 is written to data register D9, D8.
Data in channel 6 is written to data register D11, D10.
Data in channel 7 is written to data register D13, D12.
Data in channel 8 is written to data register D15, D14.

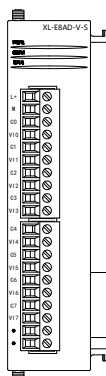
Since all channels are used, all the channel enablers are opened.

12. Analog input module XL-E8AD-V-S

This chapter mainly introduces XL-E8AD-V-S module specifications, terminal instructions, input definition number allocation, working mode settings, external connections, analog-to-digital conversion diagrams, appearance size diagrams and related programming examples.

12-1. Module features and specifications

XL-E8AD-V-S analog input module converts 8 analog current input values into digital values, and transmits them to the main unit of PLC, and interacts with the main unit of PLC in real time.



Module features

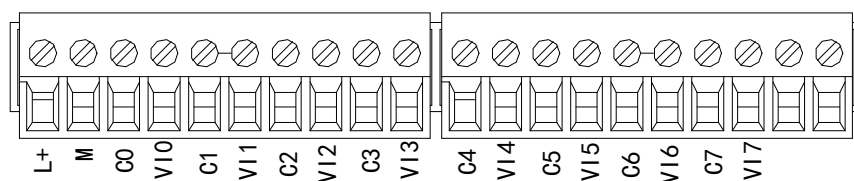
- 8-channel analog input: voltage input.
- 16-bit high-precision analog input.
- As a special functional module of the XL series, XL3 can connect up to 10 modules, XL5/XL5E/XL5N/XL5H/XLME/XLH/XSLH can expand 16 modules, and XL1 does not support expansion modules.

Module specification

| Item | Analog input |
|----------------------|--|
| | Voltage input |
| Analog input range | 0~5V, 0~10V, -5~5V, -10~10V |
| Max input range | DC±15V |
| Digital output range | 16 bits binary data (0~65535 or -32768~32767) |
| Resolution | 1/65535 (16Bit) |
| Integrated precision | ±1% |
| Conversion speed | 2ms/1 channel |
| Module power supply | DC24V±10%, 150mA |
| Installation | Fixed with M3 screws or directly installed on rail of DIN46277 (Width: 35mm) |

12-2. Terminal descriptions

Terminal arrangement



Terminal signal

| Name | Function | |
|-----------------|----------|--|
| Indicator light | PWR | The indicator lights up when the module has a power supply. |
| | COM | When the module port communicates normally, the indicator lights on. |
| | ERR | When there is an error in the module, the indicator is always on |

| | | |
|----------|----------------------------|---|
| | | <p>or flickering (red).</p> <p>When the ERR LED is always on, it indicates that the module has serious application errors and can not be used. It is necessary to adjust the mode of use and switch the PLC to STOP state.</p> <p>When the ERR LED flickers, there are application errors, abnormal work and abnormal data in the module, but the PLC is still RUN.</p> |
| Terminal | L+ | Module 24V power supply input + |
| | M | Module 24V power supply input - |
| | C0 | VI0 output ground |
| | VI0 | Channel 1 AD voltage input |
| | C1 | VI1 output ground |
| | VI1 | Channel 2 AD voltage input |
| | C2 | VI2 output ground |
| | VI2 | Channel 3 AD voltage input |
| | C3 | VI3 output ground |
| | VI3 | Channel 4 AD voltage input |
| | C4 | VI4 output ground |
| | VI4 | Channel 5 AD voltage input |
| | C5 | VI5 output ground |
| | VI5 | Channel 6 AD voltage input |
| | C6 | VI6 output ground |
| | VI6 | Channel 7 AD voltage input |
| C7 | VI7 output ground | |
| VI7 | Channel 8 AD voltage input | |

Wiring head specification

When wiring the module, its wiring head should meet the following requirements:

- (1) The stripping length is 9 mm;
- (2) Flexible wires with bare tubular ends are 0.25-1.5 square.
- (3) Flexible wires with tubular pre-insulated end is 0.25-0.5 square.

12-3. I/O address

XL series analog module does not occupy I/O unit, the converted value is directly sent to the PLC register, the corresponding channel definition number of the PLC register is as follows:

Module 1 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID10000 | Y10000 | X10000 |
| 1CH | ID10002 | Y10001 | X10001 |
| 2CH | ID10004 | Y10002 | X10002 |
| 3CH | ID10006 | Y10003 | X10003 |
| 4CH | ID10008 | Y10004 | X10004 |
| 5CH | ID10010 | Y10005 | X10005 |
| 6CH | ID10012 | Y10006 | X10006 |
| 7CH | ID10014 | Y10007 | X10007 |

Module 2 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID10100 | Y10100 | X10100 |
| 1CH | ID10102 | Y10101 | X10101 |
| 2CH | ID10104 | Y10102 | X10102 |
| 3CH | ID10106 | Y10103 | X10103 |
| 4CH | ID10108 | Y10104 | X10104 |
| 5CH | ID10110 | Y10105 | X10105 |
| 6CH | ID10112 | Y10106 | X10106 |
| 7CH | ID101014 | Y10107 | X10107 |

Module 3 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID10200 | Y10200 | X10200 |
| 1CH | ID10202 | Y10201 | X10201 |
| 2CH | ID10204 | Y10202 | X10202 |
| 3CH | ID10206 | Y10203 | X10203 |
| 4CH | ID10208 | Y10204 | X10204 |
| 5CH | ID10210 | Y10205 | X10205 |
| 6CH | ID10212 | Y10206 | X10206 |
| 7CH | ID10214 | Y10207 | X10207 |

Module 4 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID10300 | Y10300 | X10300 |
| 1CH | ID10302 | Y10301 | X10301 |
| 2CH | ID10304 | Y10302 | X10302 |
| 3CH | ID10306 | Y10303 | X10303 |
| 4CH | ID10308 | Y10304 | X10304 |
| 5CH | ID10310 | Y10305 | X10305 |
| 6CH | ID10312 | Y10306 | X10306 |
| 7CH | ID10314 | Y10307 | X10307 |

Module 5 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID10400 | Y10400 | X10400 |
| 1CH | ID10402 | Y10401 | X10401 |
| 2CH | ID10404 | Y10402 | X10402 |
| 3CH | ID10406 | Y10403 | X10403 |
| 4CH | ID10408 | Y10404 | X10404 |
| 5CH | ID10410 | Y10405 | X10405 |
| 6CH | ID10412 | Y10406 | X10406 |
| 7CH | ID10414 | Y10407 | X10407 |

Module 6 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID10500 | Y10500 | X10500 |
| 1CH | ID10502 | Y10501 | X10501 |
| 2CH | ID10504 | Y10502 | X10502 |
| 3CH | ID10506 | Y10503 | X10503 |
| 4CH | ID10508 | Y10504 | X10504 |
| 5CH | ID10510 | Y10505 | X10505 |
| 6CH | ID10512 | Y10506 | X10506 |
| 7CH | ID10514 | Y10507 | X10507 |

Module 7 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID10600 | Y10600 | X10600 |
| 1CH | ID10602 | Y10601 | X10601 |
| 2CH | ID10604 | Y10602 | X10602 |
| 3CH | ID10606 | Y10603 | X10603 |
| 4CH | ID10608 | Y10604 | X10604 |
| 5CH | ID10610 | Y10605 | X10605 |
| 6CH | ID10612 | Y10606 | X10606 |
| 7CH | ID10614 | Y10607 | X10607 |

Module 8 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID10700 | Y10700 | X10700 |
| 1CH | ID10702 | Y10701 | X10701 |
| 2CH | ID10704 | Y10702 | X10702 |
| 3CH | ID10706 | Y10703 | X10703 |
| 4CH | ID10708 | Y10704 | X10704 |
| 5CH | ID10710 | Y10705 | X10705 |
| 6CH | ID10712 | Y10706 | X10706 |
| 7CH | ID10714 | Y10707 | X10707 |

Module 9 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID10800 | Y11000 | X11000 |
| 1CH | ID10802 | Y11001 | X11001 |
| 2CH | ID10804 | Y11002 | X11002 |
| 3CH | ID10806 | Y11003 | X11003 |
| 4CH | ID10808 | Y11004 | X11004 |
| 5CH | ID10810 | Y11005 | X11005 |
| 6CH | ID10812 | Y11006 | X11006 |
| 7CH | ID10814 | Y11007 | X11007 |

Module 10 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID10900 | Y11100 | X11100 |
| 1CH | ID10902 | Y11101 | X11101 |
| 2CH | ID10904 | Y11102 | X11102 |
| 3CH | ID10906 | Y11103 | X11103 |
| 4CH | ID10908 | Y11104 | X11104 |
| 5CH | ID10910 | Y11105 | X11105 |
| 6CH | ID10912 | Y11106 | X11106 |
| 7CH | ID10914 | Y11107 | X11107 |

Module 11 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID11000 | Y11200 | X11200 |
| 1CH | ID11002 | Y11201 | X11201 |
| 2CH | ID11004 | Y11202 | X11202 |
| 3CH | ID11006 | Y11203 | X11203 |
| 4CH | ID11008 | Y11204 | X11204 |
| 5CH | ID11010 | Y11205 | X11205 |
| 6CH | ID11012 | Y11206 | X11206 |
| 7CH | ID11014 | Y11207 | X11207 |

Module 12 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID11100 | Y11300 | X11300 |
| 1CH | ID11102 | Y11301 | X11301 |
| 2CH | ID11104 | Y11302 | X11302 |
| 3CH | ID11106 | Y11303 | X11303 |
| 4CH | ID11108 | Y11304 | X11304 |
| 5CH | ID11110 | Y11305 | X11305 |
| 6CH | ID11112 | Y11306 | X11306 |
| 7CH | ID11114 | Y11307 | X11307 |

Module 13 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID11200 | Y11400 | X11400 |
| 1CH | ID11202 | Y11401 | X11401 |
| 2CH | ID11204 | Y11402 | X11402 |
| 3CH | ID11206 | Y11403 | X11403 |
| 4CH | ID11208 | Y11404 | X11404 |
| 5CH | ID11210 | Y11405 | X11405 |
| 6CH | ID11212 | Y11406 | X11406 |
| 7CH | ID11214 | Y11407 | X11407 |

Module 14 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID11300 | Y11500 | X11500 |
| 1CH | ID11302 | Y11501 | X11501 |
| 2CH | ID11304 | Y11502 | X11502 |
| 3CH | ID11306 | Y11503 | X11503 |
| 4CH | ID11308 | Y11504 | X11504 |
| 5CH | ID11310 | Y11505 | X11505 |
| 6CH | ID11312 | Y11506 | X11506 |
| 7CH | ID11314 | Y11507 | X11507 |

Module 15 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID11400 | Y11600 | X11600 |
| 1CH | ID11402 | Y11601 | X11601 |
| 2CH | ID11404 | Y11602 | X11602 |
| 3CH | ID11406 | Y11603 | X11603 |
| 4CH | ID11408 | Y11604 | X11604 |
| 5CH | ID11410 | Y11605 | X11605 |
| 6CH | ID11412 | Y11606 | X11606 |
| 7CH | ID11414 | Y11607 | X11607 |

Module 16 register address:

| Channel | AD signal | Channel enable switch (please turn on the switch to use this channel) | Channel alarm flag bit |
|---------|-----------|---|------------------------|
| 0CH | ID11500 | Y11700 | X11700 |
| 1CH | ID11502 | Y11701 | X11701 |
| 2CH | ID11504 | Y11702 | X11702 |
| 3CH | ID11506 | Y11703 | X11703 |
| 4CH | ID11508 | Y11704 | X11704 |
| 5CH | ID11510 | Y11705 | X11705 |
| 6CH | ID11512 | Y11706 | X11706 |
| 7CH | ID11514 | Y11707 | X11707 |

Note:

- (1) Banning unused channels can improve the scanning speed of input/output.
- (2) When the input enabling switch is turned off during operation, the corresponding input channel will not collect data. (Data display is 0)

12-4. Working mode settings

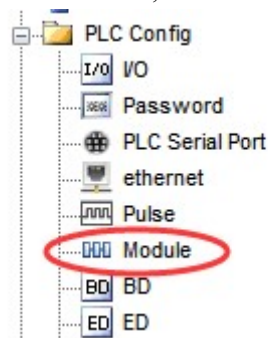
There are two ways to set the working mode (the effect of these two ways is equivalent):

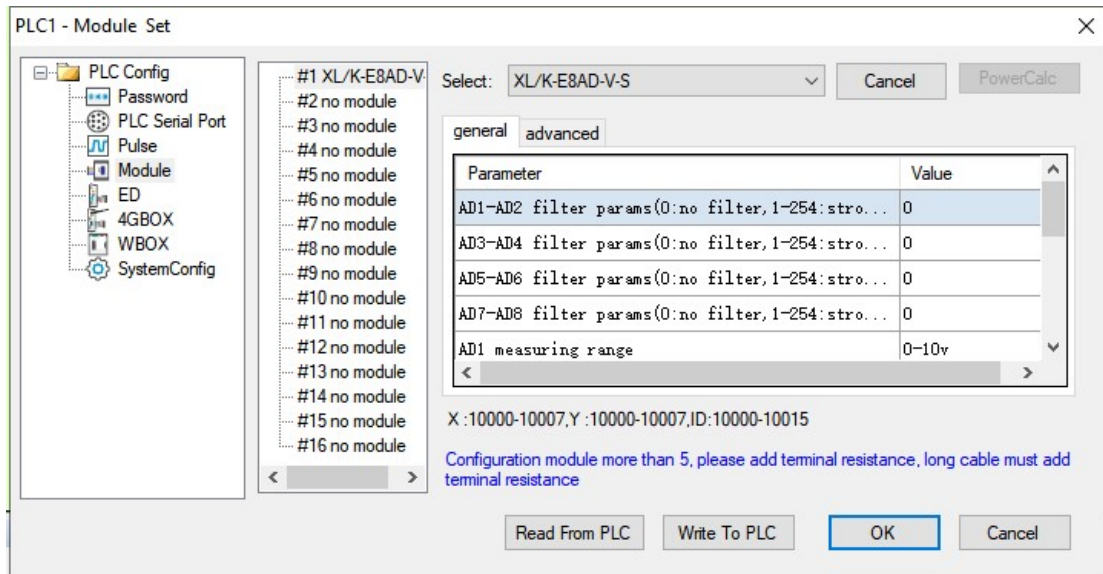
- (1) Configuration through the software
- (2) Setting up by Flash Register

Set through the software

Please use XDPpro v3.5.1 or higher version software to configure the module.

Open the software, click module in the left menu,





Choose the module type, and set each channel's parameters in the above window. Then click write to PLC, cut the power supply and power on again to make the settings effective.

Note: The first-order low-pass filtering method weighs this time sampling value and the output value of the last filtering to get the effective filtering value; the filter coefficient is set by the user to 0-254, the smaller the value, the more stable the data, but may lead to data lag; therefore, when set to 1, the filtering effect is strongest and the data is the most stable; when set to 254, the filtering effect is the weakest; default is 0 (no filtering).

Set by Flash register

The input channel of the extended module is voltage mode, with 0~5V, 0~10V, -5~5V, -10~10V optional. It is set by special FLASH data register SFD in PLC. As follows:

| Module no. | SFD register | Module no. | SFD register |
|------------|---------------|------------|---------------|
| #1 | SFD350~SFD359 | #9 | SFD430~SFD439 |
| #2 | SFD360~SFD369 | #10 | SFD440~SFD449 |
| #3 | SFD370~SFD379 | #11 | SFD450~SFD459 |
| #4 | SFD380~SFD389 | #12 | SFD460~SFD469 |
| #5 | SFD390~SFD399 | #13 | SFD470~SFD479 |
| #6 | SFD400~SFD409 | #14 | SFD480~SFD489 |
| #7 | SFD410~SFD419 | #15 | SFD490~SFD499 |
| #8 | SFD420~SFD429 | #16 | SFD500~SFD509 |

Note: As shown above, each register sets four-channel modes. Each register has 16 bits. From low to high, each four bit will set four-channel modes in turn.

SFD bit definition

| | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | NOTE |
|------------------|---|------|------|-------------|---------------|------|------|------|--|
| Byte0 | AD channel 2, channel 1 filtering parameter | | | | | | | | AD filtering parameter |
| Byte1 | AD channel 4, channel 3 filtering parameter | | | | | | | | |
| Byte2 | AD channel 6, channel 5 filtering parameter | | | | | | | | |
| Byte3 | AD channel 8, channel 7 filtering parameter | | | | | | | | |
| Byte4 | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | Set the AD module input range, Byte4 low 4-bit set AD channel1, high 4-bit set AD channel2. Byte5 low 4-bit set AD channel3, high 4-bit set AD channel4, Byte6 low 4-bit set AD channel5, high 4-bit set AD channel6, Byte7 low 4-bit set AD channel7, high 4-bit set AD channel8. |
| | AD2 | | | | AD1 | | | | |
| | 0000: 0~10V | | | | 0000: 0~10V | | | | |
| | 0001: 0~5V | | | | 0001: 0~5V | | | | |
| | 0010: -10~10V | | | | 0010: -10~10V | | | | |
| 0011: -5~5V | | | | 0011: -5~5V | | | | | |
| Byte5 | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | |
| | AD4 | | | | AD3 | | | | |
| | 0000: 0~10V | | | | 0000: 0~10V | | | | |
| | 0001: 0~5V | | | | 0001: 0~5V | | | | |
| | 0010: -10~10V | | | | 0010: -10~10V | | | | |
| 0011: -5~5V | | | | 0011: -5~5V | | | | | |
| Byte6 | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | |
| | AD6 | | | | AD5 | | | | |
| | 0000: 0~10V | | | | 0000: 0~10V | | | | |
| | 0001: 0~5V | | | | 0001: 0~5V | | | | |
| | 0010: -10~10V | | | | 0010: -10~10V | | | | |
| 0011: -5~5V | | | | 0011: -5~5V | | | | | |
| Byte7 | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | |
| | AD8 | | | | AD7 | | | | |
| | 0000: 0~10V | | | | 0000: 0~10V | | | | |
| | 0001: 0~5V | | | | 0001: 0~5V | | | | |
| | 0010: -10~10V | | | | 0010: -10~10V | | | | |
| 0011: -5~5V | | | | 0011: -5~5V | | | | | |
| Byte8~ Byte19 | - | | | | | | | | |

Take the first module as an example to illustrate how to set it up.

Example: To set the first module's input channels 1 and 0 to 0~10V, input channels 3 and 2 to 0~5V, input channels 5 and 4 to 0~10V, input channels 7 and 6 to 0~5V, filter coefficients of channels 0, 1, 2 and 3 to 254, filter coefficients of channels 4, 5, 6 and 7 to 100.

Method 1:

You can configure it directly in the PLC software, as shown above.

Method 2:

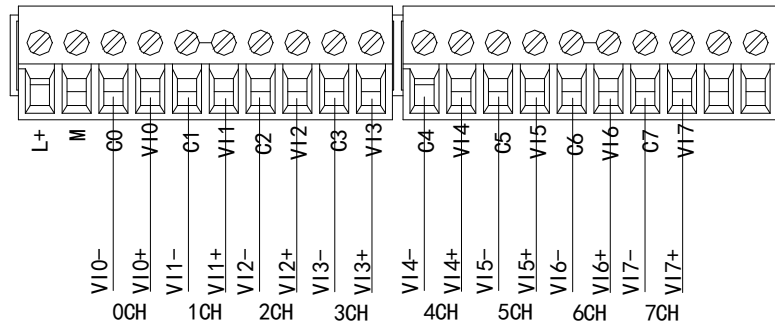
Set the SFD as follows:

SFD350=FEFEH SFD351=6464H SFD352=1100H SFD353=1100H

12-5. External wiring

For external connection, to avoid interference, use shielding wire and connect the ground to the single point of shielding layer.

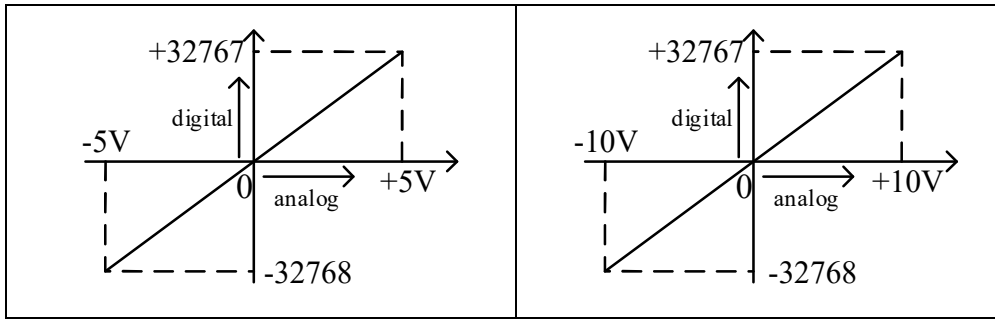
Voltage input



12-6. Analog digital conversion diagram

The relationship between input analog quantities and converted digital quantities is shown in the following table:

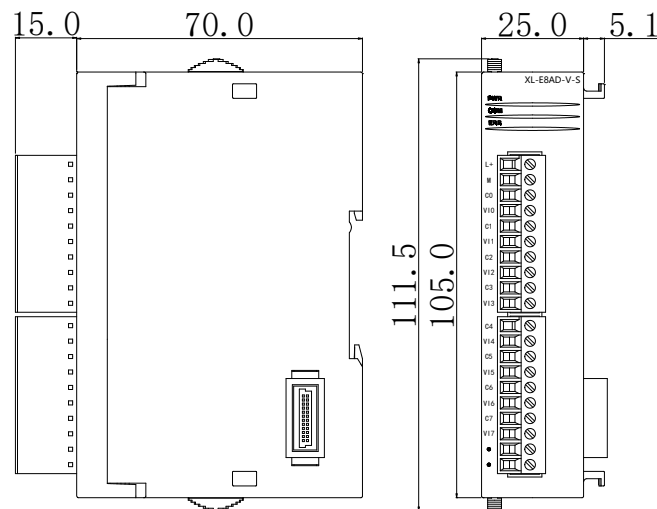
| 0~5V analog input | 0~10V analog input |
|--------------------|----------------------|
| | |
| -5~5V analog input | -10~10V analog input |



Note: When the channel enable switch is turned on and the AD current input is suspended, the ID register corresponding to the AD current input is displayed as 0. When the channel enable switch is turned off, the ID register corresponding to the AD current input is displayed as 0.

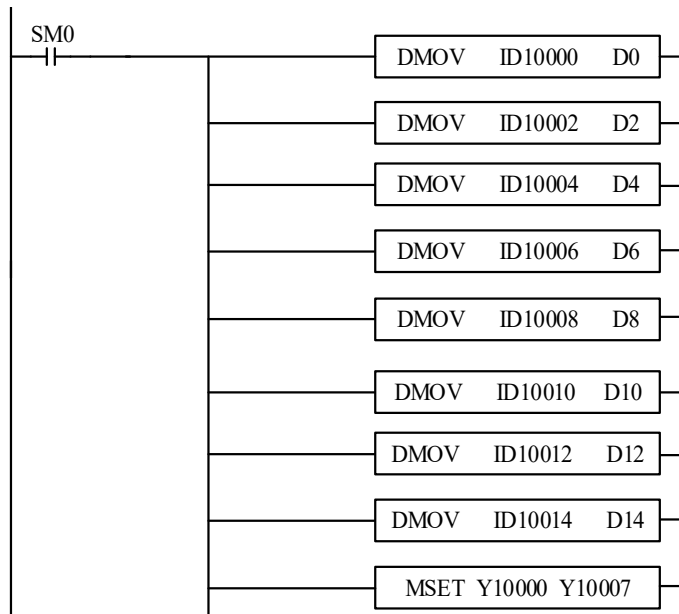
12-7. Dimension

(Unit: mm)



12-8. Application

Examples of real-time reading 8 channels of data (take Module 1 as an example)



Explain:

SM0 is a constant ON coil and has been in ON state during the operation of PLC.

The PLC starts to run, and continuously writes the data of channel 0 of the module 1 into the data register D0.

Data in channel 1 is written to data register D1, D0.

Data in channel 2 is written to data register D3, D2.

Data in channel 3 is written to data register D5, D4.

Data in channel 4 is written to data register D7, D6.

Data in channel 5 is written to data register D9, D8.

Data in channel 6 is written to data register D11, D10.

Data in channel 7 is written to data register D13, D12.

Data in channel 8 is written to data register D15, D14.

Since all channels are used, all the channel enablers are opened.

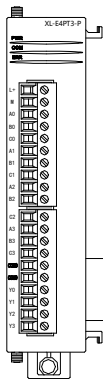
13. PT100 temperature module

XL-E4PT3-P-H

This chapter mainly introduces XL-E4PT3-P-H module specifications, terminal instructions, input definition number allocation, working mode settings, external connections, analog-to-digital conversion diagrams, appearance size diagrams and related programming examples.

13-1. Module features and specifications

XL-E4PT3-P-H temperature PID control module processes 4-channel thermal resistance temperature signals and transmits them to the main unit of PLC. Compared with XL-E4PT3-P, XL-E4PT3-P-H adopts a fully isolated scheme, which has better anti-interference performance, wider temperature measurement range, higher resolution and accuracy, and supports a variety of sensor types.



Features

- Three wires temperature sensors analog inputs and support Pt100, Pt1000, Cu50, and Cu100 thermistors.
- 4 channels of fully isolated input, 4 channels of output, 4 sets of independent PID parameters, supporting self-tuning function.
- 1mA constant current output, unaffected by external environmental changes.
- The resolution accuracy is 0.1 °C and 0.01 °C.
- As a special functional module of the XL series, the XL3 series can connect up to 10 units, the XL5/XL5E/XL5H/XL5N/XLME/XLH/XSLH series can connect up to 16 units, and the XL1 series does not support expansion modules.

Module specifications

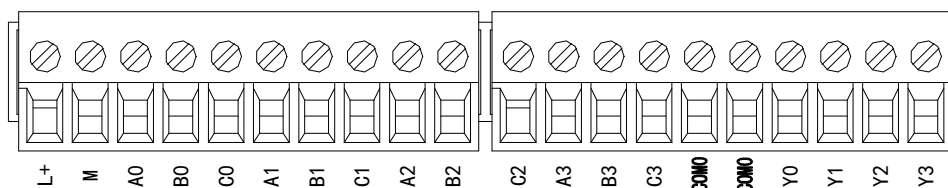
| Item | Contents | | |
|-------------------------------|---|--------------------|--------------------|
| Analog input signal | Pt100, Pt1000, Cu50, and Cu100 thermistors | | |
| Temperature measurement range | Sensor type | Display resolution | Temperature range |
| | Pt100 | (0.1°C) | -200.0°C~850.0°C |
| | | (0.01°C) | -200.00°C~300.00°C |
| | Pt1000 | (0.1°C) | -200.0°C~850.0°C |
| | | (0.01°C) | -200.00°C~300.00°C |
| | Cu50 | (0.1°C, 0.01°C) | -50.00°C~150.00°C |
| Cu100 | (0.1°C, 0.01°C) | -50.00°C~150.00°C | |
| Digital output range | -20000 to 30000 (specific differentiation based on sensor type) | | |
| Resolution | 0.1°C, 0.01°C | | |
| Integrate precision | ±0.2% (relative max value) | | |
| Repeatability | ±0.05%FS | | |
| Conversion speed | 50ms/all the channels | | |
| Module power supply | DC24V±10%, 50mA | | |
| Install format | Fixed with M3 screws or directly installed on orbit of DIN46277 (Width: 35mm) | | |

Note:

- (1) When there is no signal input, the channel data is the maximum value of the digital output range.
- (2) Connect Pt100, Pt1000, Cu50, Cu100 thermal resistor according to actual needs.
- (3) The module needs to be configured and used in conjunction with version V3.7.17 and above of the Xinje PLC programming tool software.

13-2. Terminals

Terminal arrangement



Module signal

| Name | Function | |
|-----------|---|---|
| LED light | PWR | The indicator lights up when the module has a power supply |
| | COM | When the module communication port communicates normally, the indicator lights on |
| | ERR | When there is an error in the module, the indicator is always on or flickering (red) When the ERR lamp is always on, there are serious application errors in the module that can not be used, so the mode of use must be adjusted, and the PLC body is switched to STOP state. When the ERR lamp flickers, there are application errors, abnormal work and abnormal data in the module, but the PLC body is still RUN. |
| terminal | L+ | External power supply 24V + |
| | M | External power supply 24V - |
| | A0 | CH0 temperature input |
| | B0 | CH0 input common terminal |
| | C0 | CH0 input common terminal |
| | A1 | CH1 temperature input |
| | B1 | CH1 input common terminal |
| | C1 | CH1 input common terminal |
| | A2 | CH2 temperature input |
| | B2 | CH2 input common terminal |
| | C2 | CH2 input common terminal |
| | A3 | CH3 temperature input |
| | B3 | CH3 input common terminal |
| | C3 | CH3 input common terminal |
| | COM0 | PID output common terminal |
| Y0~Y3 | PID output terminals corresponding to CH0~CH3 | |

Wiring head specifications

When wiring the module, its wiring head should meet the following requirements:

- (1) The stripping length is 9 mm;
- (2) Flexible conductors with bare tubular ends are 0.25-1.5 square.
- (3) Flexible conductor with tubular pre-insulated end is 0.25-0.5 square.

13-3. I/O address

XL series analog module will not occupy I/O unit, the conversion value will be sent to PLC register. Each channel related PLC register address are shown as below:

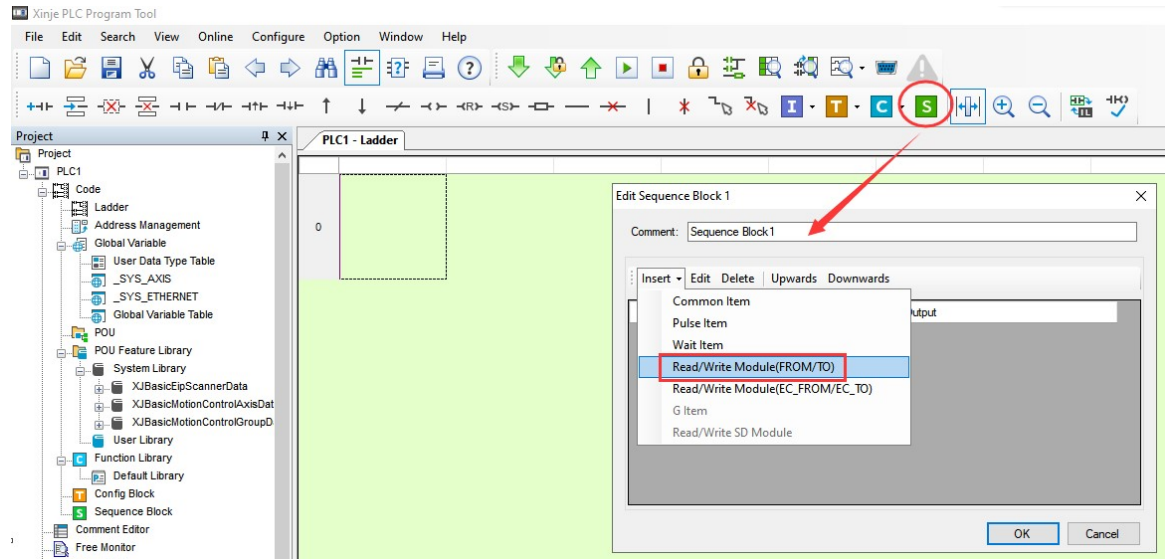
| Parameter | Address | | | | |
|---|-----------|---------|---------|---------|---------|
| | Channel | CH0 | CH1 | CH2 | CH3 |
| Display temperature (unit: 0.1°C) | Module 1 | ID10000 | ID10001 | ID10002 | ID10003 |
| | Module 2 | ID10100 | ID10101 | ID10102 | ID10103 |
| | | ID10x00 | ID10x01 | ID10x02 | ID10x03 |
| | Module 16 | ID11500 | ID11501 | ID11502 | ID11503 |
| PID enable bit (0: OFF, 1: ON) | Module 1 | Y10000 | Y10001 | Y10002 | Y10003 |
| | Module 2 | Y10100 | Y10101 | Y10102 | Y10103 |
| | | Y10x00 | Y10x01 | Y10x02 | Y10x03 |
| | Module 16 | Y11700 | Y11701 | Y11702 | Y11703 |
| PID contact output (X input returning to the main body) | Module 1 | X10000 | X10001 | X10002 | X10003 |
| | Module 2 | X10100 | X10101 | X10102 | X10103 |
| | | X10x00 | X10x01 | X10x02 | X10x03 |
| | Module 16 | X11700 | X11701 | X11702 | X11703 |
| Open circuit detection (0: normal, 1: disconnected) | Module 1 | X10010 | X10011 | X10012 | X10013 |
| | Module 2 | X10110 | X10111 | X10112 | X10113 |
| | | X10x10 | X10x11 | X10x12 | X10x13 |
| | Module 16 | X11710 | X11711 | X11712 | X11713 |
| Auto-tuning error | Module 1 | X10020 | X10021 | X10022 | X10023 |
| | Module 2 | X10120 | X10121 | X10122 | X10123 |
| | | X10x20 | X10x21 | X10x22 | X10x23 |
| | Module 16 | X11720 | X11721 | X11722 | X11723 |

Note:

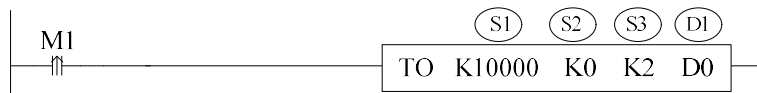
- (1) When the "Y function selection" is set to "channel enable", Y10000-Y10003 (taking # 1 module as an example) is the PID enable bit, and the PID duty cycle output needs to be monitored from X10000 to X10003 (taking # 1 module as an example).
- (2) When the "Y function selection" is set to "immediate output", Y0~Y3 are ordinary switch output terminals, and Y10000~Y10003 (taking # 1 module as an example) can be used to directly control the Y0~Y3 output of the module.
- (3) When the "Y function selection" is set to "channel enable", Y0~Y3 are the PID output terminals, and Y10000~Y10003 (taking # 1 module as an example) can be used to enable the corresponding channel's PID control. The Y0~Y3 output of the module is automatically calculated and controlled by the PID.

From/To instruction

The reading and writing of the temperature control module for the thermal resistor needs to be completed in the sequence block through the FROM/TO command, as shown in the following figure:



Parameter write insruction TO



Function: write the PLC register data to module address, the operate unit is word.

Operand:

S1: target module number, range: 10000~10015. Operand: K, TD, CD, D, HD, FD

S2: first address of module. Operand: K, TD, CD, D, HD, FD

S3: write in register numbers. Operand: K, TD, CD, D, HD, FD

D1: first address of PLC. Operand: TD, CD, D, HD, FD

Parameter read instruction FROM



Function: read the module data to the PLC regsiter, the operate unit is word.

S1: target module number, range: 10000~10015. Operand: K, TD, CD, D, HD, FD

S2: first address of module. Operand: K, TD, CD, D, HD, FD

S3: read register numbers. Operand: K, TD, CD, D, HD, FD

D1: first address of PLC. Operand: TD, CD, D, HD, FD

Note:

- (1) The FROM/TO instruction can only be written in the sequence function block. For XL series PLCs with firmware version V3.4.5 and above, a maximum of 100 BLOCKs can be written in the program, but a maximum of 8 can be run simultaneously.
- (2) The starting number of the module starts from K10000, with module # 1 being K10000, module # 2 being K10001... and so on, module # 16 being K10015.

Related address definition:

The address of the read/write parameters:

| From_To data | Address | | | | Read/write | Default value |
|--|---------|-----|-----|-----|------------|---------------|
| Channel | CH0 | CH1 | CH2 | CH3 | | |
| Auto-tune bit | K0 | K0 | K0 | K0 | R/W | 0 |
| PID output (0~4095) | K1 | K2 | K3 | K4 | R | - |
| Target temperature (unit: 0.1°C/0.01°C) | K5 | K6 | K7 | K8 | R/W | 0 |
| Kp | K9 | K13 | K17 | K21 | R/W | 40 |
| Ki | K10 | K14 | K18 | K22 | R/W | 240 |
| Kd | K11 | K15 | K19 | K23 | R/W | 60 |
| Diff (unit: 0.1°C/0.01°C) | K12 | K16 | K20 | K24 | R/W | 1000 |
| Control period (unit: 0.1s) | K25 | K26 | K27 | K28 | R/W | 20 |
| Output range (range: 0~100) | K29 | K30 | K31 | K32 | R/W | 100 |
| Temperature difference δ (unit: 0.1°C/0.01°C)) | K33 | K34 | K35 | K36 | R/W | 0 |
| Calibrate ambient temperature values (unit: 0.1°C/0.01°C)) | K37 | K38 | K39 | K40 | W | - |
| From/To data initialization | K41 | K41 | K41 | K41 | W | - |

| | |
|----------------------------------|---|
| Auto-tune PID control bit | Auto-tune triggered signal, start to auto-tune mode when set to 1 After auto-tune, PID parameters and temperature control period value are refreshed, the bit value is cleared to be 0. The user can read the bit to know the state. 1 means auto-tune is ongoing. 0 means auto-tune has finished. |
| PID output value (0~4095) | When the PID output is for analog control (such as steam valve opening or thyristor conduction angle), this value can be transmitted to the analog output module to achieve control requirements. |
| PID parameters (P, I, D) | The best PID parameters got from the PID auto-tune. If the current PID parameters cannot meet the control requirements, users can set the experience PID parameters to make the module work according to the user setting |

| | |
|--|---|
| | value. |
| PID calculation range (Diff) Unit: 0.1°C/0.01°C | This function can set the temperature range of the PID operation, such as setting the relevant parameter Tdiff, the target temperature is Target, then the operation range of the PID is Target-Tdiff < T < Target + Tdiff, when T < Target-Tdiff, the output is the max value, when T > Target + Tdiff, the output is 0. |
| Temperature difference value δ Unit: 0.1°C/0.01°C | This parameter is a signed number, with power outage duration of 0 by default. 0.1°C: actual temperature display = (sampling temperature value + temperature deviation value δ)/10. 0.01°C: actual temperature display = (sampling temperature value + temperature deviation value δ)/100. When the user thinks the measured temperature is different from the actual temperature, this value can be modified to correct the temperature. |
| Set temperature Unit: 0.1°C/0.01°C | The target temperature value of the control system. Set the range to the numerical value corresponding to the temperature upper and lower limits of the selected sensor scale. |
| Temperature control period Unit: 0.1s | The adjusting range of temperature control period is 0.1s~200s, and the minimum precision range is 0.1s. For example, when writing 5, the actual temperature control period is 0.5s. |
| Adjusting Environment temperature Unit: 0.1°C/0.01°C | When the user believes that the ambient temperature value is inconsistent with the temperature value displayed on the module channel, the known ambient temperature value can be written into this parameter. At the moment the module is written, the temperature deviation value is set to δ and save. Temperature deviation value δ = adjusting environment temperature value - sampling temperature value. Attention: When the user inputs the adjusting temperature value, confirm that it is consistent with the ambient temperature. This data is very important, and once entered incorrectly, it can lead to calculating temperature deviation values δ Serious error, which in turn affects the display temperature. |
| Auto-tune output range | The output amplitude calculated by PID is in %, where 100 represents the duty cycle as 100% of the full scale output and 80 represents 80% of the full scale output. Note: When set to 0, PID control will have no output. |
| From/To data initialization | This function can restore the parameters in the above table to their factory settings. When using it, K41 needs to be set to 1, setting to other values are invalid. |

Note:

- (1) When the "Y function selection" is set to "immediate output", only the "temperature deviation δ " and "adjusting ambient temperature value" is valid, and other parameters are not effective.
- (2) The module can automatically save the set temperature value, PID parameters, temperature control cycle, output amplitude, temperature deviation, and temperature calibration parameters. When writing the above parameters, it is necessary to use the rising edge to

trigger the writing. Do not keep writing. It is recommended to only write the parameters used. It is not recommended to write the entire piece of data for programming convenience, as writing 0 to some addresses may cause the system to malfunction.

- (3) The self-tuning enable address K0: K0 will occupy a continuous 8-bit address space. The 4-channel module enable bits correspond to the first 4 bits address space, while the last 4 bits addresses are idle (but cannot be used for other purposes). When the read/write enable bit is enabled, K0 can be a coil or register. When it is a coil, it occupies 8 consecutive bits starting from the coil address; When it is a register, it occupies that register. For example, to set the first and third channels of the module to self-tuning mode, and the other two channels to manual PID mode, with the command To K10000 K0 K1 M10, M10 and M12 should be set to ON, and M11, M13, M14, and M15 should be set to OFF; When the instruction is To K10000 K0 K1 D100, D100 should be assigned a value of 5.
- (4) When switching the "resolution", "temperature setting value", "PID parameter", "PID operation range", "temperature deviation δ ", "adjusting environment temperature value" needs to be set again, and the parameter units should be consistent with the resolution.

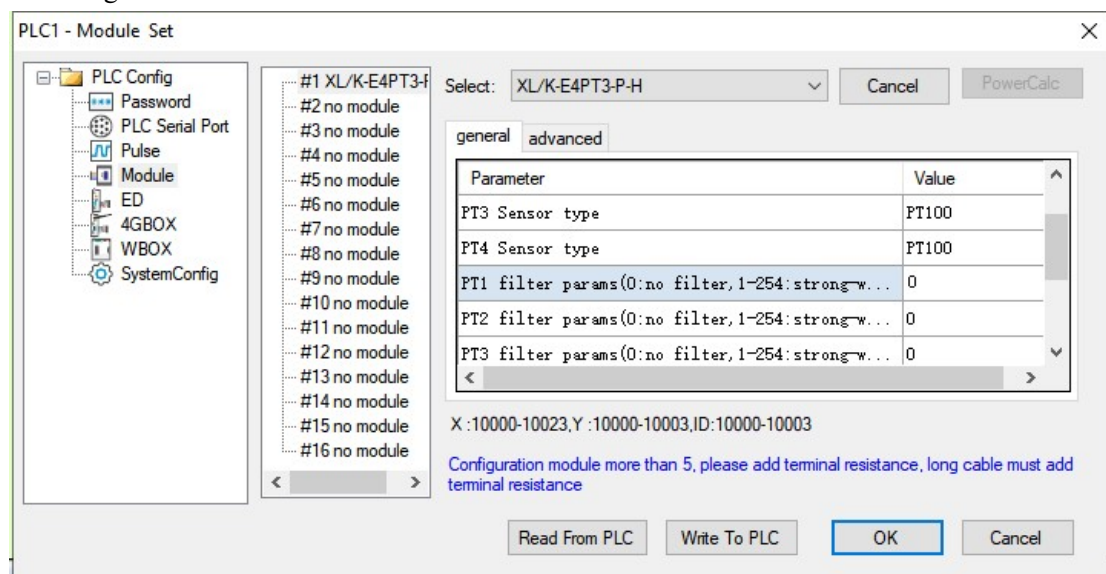
13-4. Working mode

There are two ways to set the working mode (the effect of these two ways is equivalent):

- 1: Through the XDPpro software
- 2: Through Flash Register (FD) Settings

Set through the software

Open the software, click configure/expansion module setting, then select the module type in the following window:



Choose the module model, set the parameters of each channel, click write to PLC. Then download user program and run, the settings will be effective.

Note:

- (1) The first-order low-pass filtering method weighted this sampling value and the output value of the last filtering to get the effective filtering value; the filter coefficient is set by the user to 0-254, the smaller the value, the more stable the data, but it may lead to data lag; therefore, when set to 1, the filtering effect is strongest and the data is the most stable; when set to 254, the filtering effect is the weakest; default is 0 (no filtering).
- (2) "Y Function Selection" is used to specify the functions of Y10000~Y10003 (# 1 module as an example). The default factory setting is "Channel Enable", which supports the module's own self-tuning and PID control functions. The output points Y0~Y3 on the module are affected by the PID output value, resulting in on/off effects; When set to "immediate output", the output points Y0~Y3 on the module are ordinary switch output points. Setting On Y10000~Y10003 can conduct Y0~Y3, while the module only retains the temperature acquisition function. If temperature control is required, please use the PID command of the PLC main body to achieve it.

Set through flash register

The CH0~CH3 channels of the expansion module can be set with sensor type, filtering coefficient, and Y function selection, which can be set through the special FLASH data register SFD inside the PLC. As shown below:

| Module ID | SFD address | Module ID | SFD address |
|-----------|---------------|-----------|---------------|
| #1 | SFD350~SFD359 | #9 | SFD430~SFD439 |
| #2 | SFD360~SFD369 | #10 | SFD440~SFD449 |
| #3 | SFD370~SFD379 | #11 | SFD450~SFD459 |
| #4 | SFD380~SFD389 | #12 | SFD460~SFD469 |
| #5 | SFD390~SFD399 | #13 | SFD470~SFD479 |
| #6 | SFD400~SFD409 | #14 | SFD480~SFD489 |
| #7 | SFD410~SFD419 | #15 | SFD490~SFD499 |
| #8 | SFD420~SFD429 | #16 | SFD500~SFD509 |

SFD bit definition

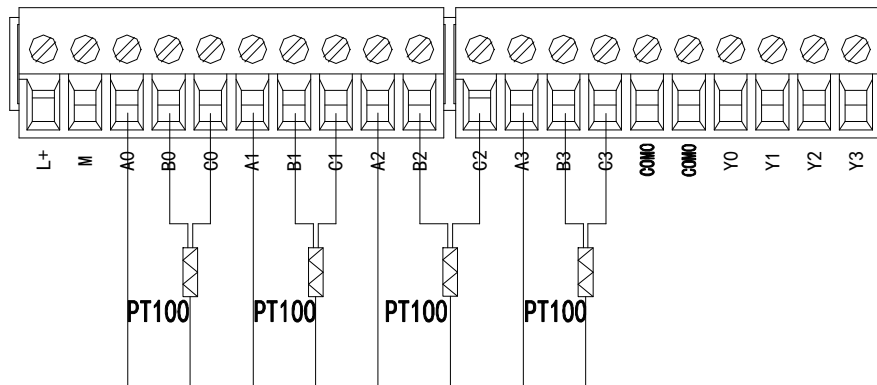
Take module 1 as an example to explain the setting method:

| Register | | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 |
|---------------|--------|---|------|---------------------------------------|------|---|------|---|------|
| SFD350 | Byte0 | PT channel 1 filtering coefficient (0 not filtered, 1-254 filtering intensity decreases sequentially) | | | | | | | |
| | Byte1 | PT channel 2 filtering coefficient (0 not filtered, 1-254 filtering intensity decreases sequentially) | | | | | | | |
| SFD351 | Byte2 | PT channel 3 filtering coefficient (0 not filtered, 1-254 filtering intensity decreases sequentially) | | | | | | | |
| | Byte3 | PT channel 4 filtering coefficient (0 not filtered, 1-254 filtering intensity decreases sequentially) | | | | | | | |
| SFD352 | Byte4 | - | | | | | | | |
| | Byte5 | - | | | | | | | |
| SFD353 | Byte6 | - | | | | | | | |
| | Byte7 | - | | | | | | | |
| SFD354 | Byte8 | - | | Resolution 00: 0.1°C 01: 0.01°C | | PT channel disconnection detection 00: On 01: Off | | Y function selection 00: Channel Enable 01: Immediate output | |
| | Byte9 | - | | | | - | | | |
| SFD355 | Byte10 | PT2 sensor type | | | | PT1 sensor type | | | |
| | | 0000: PT100 | | | | 0000: PT100 | | | |
| | | 0001: PT1000 | | | | 0001: PT1000 | | | |
| | | 0010: Cu50 | | | | 0010: Cu50 | | | |
| SFD355 | Byte11 | PT4 sensor type | | | | PT3 sensor type | | | |
| | | 0000: PT100 | | | | 0000: PT100 | | | |
| | | 0001: PT1000 | | | | 0001: PT1000 | | | |
| | | 0010: Cu50 | | | | 0010: Cu50 | | | |
| SFD356 | Byte12 | - | | | | - | | | |
| | Byte13 | - | | | | - | | | |
| SFD357~SFD359 | | - | | | | | | | |

13-5. External wiring

When connecting the thermal resistance, when connecting the external + 24V power supply, please use the 24V power supply on the PLC body to avoid interference. To avoid interference, shielding measures should be taken for signal wires.

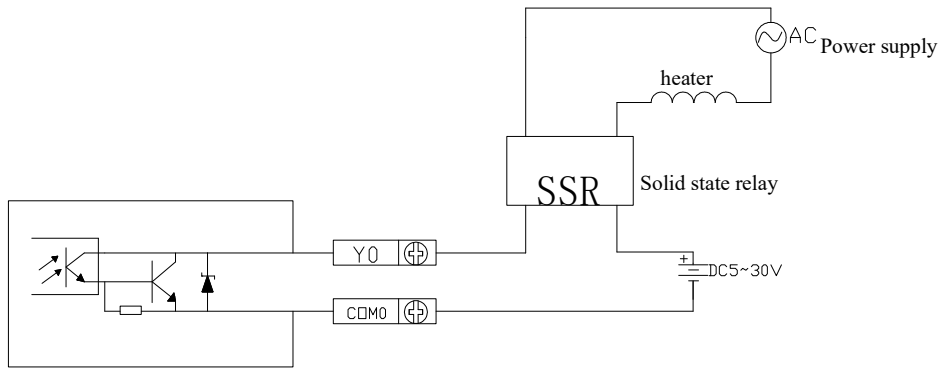
Input wiring



For a three-wire platinum thermistor, please connect two wires of the same color to the C0 end and the other wire to the A0 or A1 end.

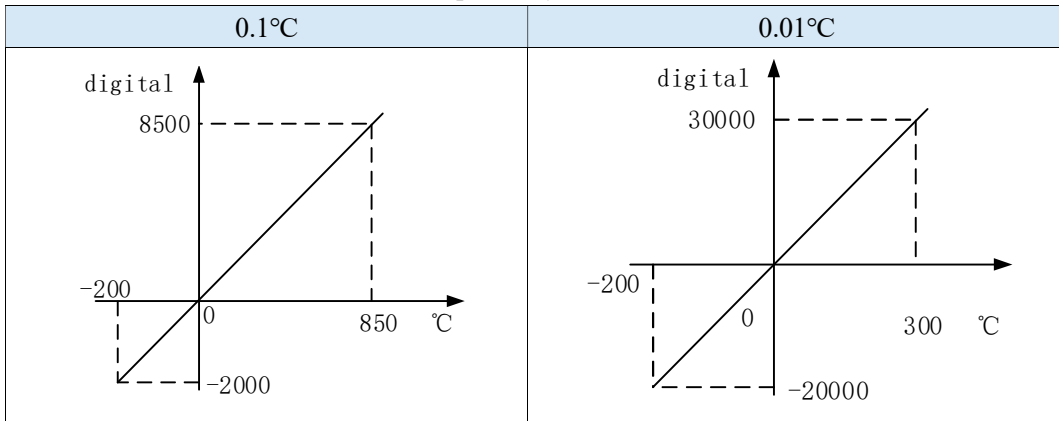
Output circuit

- Output terminal: transistor output terminal, please choose DC5V ~ 30V smooth power supply.
- Circuit Insulation: Optical couplers are used for optical insulation between the internal circuit of programmable controller and the output transistor, and the common modules are also separated from each other.
- Response time: The time from the programmable controller-driven (or circuit-breaking) optical coupler to the transistor ON/OFF is no more than 0.2 ms.
- Output Current: In order to limit the temperature rising, please make 50mA at each point.
- Open circuit leakage current: below 0.1mA.



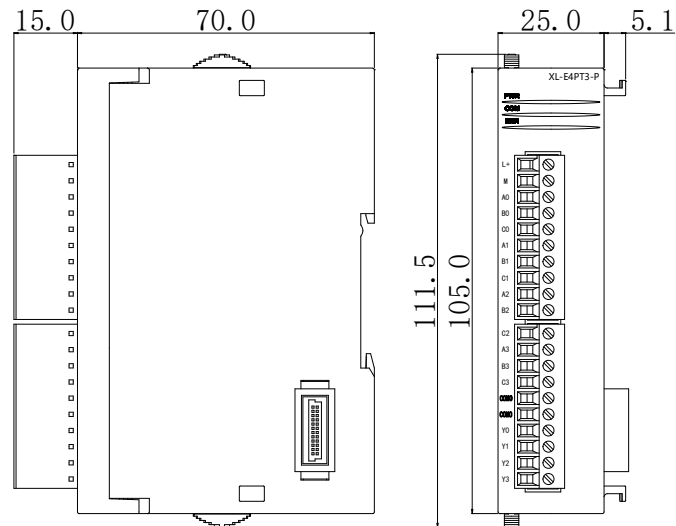
Input characteristic curve

Taking PT100 as an example, illustrate the relationship between temperature and digital quantity at resolutions of 0.1 °C and 0.01 °C, respectively.



13-6. Dimension

Unit: mm

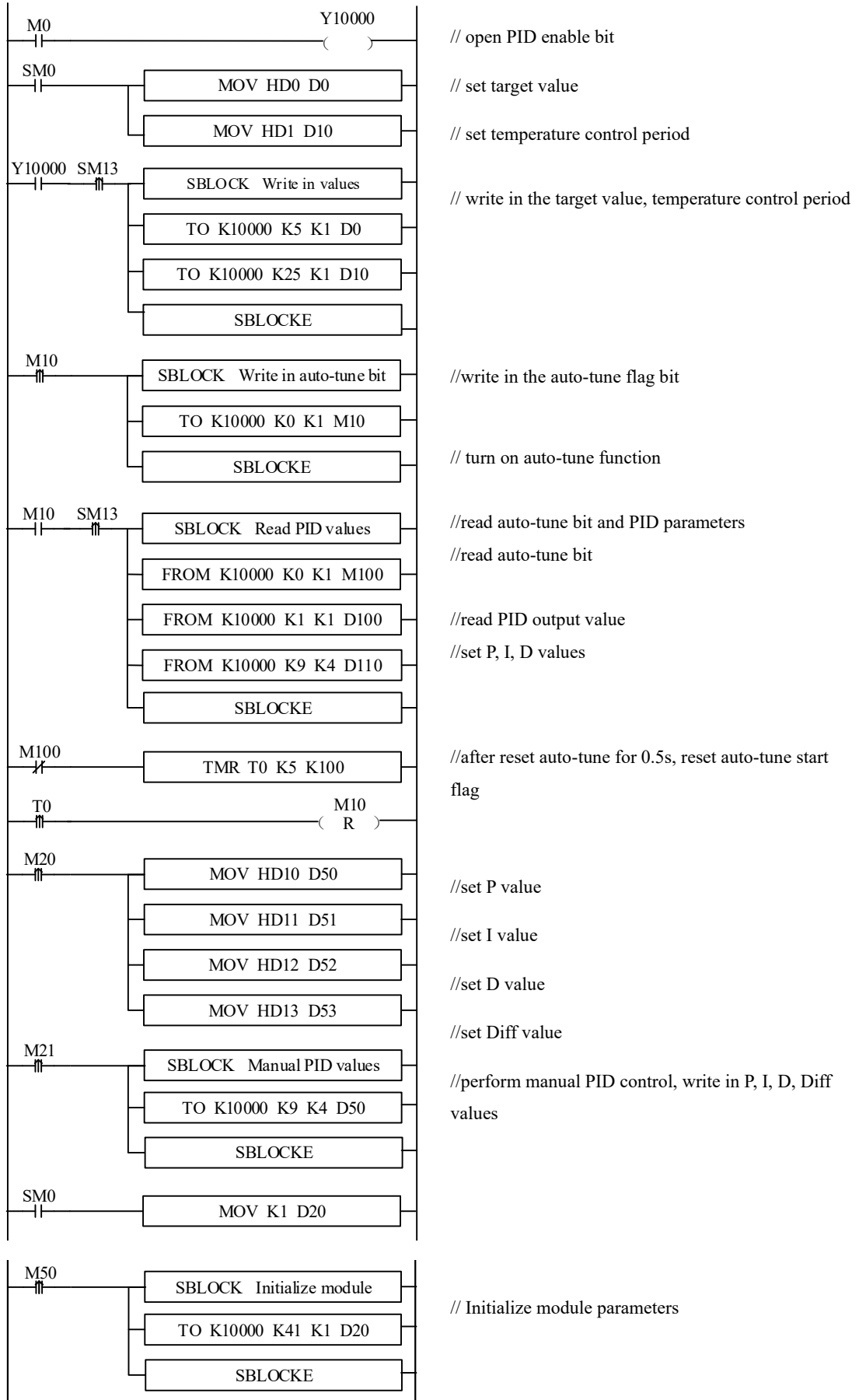


13-7. Application

When temperature control is required, there are two programming options:

1. use the PID of the PLC body for temperature control, at this time, you need to switch the Y function selection to 'immediate output', the programming case details please refer to "XDXL PLC instruction manual" chapter 7 PID control functions.
2. use the built-in PID of the module for temperature control, at this time, you need to switch the Y function selection to "channel enable", programming cases such as shown in following example 1.

Example 1: take module 1 as an example, do PID control for channel 0.



Explanation:

After enabling the self-tuning, this command will immediately occupy a total of 8 bits in M10-M17. M10-M13 corresponds to the self-tuning enable of each channel. To set which channel needs to be tuned, set the corresponding coil to ON. M14~M17 have no meaning at the moment and need to be left blank.

If the output is a solid-state relay, it is recommended to set the temperature control cycle to 1-3 seconds; If the output is a relay, it is recommended to set the temperature control cycle to 3-15s.

Due to inconsistent units, the PID parameters of the main body and module cannot be used interchangeably. The main body PID parameters are in uppercase, and the module PID parameters are in lowercase. The specific conversion relationship is as follows: $p=P/100$; $i=I/10$; $d=D/100$.

M0 turn on PID enable
SM0 set the target value, temperature control period
M1 write in target value, temperature control period
M3 set the manual P, I, D parameters
M4 write in manual P, I, D parameters
M10 read the auto-tuning bit, PID parameters and PID output value
M50 initialize the module
Y10000 PID enable bit of channel 0

D0 target value
D10 temperature control period
D80 P
D81 I
D82 D
D83 DIFF

XINJE



We chat ID

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