

# **ZP** series integral controller

User manual

WUXI XINJE ELECTRIC CO., LTD

NO. ZC01 20161213 3.4



Catalog

Preface

Safety notes

ZP series

# **Integral Controller**

User manual

ZP series introduction

I/O and wiring specification

Programming instructions

HMI screen engineering

Appendix

This manual includes some basic precautions to be followed for the safety of your devices and yourself of cause. All mentioned precautions are warned with a triangle logo ahead. Referring to the other unmentioned notes, please follow the basic electrical procedures.



Please follow the precautions. If not, your control system may be out of order, or a fortune loss caused in a severe situation.



This product and its components should only be used in situations mentioned in the catalog and technical specifications, and also be used with other devices produced by other manufactures which are admitted or recommended by our company.

### WUXI XINJE ELECTRIC CO., LTD. All right reserved

All behaviors without clear written permission, including copying, translation and using this file, should be prohibited, or you will take the responsibility of our loss. We reserve all the rights of our expansive products and their design patent license and registration.

Duty declaration

We have checked the contents of this manual in conformity with the hardware and software described in, but we still can't guarantee completely consistent because of some unavoidable mistakes. Even so, we will check data in this manual and update it frequently. Finally, welcome to put forward your valuable opinions.

2016.5

# CATALOG

SAFETY NOTES	
1 ZP SERIES INTRODUCTION	7
1-1. INTRODUCTION	7
1-1-1. Characteristics	7
1-1-2. Name rule	
1-1-3. Model list	
1-2. GENERAL SPECIFICATION	
1-2-1. Product specification	
1-2-2. Special function	
1-3. PART INTRODUCTION	
1-3-1. Structure	
1-3-2. Key function	
1-3-3. Terminal arrangement	
1-3-4. Programming port	
1-3-5. Communication port	14
1-4. DIMENSION	
2 I/O AND WIRING	16
2-1. INPUT SPECIFICATION	
2-2. RELAY OUTPUT SPECIFICATION AND CIRCUIT	
2-2-1. Relay output spec	
2-2-2. Output wiring example	
2-2-3. Output circuit composition	
2-3. TRANSISTOR OUTPUT SPECIFICATIONS AND CIRCUITS	
2-3-1. Ordinary transistor output	
2-3-2. High-speed pulse output	
3 PLC PROGRAMMING	22
3-1. LIST OF SOFTWARE COMPONENT NUMBERS	
3-2. Instruction list	
3-2-1. Basic instructions	
3-2-2. Application instructions	
3-2-3. Special instructions	
3-3. CREATE A PROJECT	
3-3-1. About Software	
3-3-2. Creation of project	
3-3-3. Upload/download of program	
3-4. COMMUNICATION	
3-4-1. Communication port	

3-4-2. Communication parameters	
3-4-3. Parameter setting	
3-4-4. Modbus communication and address	
4 PLC PROGRAMMING	
4-1. OP 20 SOFTWARE	
4-1-1. About software	
4-1-2. Installation and uninstallation	
4-1-3. Use process	
4-2. CREATE A PROJECT	41
4-2-1. Creation of project	
4-2-2. Screen download	
4-3. FUNCTION LIST OF TOOLS AND COMPONENTS	
4-3-1. Tool button list	
4-3-2. Partial function list	

## PREFACE

SIMPLIFIED INTRODUCTION ABOUT THIS MANUAL

Firstly, thank you for purchasing our ZP series product. Please read this manual carefully before related operations.

Manual purpose	• Users can operate and maintain ZP series products according to the related
·	guidance and instructions, referring to characteristics, specifications and methods
	etc.
	<ul> <li>This manual includes four parts, involving introduction, outside wiring, PLC</li> </ul>
	programming and HIVII screen editing.
	Product overview: introductions of characteristics, specification and installation on
	ZP series product.
	External wiring: introductions of power specifications and I/O wiring on ZP series
	product.
	PLC programming: introductions of PLC programming on ZP series product.
	HMI screen: introductions of HMI screen editing on ZP series product.
Relevant person	This manual is suitable for persons below:
	Terminal users
	Debugging person
	Technical support staff
	These persons mentioned above need to read the safety notes carefully before operating
	ZP series integrated controller.
Access	Electronic manual: Visit the official website of XINIE https://www.xinie.com to download
	Electronic manual. Visit die official website of ArrivE <u>meps.//www.Amje.com</u> to download
Statement of	Although the contents in the manual have been carefully checked, errors are
responsibility	inevitable and we cannot guarantee complete agreement.
	• We will often review the contents of the menual and make connections in
	we will often review the contents of the manual and make corrections in     subsequent versions. Your valuable comments are welcome.
	subsequent versions. Four variable comments are welcome.
	Please understand that the contents of the manual are subject to change without
<b></b>	prior notice.
Contact information	If you have any questions about our products, please contact the agent,
·	office of the product purchase, or directly contact with XINJE.
	Phone: 0510-85134136
	Fax: 0510-85111290
	Website: <u>www.xinje.com</u>
	Mailbox: xinje@xinje.com
	Address: 816 Jianzhu West Road, Binhu District, Wuxi City, Jiangsu
	Province

# **SAFETY NOTES**

The problems that may be caused during the use of the product are basically included in the safety precautions, and all are indicated by the two levels of attention and danger, and other unfinished matters, please comply with the basic electrical operating procedures.



When used incorrectly, it can be dangerous, there is a possibility of moderate injury or minor injury, and there is a possibility of property damage.



When used incorrectly, it may be dangerous, cause personal injury or serious injury, and may cause serious property damage.

### • Confirmation when you get the product



Don't install damaged controllers, integrated controllers that lack components, or integrated controllers that do not meet requirements, this may cause injury.

• Product system design



Design a safety loop outside the integrated controller to ensure that the entire system can run safely when the integrated controller is abnormal, this may cause the risk of misoperation and failure.



Don't bundle the control wiring and power wiring together, in principle to separate 10cm, this may cause the risk of misoperation and failure.

• Product installation



Before installing the integrated controller, disconnect all external power supplies, this may cause electric shock.



1. Please install and use this product under the environmental conditions specified in the general specifications of the manual.

Don't use in damp, high temperature, dust, smoke, conductive dust, corrosive gas, flammable gas, and vibration, impact places.

- This may cause electric shock, fire, misoperation, product damage, etc.
- 2. Don't directly touch the conductive part of the product. This may cause the risk of misoperation and failure.
- 3. When machining screw holes, please don't let cutting powder and wire debris fall into the product housing. This may cause the risk of misoperation and failure.
- 4. When connecting peripheral devices, expansion devices, and batteries, power off the device. This may cause the risk of misoperation and failure.
- Product wiring



- 1. Before connecting cables to the integrated controller, disconnect all external power supplies. This may cause electric shock.
- 2. Connect the DC power supply to the dedicated power terminal of the fusioncube. The wrong power supply could burn the controller.



- 1. Don't connect external cables to empty terminals. This may cause misoperation, product damage.
- 2. When machining screw holes, please do not let cutting powder and wire debris fall into the product housing.

This may cause the risk of misoperation and failure.

3. When connecting terminals with wires, ensure that the conductive part does not touch other wires or terminals.

This may cause the risk of misoperation and failure.

• Product operation and maintenance



3. Please don't open the rear panel.



- 1. Don't disassemble or assemble this product without authorization. This may cause damage to the product.
- 2. Remove and reinsert the cable when the power is off. The cable may be damaged or misoperated.
- 3. Don't connect external cables to empty terminals. This may cause misoperation, product damage.
- 4. Power off expansion devices, peripherals, and batteries before removing them. This may cause misoperation, failure, etc.
- 5. When the product is discarded, please treat it as industrial waste.
- 6. When the product emits odor or abnormal sound, turn off the power switch immediately. (The buzzer's short sound is normal after the product is powered on)
- 7. Don't press the screen with a sharp object, such as a pen or screwdriver. Otherwise, the screen may be damaged or faulty.

# **1 ZP SERIES INTRODUCTION**

## **1-1. Introduction**

ZP series is the perfect integration of OP series and XD series in function, under the premise of meeting the control requirements, ZP series can completely replace the OP and PLC in the control system, the compact form factor greatly saves installation space, and makes maintenance easier.

## 1-1-1. Characteristics

- It makes logic control, analog input/output and HMI integrated in one set Digital input: 10 points, optical isolation Digital output: 8 points, transistor output/relay output/transistor relay output I/O extension: Z-4X4YT-BD, Z-8X-BD, Z-8YT-BD Analog extension: Z-3AD3PT-BD, Z-4AD2DA-A-BD, Z-1WT-BD, Z-2WT-BD Communication extension: Z-NES-BD Temperature control extension: Z-4TC-BD, Z-4PT3-BD
- The HMI screen with rich functions is easy and simple to edit
- LCD: 192\*64 pixels (3.7 inches); LCD service life can be 20000 hours
- Up to 26 function keys, the functions can be freely specified
- The key sensitive and accurate
- Programming port Multi-function design: HMI and PLC programming use the same programming cable
- Waterproof rating meets IP20
- Compact structure, greatly save electric control cabinet space
- The appearance is simple and elegant and full of fashion

## 1-1-2. Name rule



- 1:` Series name
- ZP: the display area does not have touch functionality 1: XD1 series PLC
- 2: PLC type
- 2: XD2 series PLC
- 3: XD3 series PLC
- 3: I/O points 18: 10 input 8 output
- 4: Output type R: relay output
  - T: transistor output
  - RT: transistor relay output

# 1-1-3. Model list

	Μ		Qutnut			
	DC r	Input points	Output			
Input trac	<b>D</b> alay autout	Transistor	Transistor relay	(DC24V)	(P T)	
Input type	Kelay output	output	output		( <b>K</b> , 1)	
ZP1-18R		ZP1-18T	-	10 points	8 points	
NPN type	ZP2-18R	-	ZP2-18RT	10 points	8 points	
	ZP3-18R	ZP3-18T	ZP3-18RT	10 points	8 points	

### Extended BD:

Model	Instructions					
Z-4X4YT-BD, Z-8X-BD, Z-8YT-BD	Z-nXmYT-BD, n DC input(NPN input), m transistor output					
	4 thermocouple, supports multiple types thermocouple					
Z-41C-BD	temperature sensors, resolution 0.1 °C					
7 40T2 DD	4 PT100(three-wire system) temperature acquisition					
2-4r 13-8D	temperature range -100°C~500°C, resolution 0.1 °C					
Z-4AD2DA-A-BD	4 analog current input, 2 analog current output					
Z-3AD3PT-BD	3 analog voltage input, 3 PT100 temperature inputs					
Z-1WT-BD, Z-2WT-BD	1/2 pressure sensor analog voltage input					
Z-NES-BD	1 RS232 or 1 RS485					

# 1-2. General specification

# 1-2-1. Product specification

### 1) Electrical spec.

	Itam	Specification						
	item	ZP1-18R/T	ZP2-18R/T	ZP2-18R/T/RT				
	Input voltage	DC24V						
Flectrical	Power dissipation	Less than 10W (TY	(P2.0W)					
Char	Allow instantaneous outage	10ms DC24V		Less than 20ms				
Char.	Withstand voltage	AC1000V-10mA 1 minute (between signal and ground)						
	Insulation impedance	About $10M\Omega$ , DC500V (between signal and ground)						
	Operation temperature	0~50°C						
	Storage temperature	-10~60°C						
Environment	Ambient humidity	20~85% (no condensation)						
Environment	Vibration resistance	10~25Hz (X, Y, Z each direction is 30 minutes 2G)						
	Interference immunity	Voltage noisy: 1000Vp-p						
	Ambient air	No corrosive gas						

	Protective structure	Meet IP20				
Structure	Cooling mode					
	External dimension	172.0*121.0*56.5				
	Panel openings dimensions	164.0*113.0				
Interface	Download port	RS-232				
	Communication port	RS-232/ RS-485 (PLC)	RS-485			

### 2) HMI specification

Item		Specification					
	Туре	Yellow-green color LCD					
	LCD size	3.7 inches					
	Service life	More than 20000 hours, 24 hours run under the ambient					
		temperature 25°C					
Screen	Display area	192*64					
	Contrast	Potentiometer adjustable					
	Language	Simplified/traditional Chinese; English					
	Character size	Dot font and vector font					
	Touch mode	Untouchable					
Mamami	Screen	64KB FlashROM					
Memory	Data	4KB SRAM					

### 3) PLC specification

Itom		Specification						
10	em	ZP1-18R/T	ZP2-18R/T	ZP2-18R/T/RT				
	Total points	18						
Ontology IO	Input points		10					
	Output points		8					
Max IC	) points							
High speed positioning <sup>**6</sup>	Ordinary pulse output	/	2 2					
High speed	Single-phase /AB mode	/	3	3				
input	Input mode	/	OC	OC				
Expansion capability	BD board	/	1	2				
Frequency r	neasurement	Nonsupport	Support					
Program exe	ecution mode	Cyclic scanning mode						
Programn	ning mode	Order, ladder diagram						
Processi	ng speed	0.02~0.05us						
Blacko	out hold	Use FlashROM and lithium battery						
User program	n capacity <sup>*1</sup>		256KB					
I/O po	oints <sup>**2</sup>	Input 10, output 8						

Internal coil (M. HM)		11000	M0~M7999 [HM0~HM959] **3			
Internal coil (M, H	.M)	11008 points	Special use <sup>**4</sup> SM0~SM2047			
Flow (S)		1152 points	S0~S1023 [HS0~HS127] *3			
	Dointa	704 mainta	T0~T575 [HT0~HT95] *3			
	Points	704 points	Precise timer ET0~ET31			
Timer (T)		100ms t	imer: 0.1~3276.7s			
	Spec	10ms ti	mer: 0.01~327.67s			
		1ms tir	ner: 0.001~32.767s			
Counter (C)	Dointa	704 points	C0~C575 [HC0~HC95] **3			
	Points	704 points	High-speed counter HSC0~HSC31			
Counter (C)	Spec	16-bit counter: K0~32,767				
		32-bit counter: -2147483648~+2147483647				
			D0~D7999 [HD0~HD999] **3			
Data register (D	)	11548 words	Special use <sup>**4</sup> SD0~SD2047			
			Special use <sup>**4</sup> HSD0~HSD499			
ElechDOM register		7120 words	FD0~FD5119			
FlashKOW legister	(FD)	/120 words	Special use <sup>**4</sup> SFD0~SFD1999			
Confidentiality registe	er (FS)	48 words	FS0~FS47			
Sequential function bloc	ek WAIT	22	SEMO SEM127			
order special coil		52	SEM0~SEM127			
High-speed processing	function	High-speed count, pulse output, external interruption				
Password protection		6-bit ASCII				
Self-diagnostic func	tion	Power-on self-test, monitor	r timer, grammar checking			

Notes:

%1: the max capacity of secret download mode

%2: I/O numbers means the input and output terminal numbers

X3: register area in [] is the power-off retentive area, not for other uses

%4: special use: special register, not for other uses. Refer to the appendix to know in detail.

%5: serial number of input coil, output relay/transistor is octal number, and other registers are decimal number.

%6: the PLC with only transistor output has high-speed positioning function.

# 1-2-2. Special function

### 1) High-speed count

ZP2-18, ZP3-18												
	Incremental mode								AB	phase mo	ode	
	HSC0	HSC2	HSC4	HSC6	HSC8	HSC10	HSC12	HSC0	HSC2	HSC4	HSC6	HSC8
Max frequency	80K	10K	10K					50K	5K	5K		

4-time						2/4	2/4	2/4	
Count									
interruption	$\checkmark$	$\checkmark$				$\checkmark$	$\checkmark$	$\checkmark$	
X000	U					А			
X001						В			
X002						Z			
X003		U					А		
X004							В		
X005							Z		
X006			U					А	
X007								В	
X010								Z	
X011									

Notes: Counting function of Z phase signal is still in research.

### 2) High-speed pulse

• T type: Y0, Y1, max speed 100KHz

### 3) External interrupt

Input terminal	Poi	Suppress intermention			
	Rising interruption	Falling interruption	Suppress interruption		
X2	10000	I0001	SM050		
X3	I0100	I0101	SM051		
X4	10200	I0201	SM053		
X5	10300	I0301	SM054		
X6	I0400	I0401	SM055		
X7	10500	I0501	SM056		
X10	10600	I0601	SM056		
X11	10700	10701	SM057		

#### Notes:

- (1) The above lists only the specifications. For details about the parameters and usage guide, please refer to XD/XL series PLC manual [basic instruction].
- (2) External interruption will not be executed after suppress interruption coil is ON.

### 4) Frequency measurement

Model	l	X ID	Max frequency		
ZP2, ZP3 series	18 points	X0	80 KHz		
		X3	10 KHz		
		X6	10 KHz		

# 1-3. Part introduction

## 1-3-1. Structure



# 1-3-2. Key function

Key	Basic function
	No matter what state the monitor is in, when this key is pressed, it returns to the initial
Ecc	screen of the system. The initial screen of the system is specified by the user when
ESU	designing the screen, and the initial screen of the system is generally set as the main
	menu or the screen with the highest frequency of use

	Flip the screen to the previous page
	Flip the screen to the next page
SET	<ul><li>Press this key to modify the register value. The register area being modified is displayed in reverse color, and the modified bits are displayed blinking.</li><li>If the current screen does not have a register setting window component, an empty operation is performed.</li><li>Press the [SET] key again before pressing the [ENT] key to cancel the current modification operation and continue to modify the next data register.</li></ul>
ENT	Write the modified data into the register, and continue to modify the next data register, the last register of the current screen is modified, exit the modified register state
ALM	Alarm list key, after setting the alarm list function, press this key to quickly switch to the alarm list screen
CLR	When modifying register data, clear the selected region
+/-	When modifying register data, set the data positive or negative
	Number key (0-9), in the number setting state, the modified number bits into the corresponding key value
Fn	Normal function key (F1-F8)

**Notes:** In addition to the common functions in the above table, each key in the panel can be defined by the user as any of the functions of "ON", "OFF", "reverse" and "instantaneous ON".

## 1-3-3. Terminal arrangement

24V OV A F	B COMO YO	Y1	Y2	Y3	COM1 Y4	Y5	Y6	Y7	COM XO	X1	X2	Х3	Χ4	Χ5	X6	X7	X10 X11

## 1-3-4. Programming port

Download port is RS232. The programming port has dual download function, both PLC program and HMI screen data can be downloaded. The port supports MODBUS and X-NET protocols, the appearance and main pins are as below:

Pin NO.	function
Pin4	RxD
Pin6	TxD
Pin8	GND



Please use the special programming cable of our company for downloading. If you have none, you can also make it by yourself. The connection of programming port and 9 pins of PC is as follows.



### NOTICE:

- (1) Please use the dedicated programming cable provided by XINJE for PLC to download the PLC program and HMI screen.
- (2) Please don't modify the communication parameters of the download port, otherwise the PLC cannot connect to the PC.

# 1-3-5. Communication port

Communication port of ZP series integrated machine is the communication port of the PLC part, accords to RS485 (serial port 2).

When PLC is in the state of factory settings, you can also use this port for downing or uploading, it is mainly used for communicating with external sensors, instrument, equipment and other devices.

AB port appearance and main pins:



1) Communication parameters

Station	Modbus station 1~254, 255 (FF) is free format
number	communication
Baud rate	300bps~115.2Kbps
Data bit	7, 8
Stop bit	1,2
checking	None, Odd, Even, Empty, Mask

### 2) Parameter setting

When RS485 is used to communicate with peripheral devices, you cannot modify the communication parameters. You can only use the default parameters.

Communication default parameters: station number is 1, baud rate 19200bps, 8 data bits, 1 stop bit, even parity.

### NOTICE:

RS485 port support MODBUS, free format and X-NET Bus communication. Serial port parameters can be set through the RS232 download port. X-NET communication mode can be modified by XINJEConfig tool. Refer to [X-NET manual].

## 1-4. Dimension

Appearance and hole dimension (unit: mm)



# 2 I/O and wiring

This chapter explains the I/O specification and wiring method of ZP series

# 2-1. Input specification

#### 1) Basic unit

Input signal voltage	DC24V±10%				
Input signal current	7mA/DC24V				
Input ON current	Above 4.5mA				
Input OFF current	Below 1.5mA				
Input response time	About 10ms				
Input signal format	Point input/ open collector NPN transistor				
Circuit insulation	Optical coupling insulation				
Input action display	LED light is ON when inputting ON				



#### 2) Input wiring

The ZP3 series don't provide 24V power supply internally, so when using an external power supply to drive sensors such as photoelectric switches, the external power supply voltage should be DC24V  $\pm$  4V, and the output transistor of the sensor should use NPN open-collector type.



### • Input points

If using the no voltage contact or NPN open collector transistor between input points and COM, the input need to be ON.

• Input circuit

Use the optical coupler to make insulation isolation between the first loop and the secondary loop of inputting, and set C-R filter in the secondary loop to avoid the noise produced by vibration of input points, mixture of input line or wrong operation. So for the transformation of  $ON \rightarrow OFF$ ,  $OFF \rightarrow ON$ , the response delay time is about 10ms in the product. Input terminal has a built-in digital filter.

• Input sensitivity

The input current of integrated controller is DC24V 7mA, but for the reliable action, the current is above 3.5mA if ON, and it is below 1.5mA if OFF.



#### 3) Typical connection

# 2-2. Relay output specification and circuit

Ν	Iodel	R output	RT output				
Relay	output bit	Y0~Y7	Y4~Y7				
Exter	nal power	Below AC250V, DC30V					
Circuit	t insulation	Machinery	Machinery insulation				
Action	command	Make a "close" sound					
	Resistance load	3A					
Max loader	Inductance load	80VA					
	Lamp load	100	100W				
Mir	n loader	DC5V	2mA				
Response	OFF→ON	10ms					
time	ON→OFF	10ms					

# 2-2-1. Relay output spec

## 2-2-2. Output wiring example



To prevent the load short circuit and other faults to burn the PLC

Notes: T type has no relay output, don't access 220V, otherwise it will cause product damage

# 2-2-3. Output circuit composition

- DC inductive load, fly-wheel diode need to be in parallel. If not, the service life of junction will be low.
   Please select the diode whose forward current is higher than the load current, allowing reverse pressure over load voltage 5 ~ 10 times.
- AC inductive load, surge absorber need to be in parallel. It will reduce noise and extend the service life of relay.



## 2-3. Transistor output specifications and circuits

Transistor output has two types, including high-speed pulse output and ordinary trans istor.

## 2-3-1. Ordinary transistor output

	Model	Т
Output bit		Y2~Y7
Externa	l power supply	Below DC 5~30V
Circu	uit insulation	Coupling light insulation
	Resistance load	0.3A
Max load	Inductance load	7.2W/DC24V
	Lamp load	1.5W/DC24V
ľ	Min load	DC 5V 2mA
Open	circuit current	Below 0.1mA
Response	OFF→ON	Below 0.2ms
time	ON→OFF	Below 0.2ms

Ordinary transistor output circuit :

• Output points

Transistor output of integrated controller has a common point output

• External power supply The power to drive load is DC5~30V regulated power supply

- Circuit insulation It is insulated isolation by photoelectric coupler between its internal loop and output transistor.
- Action instruction
   While driving the optical coupling, output transistor is ON.
- Response time

The time is below 0.2ms from photoelectric coupler driving (cut down) to transistor ON(OFF).

- Output current The output current is 0.3A each 1 point. However, due to the temperature rise limit, the total current is 0.5A each output 4 points.
- Open circuit current Below 0.1mA.



# 2-3-2. High-speed pulse output

Model	Т
High-speed pulse output bit	Y0~Y1
External power supply	Below DC5~30V
Max current	50 mA
Pulse output max frequency	200KHz

High-speed pulse output circuit:



Below is wiring of T type integrated controller and servo drive

Integrated controller

```
Servo drive
```



(make sure the current of servo driver optical coupling input is 8~15mA)

# **3 PLC programming**

This chapter describes the specific operations of the ZP3 series PLC programming, includes internal software component allocation, instruction list, software related introduction, and how to create projects, and communicate content.

## 3-1. List of software component numbers

ZP1/ZP2/ZP3 series assignment of software component number are as follows:

In addition, when expanding the BD board for special features, correlation definition number, please refer to [Z Series Extended BD Board User Manual].

Identification		Radius	Points
mark	Name	18 points	18 points
X	Input points	X0~X11	10
Y	Output points	Y0~Y7	8
v	Lugart a cinta ×3	X20000~X20077 (#1 extend BD)	64
Λ	input points <sup>22</sup>	X20100~X20177 (#2 extend BD)	64
V	Output points <sup>×3</sup>	Y20000~Y20077 (#1 extend BD)	64
I	Output points	Y20100~Y20177 (#2 extend BD)	64
М		M0~M7999	8000
HM	Internal relay	HM0~HM959 <sup>**1</sup>	960
SM		Special use SM0~SM2047 <sup>**2</sup>	2048
S	Flow	S0~S1023	1024
HS	FIOW	HS0~HS127 <sup>**1</sup>	128
Т		T0~T575	576
HT	Timer	HT0~HT95 <sup>**1</sup>	96
ET		Precise timing ET0~ET31	32
С		C0~C575	576
НС	Counter	HC0~HC95 <sup>**1</sup>	96
HSC		High-speed counter HSC0~HSC31	32
D		D0~D7999	8000
HD	Dete mediaten	HD0~HD999 <sup>*1</sup>	1000
SD	Data register	Special use SD0~SD2047	2048
HSD		Special use HSD0~HSD499 <sup>*2</sup>	500
FD	FlashROM	FD0~FD6143	6144
SFD	register	Special use SFD0~SFD1999 <sup>*2</sup>	2000
FS	Special secret register	FS0~FS47	48
	Noumenon	ID0~ID99	100
ID <sup>×4</sup>	Extend DD	ID20000~ID20099 (#1 extend BD)	100
	Extend BD	ID20100~ID20199 (#2 extend BD)	100
QD <sup>*5</sup>	Noumenon	QD0~QD99	100

	Extend DD	QD20000~QD20099 (#1 extend BD)	100
	Extend BD	QD20100~QD20199 (#2 extend BD)	100
SEM	Sequential function block	SEMO SEM21	32
	WAIT instruction specific coil	SEMO~SEM51	52

Notes:

- 1) The memory area is the default blackout hold area(The PLC power off hold area cannot be modified).
- 2) Special use(Hold without power failure), a special purpose register occupied by the system, don't use it for other purposes. Please refer to the section [List of Special Software Components] in the appendix of this manual.
- 3) Extended I/O address allocation for BD(Oct), maximum of two can be extended simultaneously.
- 4) Analog input software component address.
- 5) Analog output software component address.

## **3-2. Instruction list**

## **3-2-1.** Basic instructions

Instruction	Function	Usable software component
LD	Initial logic normally open contactor	X,Y,M,HM,SM,S,HS,T,HT,C,HC,Dn.m
LDD	Directly from the contact read state	X
LDI	Initial logic normally close contactor	X,Y,M,HM,SM,S,HS,T,HT,C,HC,Dn.m
LDDI	Direct read normally closed contact	X
LDP	Rising edge detection algorithm	X,Y,M,HM,SM,S,HS,T,HT,C,HC,Dn.m
LDF	Falling edge detection operation began	X,Y,M,HM,SM,S,HS,T,HT,C,HC,Dn.m
AND	Serial connection normally open contactor	X,Y,M,HM,SM,S,HS,T,HT,C,HC,Dn.m
ANDD	Directly from the contact read state	X
ANI	Serial connection normally close contactor	X,Y,M,HM,SM,S,HS,T,HT,C,HC,Dn.m
ANDDI	Direct read normally closed contact	X
ANDP	Rising edge detection in series connection	X,Y,M,HM,SM,S,HS,T,HT,C,HC,Dn.m
ANDF	Falling edge detection in series connection	X,Y,M,HM,SM,S,HS,T,HT,C,HC,Dn.m
OR	Parallel connection normally open contactor	X,Y,M,HM,SM,S,HS,T,HT,C,HC,Dn.m
ORD	Directly from the contact read state	Х
ORI	Parallel connection normally close contactor	X,Y,M,HM,SM,S,HS,T,HT,C,HC,Dn.m
ORDI	Direct read normally closed contact	X
ORP	Pulse rising edge detection parallel connection	X,Y,M,HM,SM,S,HS,T,HT,C,HC,Dn.m
ORF	Parallel connection of pulse falling edge detection	X,Y,M,HM,SM,S,HS,T,HT,C,HC,Dn.m
ANB	Series connection of parallel circuit block	none
ORB	Parallel connection of series circuit block	none
OUT	Coil drive	X,Y,M,HM,SM,S,HS,T,HT,C,HC,Dn.m
OUTD	Output to the contactor	Y
SET	Keep the coil ON	X,Y,M,HM,SM,S,HS,T,HT,C,HC,Dn.m
RST	Clear the coil-ON state	X,Y,M,HM,SM,S,HS,T,HT,C,HC,Dn.m

PLS	Rising edge detection instruction	X,Y,M,HM,SM,S,HS,T,HT,C,HC,Dn.m
PLF	Falling edge detection instruction	X,Y,M,HM,SM,S,HS,T,HT,C,HC,Dn.m
MCS	Connecting coil instruction for common serial points	none
MCR	Removal of common serial points	none
ALT	Negate the coil	X,Y,M,HM,SM,S,HS,T,HT,C,HC,Dn.m
RST	Reset the contactor, clear the current value	Y、C、HC、HSC
CNT	No power down keep counting up, count coil drive	K <sub>N</sub> D
CNT_D	Power down keep counting up, count coil drive	K <sub>N</sub> D
TMR	No power down keep the timer coil drive	K <sub>N</sub> D
TMR_A	Power down keep the timer coil drive	K <sub>N</sub> D
END	Operate output/input and return to step 0	none
GROUP	Block folding start	none
GROUPE	Block folding end	none

# **3-2-2.** Application instructions

type	Instruction	Function		
	SHL	Arithmetic shift left		
	SHR	Arithmetic shift right		
	LSL	Logic shift left		
	LSR	Logic shift right		
Data shift	ROL	Rotate left		
	ROR	Rotate right		
	SFTL	Bit shift left		
	SFTR	Bit shift right		
	WSFL	Word shift left		
	WSFR	Word shift right		
	WTD	Word convert to double word		
	FLT	16-bit integer convert to float		
	FLTD	64-bit integer convert to float		
	INT	Float convert to integer		
Data	BIN	BCD convert to binary		
Data	BCD	Binary convert to BCD		
conversion	ASCI	Hex convert to ASCII		
	HEX	ASCII convert to hex		
	DECO	Decoding		
	ENCO	High-bit encoding		
	ENCOL	Low-bit encoding		
	ECMP	Float comparison		
Float	EZCP	Float zone comparison		
calculation	EADD	Float addition		
	ESUB	Float subtraction		

	EMUL	Float multiplication
	EDIV	Float division
	ESQR	Float square
	SIN	Float sine
	COS	Float cosine
	TAN	Float tangent
	ASIN	Float arcsine
	ACOS	Float arccosine
	ATAN	Float arctangent
	TRD	Read clock data
Clock	TWR	Write clock data
	ТСМР	Clock comparison

# **3-2-3.** Special instructions

Туре	Instruction	Function			
	PLSR	Multiple pulse output			
	PLSF	Variable frequency pulse output			
	STOP	Pulse stop			
Dulas	GOON	continue to pulse			
Puise	ZRN	Mechanical origin regression			
output	DRVA	Absolute location			
	DRVI	Relative location			
	CNT	Single phase high speed counting/Single phase high speed			
		counting interrupt			
	CNT_AB	AB phase high speed counting/AB phase high spe			
High-speed count		counting interrupt			
	DMOV	32 bit high-speed count read			
	DMOV	32 bit high speed count write			
	RST	High-speed count reset			
	COLR	MODBUS read coil			
	INPR	MODBUS read input coil			
	COLW	MODBUS write single coil			
	MCLW	MODBUS write multi-coil			
	REGR	MODBUS read register			
Modbus	INRR	MODBUS read input register			
communication	REGW	MODBUS write single register			
	MRGW	MODBUS write multi-register			
Free format	SEND	Free format data sending			
communication	RCV	Free format data reception			

	BIT_READ	Read instruction		
X-NET	BIT_WRITE	Write instruction		
communication	REG_READ	Read register instruction		
	REG_WRITE	Write register instruction		
	STR	Precise timing		
Precise timing	DMOV	Read precise timing register		
	STOP	Stop precise timing		
	EI	Enable the interruption		
Interruption	DI	Disable the interruption		
	IRET	Interruption return		
	FRQM	Frequency measurement		
Others	PWM	Pulse width modulation		
	PID	PID control		

**Notes:** This manual simply lists all supported instructions. Detailed instructions on the use of the directive, please refer to XD/XL series PLC manual [basic instructions] and XD/XL series PLC manual [position control].

# 3-3. Create a project

## 3-3-1. About Software

ZP series is the organic integration of XD series PLC and OP in function. Therefore, when writing the control program, the software used is the same as the XD series PLC, which uses XDPPro software.

The interface of XDPPro software is shown in the figure below :



# **3-3-2.** Creation of project

Let's take ZP3-18T as an example, specify the steps to create a PLC program project.

1) Open the software

Double click the XDPPro software icon "", open the software, the screen shown above will display.

The PLC object of the software defaults to XDH-60A32 (look at the status bar at the bottom, as shown in the image below), not the PLC type of ZP, so it needs to be modified.

PLC1:XDH-60A32 Communication:Com,Station:1

2) Modify the model

Click "File" in the menu bar, then click "Change PLC type", as shown in the following picture:

File	Edit Search	View	C				
	New Project	Ctrl+N					
2	Open Project						
	Close Project						
=	Save Project	Ctrl+S					
	Save Project As						
	Advanced Save						
	Add PLC						
	Search 485 Network						
	Delete PLC						
	Change PLC Mo	del					
	Import PLC Mod	del					
	Import Downloa	id File					
	Export Downloa	d File					
	Print Set	Ctrl+P	- 23				
	Print						
	Recent Projects						
	Exit						

Select the appropriate PLC type in the pop-up window, the example is ZP3-18T, so here select "XD3" and then click "ZP3-18T", as shown in the following picture:

XD2	XD3-24
XD3 XD3E	XD3-32 XD3-48
XD3E(N)	XD3-60 763-30
XD5E XDC XDE XDH XDH XDM XDME	ZP3-18

### 3) Write program

After the above two steps, you can start writing programs in the software. The programming specification and the specific operation of the software, please refer to [ XD series PLC manual ].

PL	.C1 - Ladde	r						• ×
0	M0						(	Y0 )

## 3-3-3. Upload/download of program

### 1) On-line

Before downloading the program, please verify that the ZP is successfully connected to the computer (For cable connections, refer to section 1-3-5). Click on Menu bar [Options], then click [Software Serial Port

Op	tion Window Help
	Comm Mode Settings
	Ethernet Module Settings
	Download Settings
	Software Serial Port Config
	Default Unlock Psw Config
	Other Project Config
	Ladder Color Config
	C Editor Settings

#### Operation as shown below:

Communication configuration

New Edit Delete Move-Up Move-Down

Name	Connection status	Status	Belonging	Description	Connect Info
USB_Xnet_Default	Not connected	in use	Global	Search type: Automatic search, Search mode:	í I
Ethernet_Xnet_Default	Not connected		Global	Search type: ethernet, Search mode: Device t	
COM_Modbus_1	Not connected		Global	Station number: 1, serial port: COM1, baud r	Communicat
					OK

×

Click automatic detection, the PLC connection is displayed successfully, click OK.

Communication G			
Name:	.M_Modbus_1		
Connection mode :	selection		
Interface Type:	COM	~	
CommProtocol:	Modbus	~	
Communication pa	rameter confi	guration	
Automatic Detect	tion	-	
Station No		Baudrate(B)	
1			000825
Serial Port(C)			SAUUBBS
COM4 (USB) 🗸			0400013
🗌 Blue Tooth S	erial Port	0 1152008F5	
Parity( <u>P</u> )		Other set	
O None O Odd	🖲 Even	Databits:8,St	opbits:1
Connect To PLC Su	cceeded	🗹 Auto-conne	ect on exit

Change the usage status to "in use" and click OK.

Import	·····································	◎ ⑤ 肇 幣 副 ② ◆ 参 今 ▶ ■ 島 餅 悪 整 整 約 図・■	
Constant Star Constant	roject # x	₹ X /PLC1 - Ladder	• ×
Rest         Activation         Rest	Image: Section 2014         Address           Image: Section 2014         Address           Image: Section 2014         Reserved Block           Image: Sectio	8	
Lig AC Mark Dreu Lat Outer  C A C Mark Court   C A	R Axis group configuration	Information	ą x
	Lie O, CAN Can CA Tables Can CA Tables Can CA Project Vessage Can CA Project Vessage Can CA Project Vessage Can Contain Can Can Can Can Can Can Can Can Can Can	The Lat Colpet	(

"Connect To PLC Succeeded" is displayed, so you have successfully connected your PLC to your PC! If the automatic detection fails and the following message is displayed, the serial port parameters may be modified, you can use "Stop PLC When Reboot".

Communication configura	tion	×
Communication COM_Modb	us_1	
Connection mode selecti	on	
lint		;
please try to use	the function "Stop PLC When Reb	oot"
please try to use	the function "Stop PLC When Ret	poot" 定
COM4 (USB) ~ Blue Tooth Serial F	the function "Stop PLC When Ret	poot" 定
COM4 (USB) $\checkmark$ Blue Tooth Serial F Parity(P)	the function "Stop PLC When Ret	poot" 定
COM4 (USB) ~ Elue Tooth Serial F Parity(P) None Odd Ev	the function "Stop PLC When Ret ort O 115200BPS Other set Databits:8,Stopbi	poot" 定
COM4 (USB) Blue Tooth Serial F Parity(P) None Odd Ev Communication Error	the function "Stop PLC When Red ort 0 115200BFS Other set en Databits:8, Stopbi Auto-connect	poot" 定 its:1 on exit

### 2) Upload/download of program

After successful connection, click the toolbar icon ", the program in the PLC can be uploaded.

Click the icon "

Uploading Program & Data	×
Vploading Cancel	

After successful connection, click the toolbar icon ", the program in the PLC can be downloaded. If the PLC is running, the following information window is displayed.

Downloading Program	X	×
	Stop PLC, contitue	
	Data retention,	
	Cancel Download	

The program download process will automatically calculate the current program percentage, as shown in the following picture:

×

At the end of the program download, the "Download User Data" window will be displayed.

User can select the type of data to download as required, by default select all, as shown in the following picture:

<ul> <li>✓ Reg Init Value</li> <li>✓ Serial Port Config</li> <li>✓ Module Config</li> <li>✓ BD Module Config</li> <li>✓ ED Module Config</li> </ul>	
<ul> <li>I/O Config</li> <li>Sys Pulse Block Config</li> <li>Instruction Data</li> <li>Ethernet Port Config</li> <li>EtherCAT Config</li> <li>Axis/Axis Group Config</li> <li>System Config</li> <li>CAM Config</li> <li>Global variable initial value</li> </ul>	^
✓ Float Setting ✓ ModbusTCP Config	~

After downloading the program, click the toolbar icon "[1], operating PLC.

### Notes:

- 1) If the program has a password set, or is a private download, six red dots will appear on the right side of the interface.
- 2) More detailed usage of XDPPro software, please refer to XD/XL series PLC manual.

# **3-4.** Communication

## **3-4-1.** Communication port

ZP series with programming port (RS232) and RS485 communication port (A,B port). Among them, the programming port can only be used for PLC program and HMI screen download. The RS485 communication port can be used to communicate with other devices, the communication parameters of this port can be reset by software.



RS485 communication port pin A is the "+" signal, and B is the "-" signal.

## **3-4-2.** Communication parameters

Station number	Modbus station 1-254, 255 (FF) is free format communication
Baud rate	300bps~115.2Kbps
Data bit	8 data bits, 7 data bits
Stop bit	1, 2
Checking	None, Odd, Even

Communication port default parameter: station NO.1, baud rate 19200bps, 8 data bits, 1 stop bits, even check

## 3-4-3. Parameter setting

Users can use RS485 port for Modbus communication, free-form communication and X-NET communication. There are two ways to set Modbus communication parameters:

- 1) Parameters are set by programming software;
- 2) Configure the XINJEConfig tool to set parameters.

Free format communication parameter settings can be set by programming software.Specific introduction please refer to XD/XL series PLC manual [basic instruction].

X-NET communication parameter settings can be set by XINJEConfig tool. X-NET communication feature can refer to [X-NET manual].

- 1. Parameters are set by programming software.
- 1) The PLC will be connected to the PC using the download cable.
- 2) Open the Xinje PLC Program Tool, find the "Configure" in the menu bar, and click the "PLC Comm Port settings ". As shown in the following picture:

III Xinje PLC Program Tool			×
File Edit Search View Online Configure □ C III Configure PLC Con Security +++ 문 -K- 문 -H - +- ++ Configure PLC Con	Option Window Help nm Port Settings Settings on Module Settings on Module Settings	<b>▲</b> 5 ₩€ Q	Ŧ
Project # X PLC1 - Lat Floating	point number setting	•	×
Code Code		( <sup>Y0</sup>	)

3) After clicking, the page shown below will appear:

- Serial Port Set					
M PLC Config	Add - Remo	ove			
- Password					
- E PLC Serial Por					
Pulse					
- Module					
BD					
— 📴 ED					
4GBOX					
SustenConfig					
Up bystemcontrig					
		Read From PLC	Write To PLC	OK	Cancel
					-

4) Click " add", there are two modes of communication, Modbus and Free.

LCT - Senar Port Se		(
Config  PLC Config  Password  PLC Serial  P ethernet  Pulse  Pulse  Pu	Add     Remove       Modbus     Free	
HD HED HGBOX WBOX GSystemConf	is	
٢	>	
	Read From PLC Write T	o PLC OK Cancel

After selecting Modbus communication , the serial port configuration screen

is displayed on the right, as shown in the following figure:



**Port No.:** It refers to Port of PLC, COM1 refer to port1(RS232), COM2 refer to port2(RS485). **The baud rate, data bit, parity bit, stop bit** should be same to the communication device. **Station number**: If the PLC is master, the station no. is defaulted 1. If the PLC is slave, it needs to set different station no.

### Two modes of communication: RTU and ASCII.

**Delay before sending(ms):** Waiting time before PLC sends data. In the original XC series PLC, if the master PLC communicates with the slave PLC, the master PLC sends data to the slave PLC. If the master PLC sends data to the slave PLC after the first time, and the slave PLC has not yet had time to receive the data, then the master PLC sends data to the slave PLC again, which easily leads to the error of the slave PLC; In XD series PLC, it has send delay to solve the problem. That is, after receiving data from the slave station, it must delay a certain time to receive the next communication data, so as not to cause the above problems.

**Reply overtime(ms):** It refers to the time when the PLC can not receive the response after sending the request and wait for sending again.

**Retry times:** It refers to the number of times that the PLC can not receive the reply, and each reply needs a reply timeout time.

5) After setting, click write to PLC, then cut off the PLC power supply and power on again to make the settings effective.

- 2. Set the parameters by using XINJEConfig tool.
- 1) Use the OP download cable to connect the PLC to the PC.
- 2) Open the XINJEConfig software, the following window appears:



3) Click "PLC", the following window appears:

					Help
Connection mo	de				]
Interface:	COM		~		
Protocol:	Modbus		~		
Comm config p	arameters				
LinkPort:	COM4		) ~		
port paramete	rs				
Station:	1	-	(Requ	ired)	
Baud rate:	19200	~	(BPS)		
Parity bits:	Even	$\sim$			
Data bits:	8	$\sim$			
Stop bits:	1	~			
		1	Connec	ting	10

The Link Port must be the COM port that connects the computer to the PLC, which can be viewed in the Device Manager. Serial port parameters are the parameters of the PLC serial port connected to the computer.

 In the "Link Port", select the connection port for the PC and PLC. The "Protocol" select Modbus, click to "Find Device", the following window appears:

ndby CommPort Route Ethernet			
COM No 2	-MODBUS Station Band rate	1	Hel:
Net type X_Net Modbus Free Format	Data bits Parity bits Stop bits AckTimeout	8 ~ Even ~ 1 ~	
Physical Type RS232	Retrytimes Senddelay	3	
Restart PLC to enable!	RTU	O ASCII	

Comport NO.: K1~K5, port1(RS232), port2(RS485).

Here, we can set the communication mode and parameters of each communication port.

5) When the com port parameters setting is completed, click writeconfig. It will show "write configuration success" message.

Success.			×
	Success.		
确定		确定	

6) Close XINJEConfig tool, cut the PLC power and power on again to make the settings effective.

## 3-4-4. Modbus communication and address

ZP1/ZP2/ZP3 series support both Modbus master and Modbus slave.

Master mode: When PLC is set to be master, it can communicate with other slave devices which have MODBUS-RTU or MODBUS-ASCII protocol via Modbus instructions; it also can change data with other devices.

For example: Xinje ZP3 series can control inverter by Modbus.

Slave mode: When PLC is set to be slave, it can only response with other master devices.

### **Communication address**

ZP3 series Modbus address and internal soft component table:

	Comment			Modbus	Modbus			
Туре	Component	<b>Component ID</b>	Number	address	address			
	symbol			(Hex)	(decimal)			
	М	M0~M7999	8000	0~1F3F	0~7999			
		X0~X77(main unit)	64	5000~503F	20480~20543			
		X10000~X10077(#1 module)	64	5100~513F	20736~20799			
		X10100~X10177(#2 module)	64	5140~517F	20800~20863			
		X10200~X10277(#3 module)	64	5180~51BF	20864~20927			
		X10300~X10377(#4 module)	64	51C0~51FF	20928~20991			
	v	X10400~X10477(#5 module)	64	5200~523F	20992~21055			
	Λ	X10500~X10577(#6 module)	64	5240~527F	21056~21119			
		X10600~X10677(#7 module)	64	5280~52BF	21120~21183			
		X10700~X10777(#8 module)	64	52C0~52FF	21184~21247			
		X11000~X11077(#9 module)	64	5300~533F	21248~21311			
		X11100~X11177(#10 module)	64	5340~537F	21312~21375			
		X20000~X20077(#1 BD)	64	58D0~590F	22736~22799			
		Y0~77(main unit)	64	6000~603F	24576~24639			
		Y10000~Y10077(#1 module)	64	6100~613F	24832~24895			
		Y10100~Y10177(#2 module)	64	6140~617F	24896~24959			
		Y10200~Y10277(#3 module)	64	6180~61BF	24960~25023			
0 11 1 1		Y10300~Y10377(#4 module)	64	61C0~61FF	25024~25087			
Coil, bit	N/	Y10400~Y10477(#5 module)	64	6200~623F	25088~25151			
	Y	Y10500~Y10577(#6 module)	64	6240~627F	25152~25215			
		Y10600~Y10677(#7 module)	64	6280~62BF	25216~25279			
		Y10700~Y10777(#8 module)	64	62C0~62FF	25280~25343			
		Y11000~Y11077(#9 module)	64	6300~633F	25344~25407			
		Y11100~Y11177(#10 module)	64	6340~637F	25408~25471			
		Y20000~Y20077(#1 BD)	64	68D0~690F	26832~26895			
	S	S0~S1023	1024	7000~73FF	28672~29695			
	SM	SM0~SM2047	2048	9000~97FF	36864~38911			
	Т	T0~T575	576	A000~A23F	40960~41535			
	С	C0~C575	576	B000~B23F	45056~45631			
	ET	ET0~ET31	32	C000~C01F	49152~49183			
	SEM	SEM0~SEM31	32	C080~C09F	49280~49311			
	$HM^{*1}$	HM0~HM959	960	C100~C4BF	49408~50367			
	$\mathrm{HS}^{st_1}$	HS0~HS127	128	D900~D97F	55552~55679			
	$HT^{*_1}$	HT0~HT95	96	E100~E15F	57600~57695			
	$HC^{*_1}$	HC0~HC95	96	E500~E55F	58624~58719			
	$HSC^{*1}$	HSC0~HSC31	32	E900~E91F	59648~59679			
Dominter	D	D0~D7999	8000	0~1F3F	0~7999			
Kegister,		ID0~ID99(main unit)	100	5000~5063	20480~20579			
word	ID	ID10000~ID10099(#1 module)	100	5100~5163	20736~20835			
		ID10100~ID10199(#2 module)	100	5164~51C7	20836~20935			

	ID10200~ID10299(#3 module)	100	51C8~522B	20936~21035
	ID10300~ID10399(#4 module)	100	522C~528F	21036~21135
	ID10400~ID10499(#5 module)	100	5290~52F3	21136~21235
	ID10500~ID10599(#6 module)	100	52F4~5357	21236~21335
	ID10600~ID10699(#7 module)	100	5358~53BB	21336~21435
	ID10700~ID10799(#8 module)	100	53BC~541F	21436~21535
	ID10800~ID10899(#9 module)	100	5420~5483	21536~21635
	ID10900~ID10999(#10 module)	100	5484~54E7	21636~21735
	ID20000~ID20099(#1 BD)	100	58D0~5933	22736~22835
	QD0~QD99(main unit)	100	6000~6063	24576~24675
	QD10000~QD10099(#1 module)	100	6100~6163	24832~24931
	QD10100~QD10199(#2 module)	100	6164~61C7	24932~25031
	QD10200~QD10299(#3 module)	100	61C8~622B	25032~25131
	QD10300~QD10399(#4 module)	100	622C~628F	25132~25231
	QD10400~QD10499(#5 module)	100	6290~62F3	25232~25331
QD	QD10500~QD10599(#6 module)	100	62F4~6357	25332~25431
	QD10600~QD10699(#7 module)	100	6358~63BB	25432~25531
	QD10700~QD10799(#8 module)	100	63BC~641F	25532~25631
	QD10800~QD10899(#9 module)	100	6420~6483	25632~25731
	QD10900~QD10999(#10 module)	100	6484~64E7	25732~25831
	QD20000~QD20099(#1 BD)	100	68D0~6933	26832~26931
SD	SD0~SD2047	2048	7000~77FF	28672~30719
TD	TD0~TD575	576	8000~823F	32768~33343
CD	CD0~CD575	576	9000~923F	36864~37439
ETD	ETD0~ETD31	32	A000~A01F	40960~40991
$HD^{*_1}$	HD0~HD999	1000	A080~A467	41088~42087
$\mathrm{HSD}^{st_1}$	HSD0~HSD499	500	B880~BA73	47232~47731
HTD <sup>**1</sup>	HTD0~HTD95	96	BC80~BCDF	48256~48351
HCD <sup>**1</sup>	HCD0~HCD95	96	C080~C0DF	49280~49375
HSCD <sup>**</sup> 1	HSCD0~HSCD31	32	C480~C49F	50304~50335
FD <sup>*2</sup>	FD0~FD6143	6144	C4C0~DCBF	50368~56511
SFD <sup>**2</sup>	SFD0~SFD1999	2000	E4C0~EC8F	58560~60559
$FS^{*2}$	FS0~FS47	48	F4C0~F4EF	62656~62703

Notes:

1) The power down holding area is marked with  $\times 1$ , and the flash area is marked with  $\times 2$ .

2) The bit software components X and Y are addressed in base 8 and the rest in base 10.

3) Specific usage of Modbus communication instructions, please refer to XD series PLC manual [basic instruction].

# **4 HMI screen programming**

This chapter describes the specific operations of the ZP3 series HMI programming, includes brief description of the software, how to create HMI screen project in software, and basic components and main functions of tools.

# 4-1. OP 20 software

## 4-1-1. About software

HMI screen of ZP3 series need to be programmed in HMI software. The HMI of the ZP3 series belongs to the OP series, therefore the software used is OP 20 software.

OP 20 software runs under Windows98/XP/NT. As a secondary development tool, the software is easy to learn, easy to use, and can directly set Chinese and English characters. The user project consists of images, and set the screen to accomplish some specific functions. Realize the free jump between different screens. The interface of OP20 software is shown as follows:



# 4-1-2. Installation and uninstallation

OP20 software V9.3.2 and later adopts the registry installation mode, therefore before using the software, the user must first install the software correctly on the computer. The following uses the OP20 V6.5K as an example, this section describes how to install and uninstall the software.

Find the " <sup>setup</sup> " under the installation folder and double click the icon, enter the software installation procedure, the installation interface is shown as follows:



2) Click the "Next" button, select "I accept the Deal". Click the "Next" continuously. When the following page appears, click the "Install". (When the page for selecting an installation location is displayed, you can select the default setting. If another version of the OP software has been installed before and has not been uninstalled, you must select another installation location. If the software is installed in the same path, it may run incorrectly. In general, it is not recommended to install two or more versions of OP20 software on a computer.)



3) Finally, the installation is complete. At this point, you can start to use the software to edit the screen. **Notes:** 

OP 20 software adopts backward compatibility processing, that is, using a later version of the software can open a lower version of the project file.

4) Unload

😼 unins000

Find " " in the installation directory and double click the icon. The following window is displayed, ask if you want to uninstall the software. As shown in the following picture:

F20 01	nstall			~
?	Are you sure components	you want to com ?	pletely remove O	P20 and all of its

Click the "Yes" to start the uninstallation process. Finally, a window indicating that the software has been successfully uninstalled will appear, as shown in the following figure:



## 4-1-3. Use process

After the OP20 software is correctly installed through the previous steps, the editing of the project screen can be officially started.. The following is the basic process for editing project images using software. The basic use process of OP20 is as follows:



# 4-2. Create a project

The HMI engineering screen of the ZP3 series is edited in OP20 software. OP software is easy to understand and easy to use. The following will take ZP3-18T as an example to explain the process of making a specific project screen.

# 4-2-1. Creation of project

### 1) New construction

Double click the icon """ of to open the software, there is no picture at this time. Click "File" in the menu bar and then click "New Project" to create a new project.

OP Series Edit Tool	 $\Box$ $\times$
File Edit Tool Help	
New Project       Ctrl+1         Image: Open Project       Ctrl+O         Save Project       Ctrl+S         Save Project As	
Import Data Outport Data	
Select Model Select PLC	
Comm Port	
Exit	
< > > New Delete	

### 2) Display selection

After the new project is created, an "Select Model" window will appear, in which you can select the model of you want. The object model in this example is ZP3-18T, so the display should select "ZP3-18", as shown below:

elect Model:	
C 0P320	C 0P320/5A
OP330 (XP)	• ZP3-18
ОК	Cancel

### 3) PLC selection

Since the ZP series is a combination of HMI and XD series PLC functions, for OP displays, the object it communicates with should be XD series PLC, of course, the communication between the two is built-in, and the communication parameters can be set by default.

	a
PLC Type: Xinie (XD)	
Set communication parameter	Setting

### 4) Screen editing

After setting the display and selecting the PLC type, the editing mode of the project screen will be officially entered. Below is the environment for editing screen 1. For specific instructions on screen production, please refer to [OP20 programming manual].

e <u>E</u> dit <u>T</u> ool <u>H</u> elp																						
		3	6	Ø		6																
Scree Description		_						 			 							 			A	F
1			÷.	1	8.0		1	 1	ċ	1	2	ċ	1	•	<u>.</u>	<u>.</u>	6 8 	2	÷			į
			0			1	÷.	2	0	÷.	2	0	0		2	0	1	2	01	-		
											2				2		1			-	39	2.17
																				iš		
											÷				÷		i i			Ĩ	E I	1
	1.1					×.	$\sim$			2					÷.	2	1			-	- 1-	-
	De Pri	escrip eviou ext Si	otion us So cree	reen n No.	No.:		1	•	3													

## 4-2-2. Screen download

### 1) Communication port selection

Before downloading the screen, you must correctly select the connected communication port. This communication port is the 9-pin serial port of the computer itself, and the computer will automatically number it, so long as the user knows the number of the connected communication port. If you cannot confirm, you can make connection attempts in sequence. If the selected COM port is incorrect, a message will be displayed indicating that it cannot be opened, as shown in the following figure:



Click the menu bar "File", select "Comm port", select the correct serial port number. In this example, the communication port is COM3, as follows:

Select Comm	Port X
Select the for Downl	e communication port, oading
Comm Po	rt: COM 💈 💌
ОК	Cancel

### 2) Download

Connect the ZP3 download port to the computer using the download cable. At the same time, the ZP3 must be

powered on. Click "B" on the toolbar to start the download process, and the download progress window is

displayed. After all screen data is downloaded, a window indicating that the download is complete will pop up. **Notes:** 

- 1) Please don't power off the machine during the process of downloading the screen, otherwise please power on again and download again.
- 2) The cable for downloading the screen and the cable for downloading the PLC program can be the same.
- 3) Don't download images when the XDPPro software and the OP software are open at the same time.

## 4-3. Function list of tools and components

## 4-3-1. Tool button list

Button	Main function
D	Create a new project
1	Open a saved project
	Save the project you are editing
	New screen
5	Displays the properties of the current screen
	Copy one picture to another
M	Delete current screen

26	Log in the alarm list information, each alarm information corresponds to an intermediate
<b>4</b>	relay
×	Specify the initial screen of the system, when the display is working, the key is directly returned to this screen. Generally, this screen is the main menu or the most frequently used screen, and the system password is set; Sets the interactive control register definition number.
义	Set the global function key
M	Through the computer RS232 port, the edited project file is downloaded to ZP

# 4-3-2. Partial function list

Button	Main function
Α	Enter text, including Chinese characters or English letters.
ÂĂ	Place variable text to display the current machine status through dynamic text, making it easier for operators to operate and improve production efficiency. Variable text is ideal for you.
F <sup>f</sup> F	Vector text, you can size the input text, you can set the font.
F <sup>FF</sup>	Dynamic vector text, the display content varies according to the different values, can be set $0 \sim 254$ state display content.
	Place an indicator to show the switching status of the intermediate relay inside the PLC.
	Place a data monitoring window or a data setting window(The object is a PLC data register).
Þ	Place the function key, the function of the function key includes screen jump and switch control.
E.	Touch key, allows the user to touch the display screen(Only XMP series all-in-one machines support this feature).
and Band	Insert the bitmap file, can display the graphics of the machine, so that the operator can easily understand, but also can display the factory logo, factory emblem, enhance the product image.
	Place bar charts that visually display analog parameters such as flow, pressure, level, etc. Its height, width and direction can be specified arbitrarily.
3	Place the line chart. In the process of industrial control, some parameters change slowly, and operators want to understand the change process of these parameters in a certain period of time, and line charts should be the most ideal way.